

**ITS World Congress 2021  
SIS38 Connected & Automated Driving research cooperation  
between Europe and Japan**



# **SIP-adus FOT in Tokyo waterfront area**

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**SIP-adus International Cooperative WG**

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## Strategic Innovation promotion Program

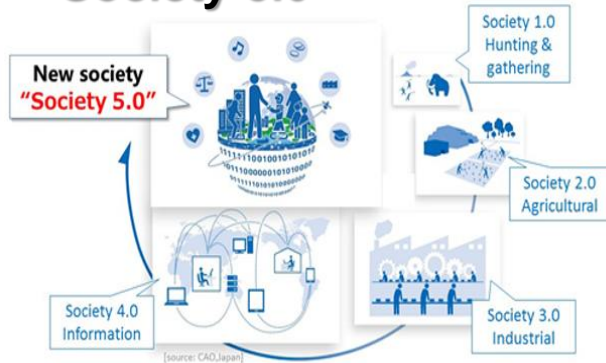
SIP 2<sup>nd</sup> FY2018~FY2022



12 themes on going (SIP-adus is one of them)

adus ; Automated driving system for universal service

### Society 5.0



- Promote cross-sector and **industry-academia-government collaboration**
- Intensive R&D program from **fundamental research to practical and commercialization**
- Promote Regulatory reform

# SIP-adus Initiative

## ADS (Automated Driving Systems)

Safe and secure mobility for all



**Competition**



**Cooperation**



## Realization of **S**ociety 5.0



### ➤ Technology

- ① Dynamic Map
- ② Safety Assurance
- ③ Cybersecurity
- ④ Geospatial dynamic data utilization  
etc.

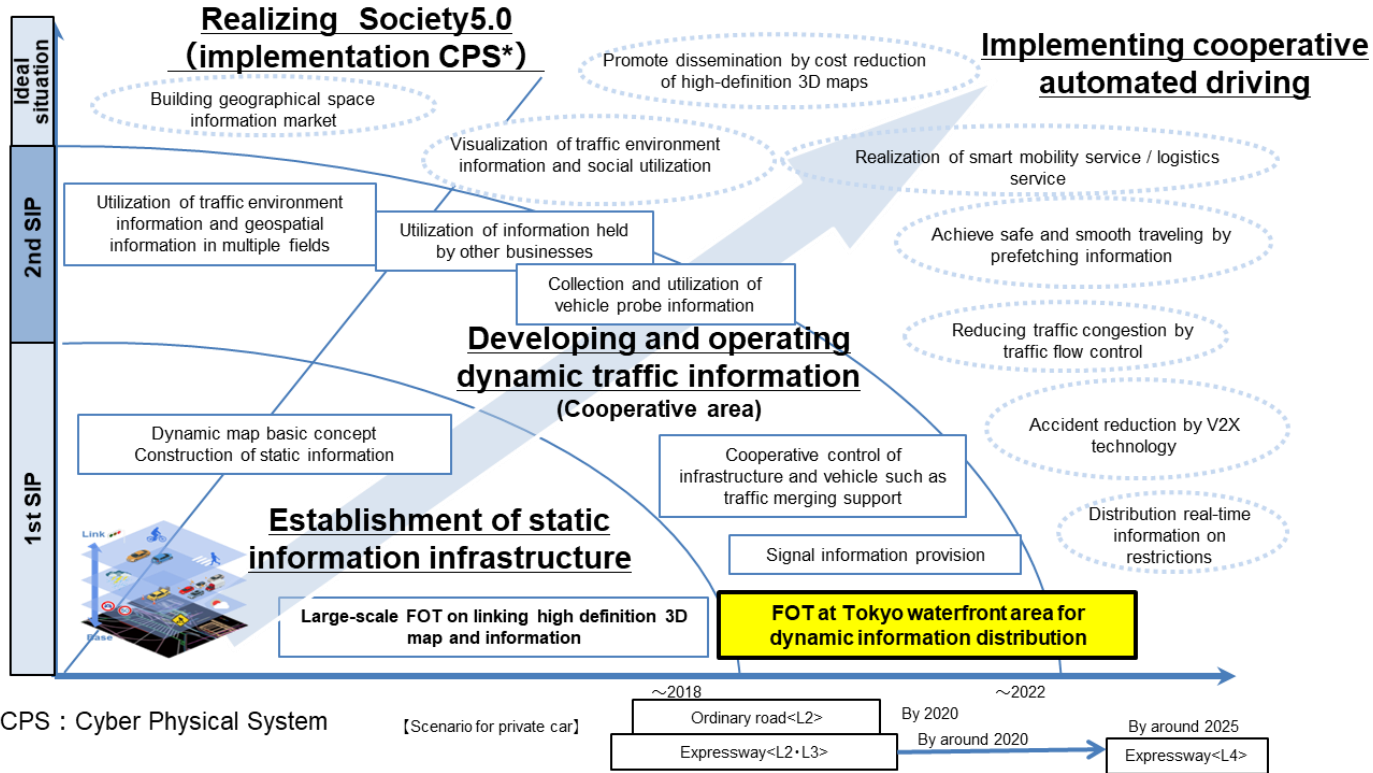
### ➤ Int. cooperation/Standardization

### ➤ Public acceptance

### ➤ Deregulation/Regulatory reform

# Building the Traffic Environmental Info. Framework

- ◆ SIP-adus is working on the development and operation of **traffic environment information** through **FOT on public roads**.



# 2019-2020 FOT areas

Period; October 2019 – march 2021

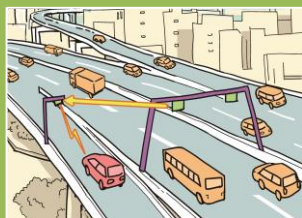


## Tokyo waterfront city area



- Signal display and change timing information via ITS infrastructure
- Precise 3D map linked with signal info. etc

## Tokyo metropolitan expressway



- Merging assistance on the main lane of highways
- ETC gate open/close info.
- Lane level traffic flow regulation info. Etc.

## Haneda airport area (AD-Bus)



- Signal display and change timing information via ITS infrastructure
- Magnetic marker
- Bus stop, dedicated lane for bus service

# Environment

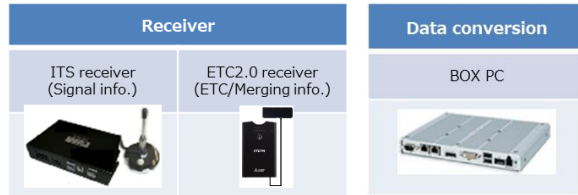
◆ Establish an experimental environment for effective execution

- ✓ **High-precision 3D map** distribution
- ✓ Development of information distribution **infrastructure**
- ✓ Lending information **receiver**
- ✓ **Data conversion** to in-vehicle communication I / F

## HP 3D map



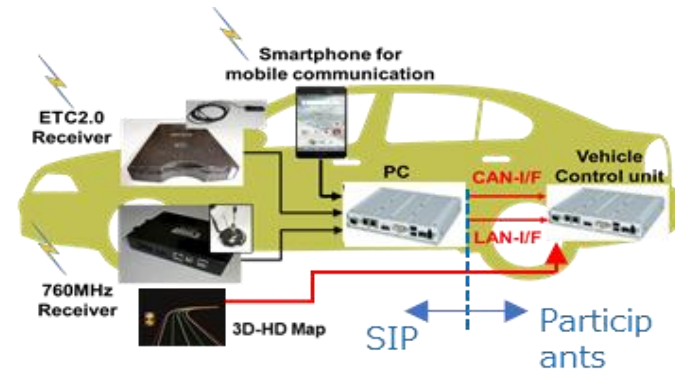
## Equipments



## Infrastructure



## Data conversion



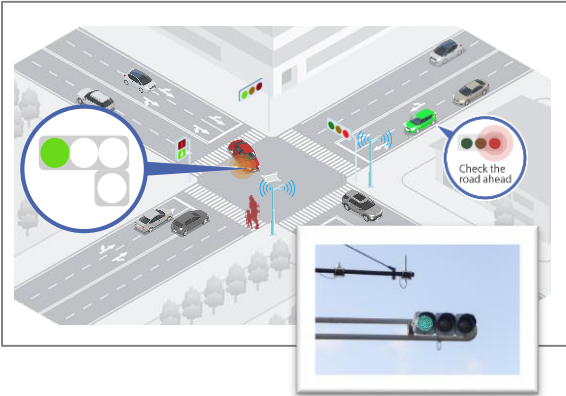
# Participants



Alphabetical order. A total of 29 institutions

# Results of FOT (Tokyo waterfront city area)

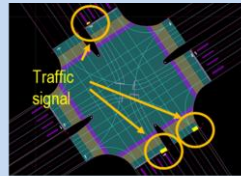
- ◆ Demonstrated the effectiveness of providing **signal information** via V2I



Installed V2I (760MHz) equipment at 33 intersections in Odaiba



- Confirmed that **signal recognition** can be performed stably under various conditions based on **V2I information**.



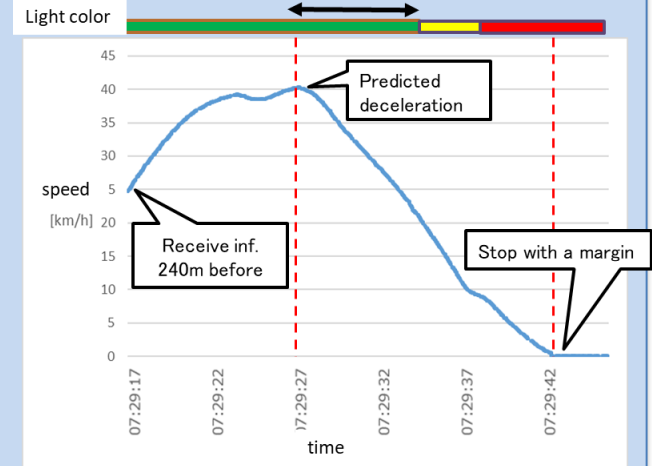
Superimpose display of the received V2I information on a high-precision 3D map



Ex.) Traffic signal color (green/yellow/red)



- Confirmed that **the dilemma zone\*** can be avoided by V2I remaining seconds information

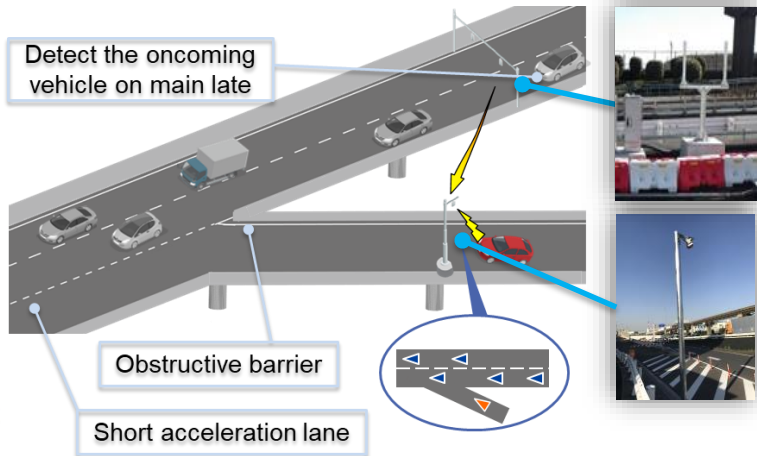
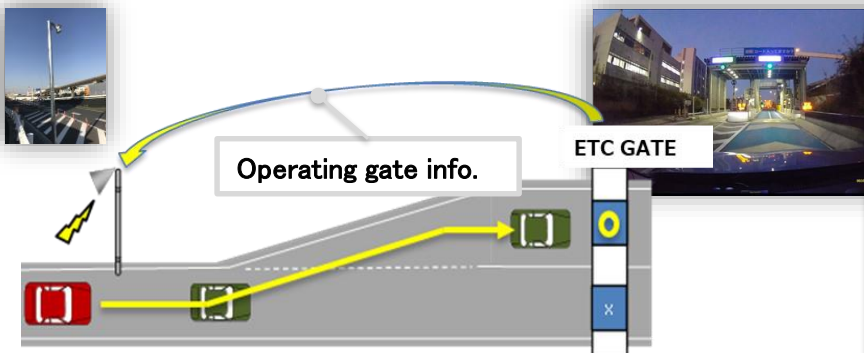


\* It is the timing which the vehicle cannot pass the stopping line, and stop without sudden braking in yellow light.

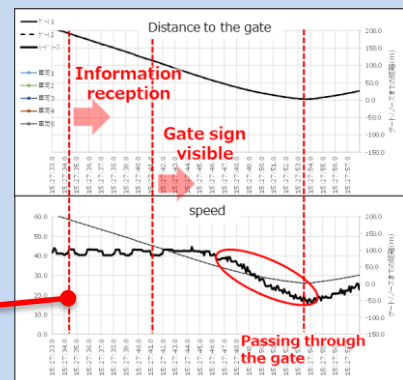


# Results of FOT (Tokyo metropolitan expressway)

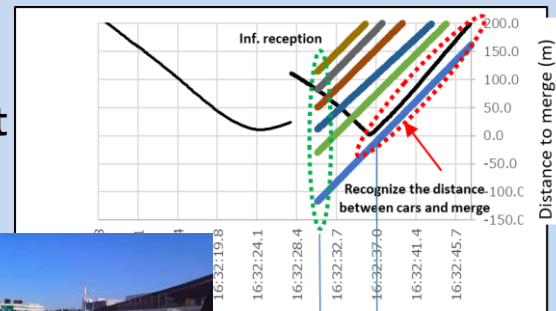
◆ Demonstrated the effectiveness of **merging support information** via V2I



- Smooth course change and gate passage due to early recognition of operating gates.



- Confirmed the possibility of **merging judgment and speed control** aiming at the gap by automated driving control.



About 5 to 6 seconds from receiving information to merging 8

# Results of FOT (Haneda airport area)

- ◆ Demonstrated the realization of **next-generation ART\*** using AD technology under mixed traffic. (\*ART : Advanced Rapid Transit)

- Demonstrated **level 4 AD bus** that does not require driver intervention and **on-time express delivery** by road-vehicle cooperation.



- Demonstrated a bus that is friendly to all people by gentle acceleration / deceleration and **precise docking for accessibility** (45mm± 10 mm) by AD control.



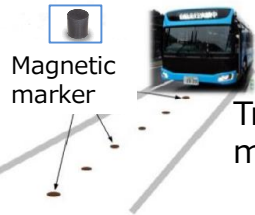
Haneda Airport access road



## Road vehicle coordination equipment



PTPS\*\* & Signal info. via V2I



Magnetic marker

Track guidance magnetic marker

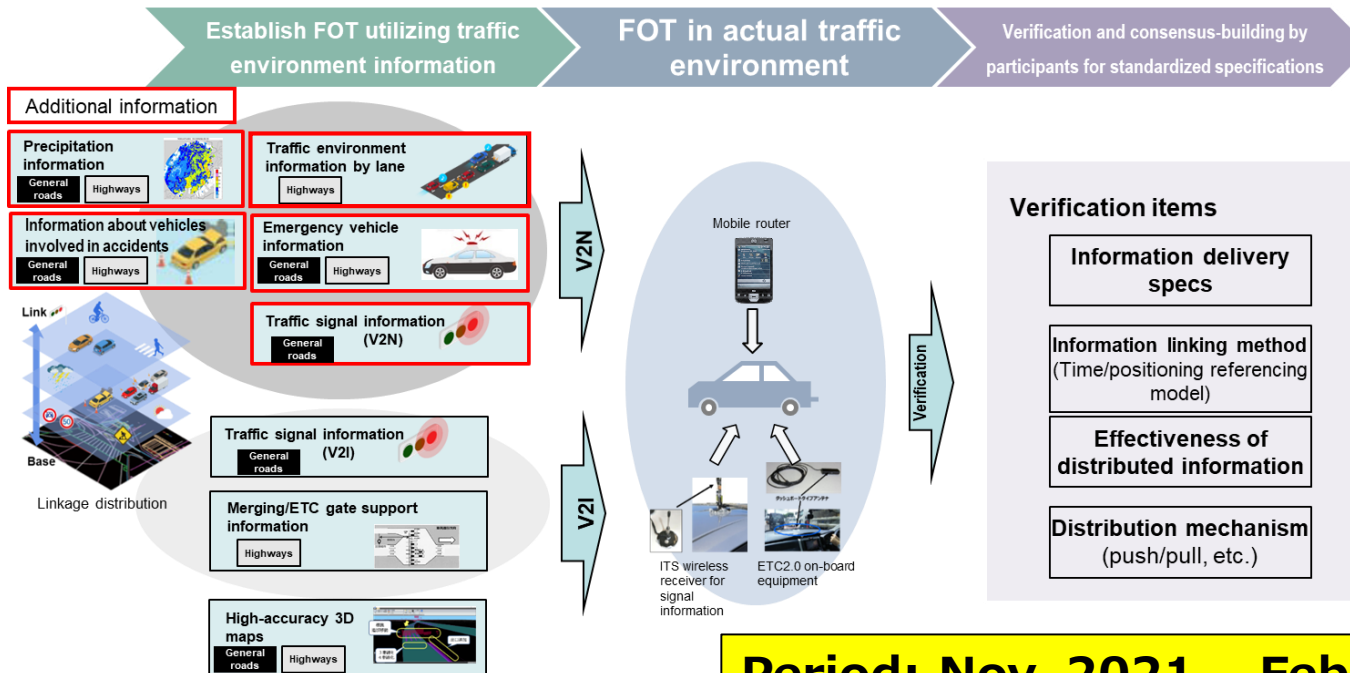


Dedicated bus lane

(\*\*PTPS: Public Transport Priority system)

# FOT in 2021 (V2N)

- ◆ SIP-adus is planning FOT that provide **dynamic traffic info. from a wide area** of infrastructure via **V2N** in 2021 with the aim of further expanding the operation design domain (ODD) of ADV and mobile / logistics services.



\*The technological topics may increase/decrease according to R&D progress

**Period; Nov. 2021 – Feb. 2022**

# FOT in 2021 (Simulation)

- ◆ SIP-adus is also working on the practical application of **a tool for the safety assurance of AD systems in virtual space.**
- ◆ FOT is realized by **developing and providing a simulation environment** for the Tokyo Waterfront City (Odaiba).

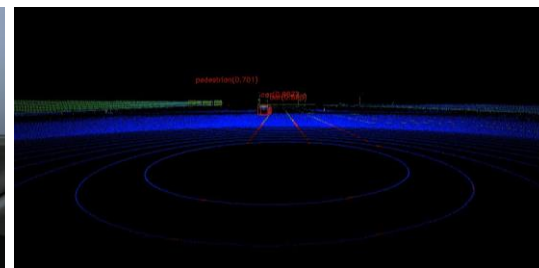
- Verification of the **reproducibility** of a realistic traffic environment
- Evaluate tool **usability** and simulation **effectiveness**
- Evaluation of **scenario setting tool** including movement of surrounding traffic participants



Euro-NCAP protocol



Camera output



LiDAR output

[URL for FOT details and how to join](https://www.nedo.go.jp/english/news/ZZCD_100017.html)  
[https://www.nedo.go.jp/english/news/ZZCD\\_100017.html](https://www.nedo.go.jp/english/news/ZZCD_100017.html)

**Thank you**

