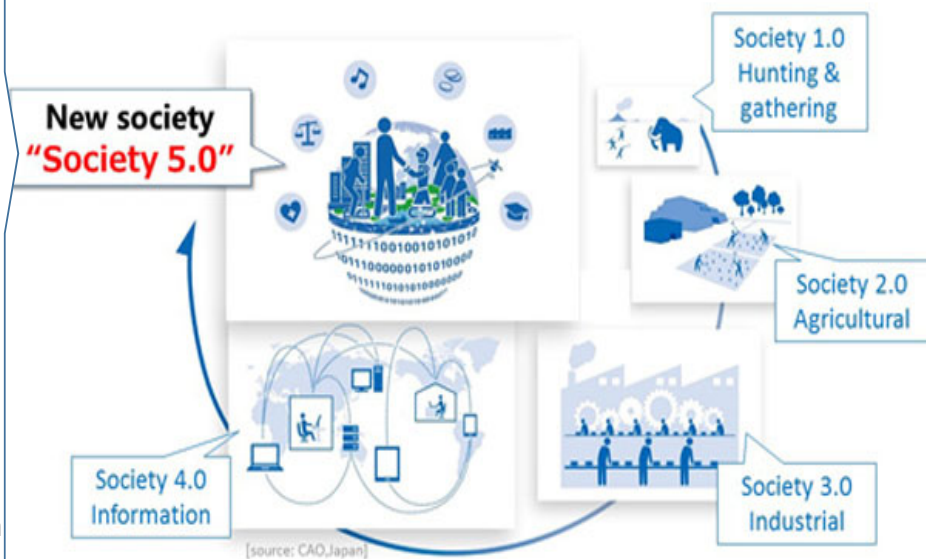
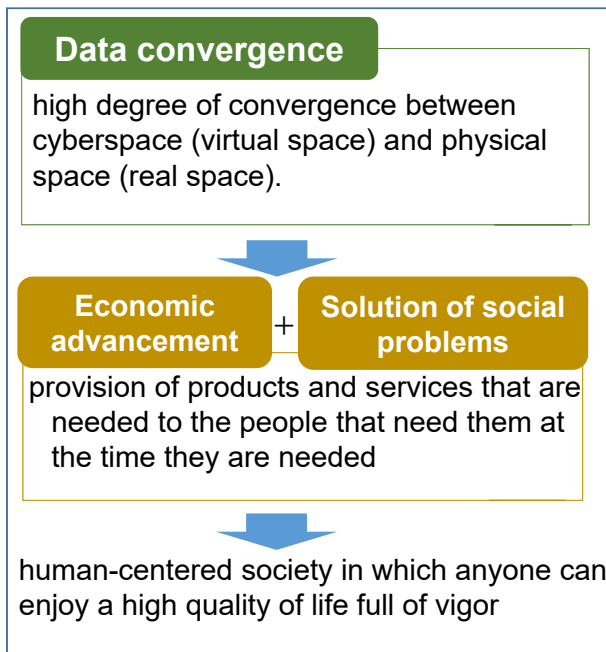


## Overview

- Promote cross-sector and **industry-academia-government collaboration**
- Intensive R&D program from **fundamental research to practical and commercialization**
- Promote Regulatory reform

SIP 2<sup>nd</sup> FY2018~FY2022

12 themes on going (SIP-adus is one of them)



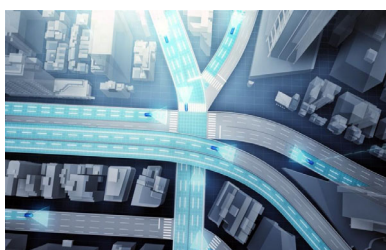
(Cabinet office HP)

### ADS (Automated Driving Systems)

Safe and secure mobility for all



**Competition**



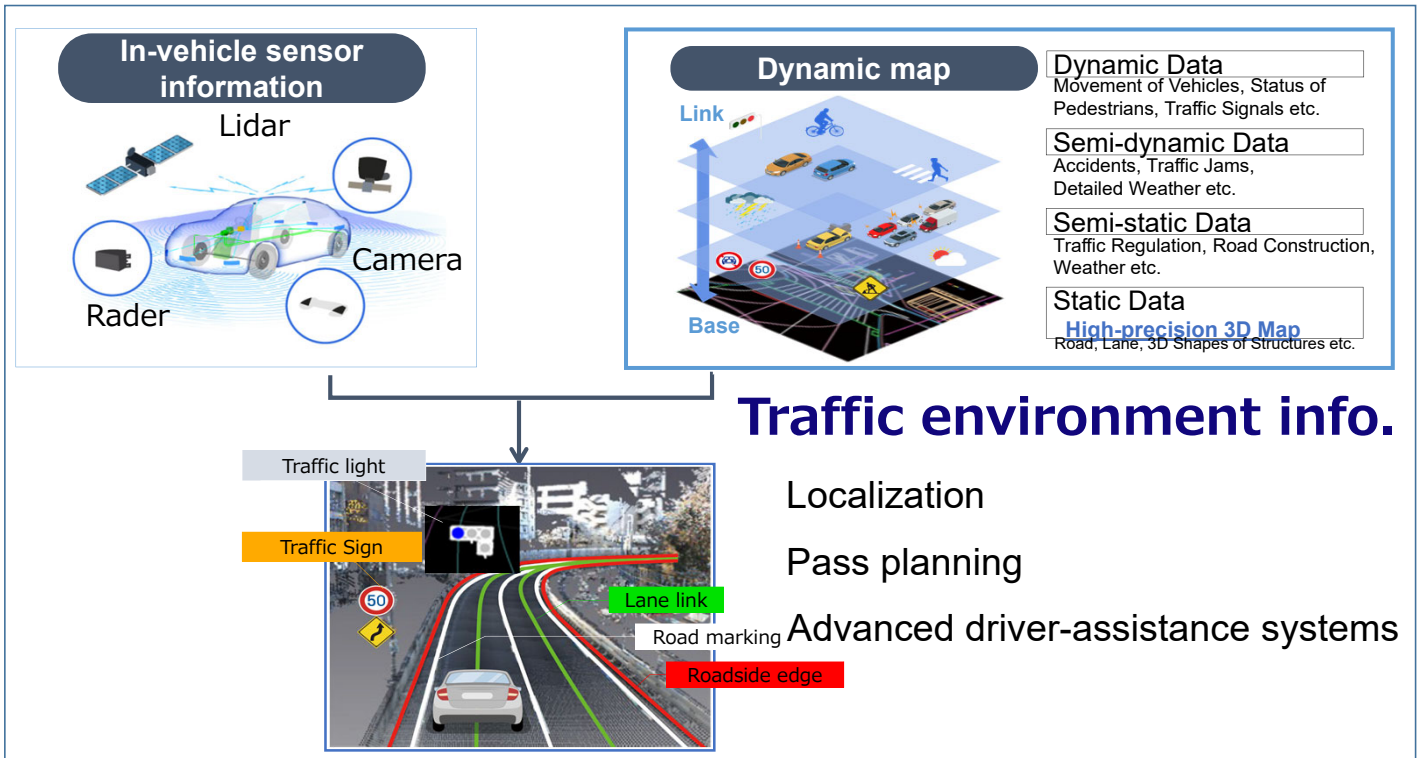
**Cooperation**

### Realization of Society 5.0



# ① Dynamic map

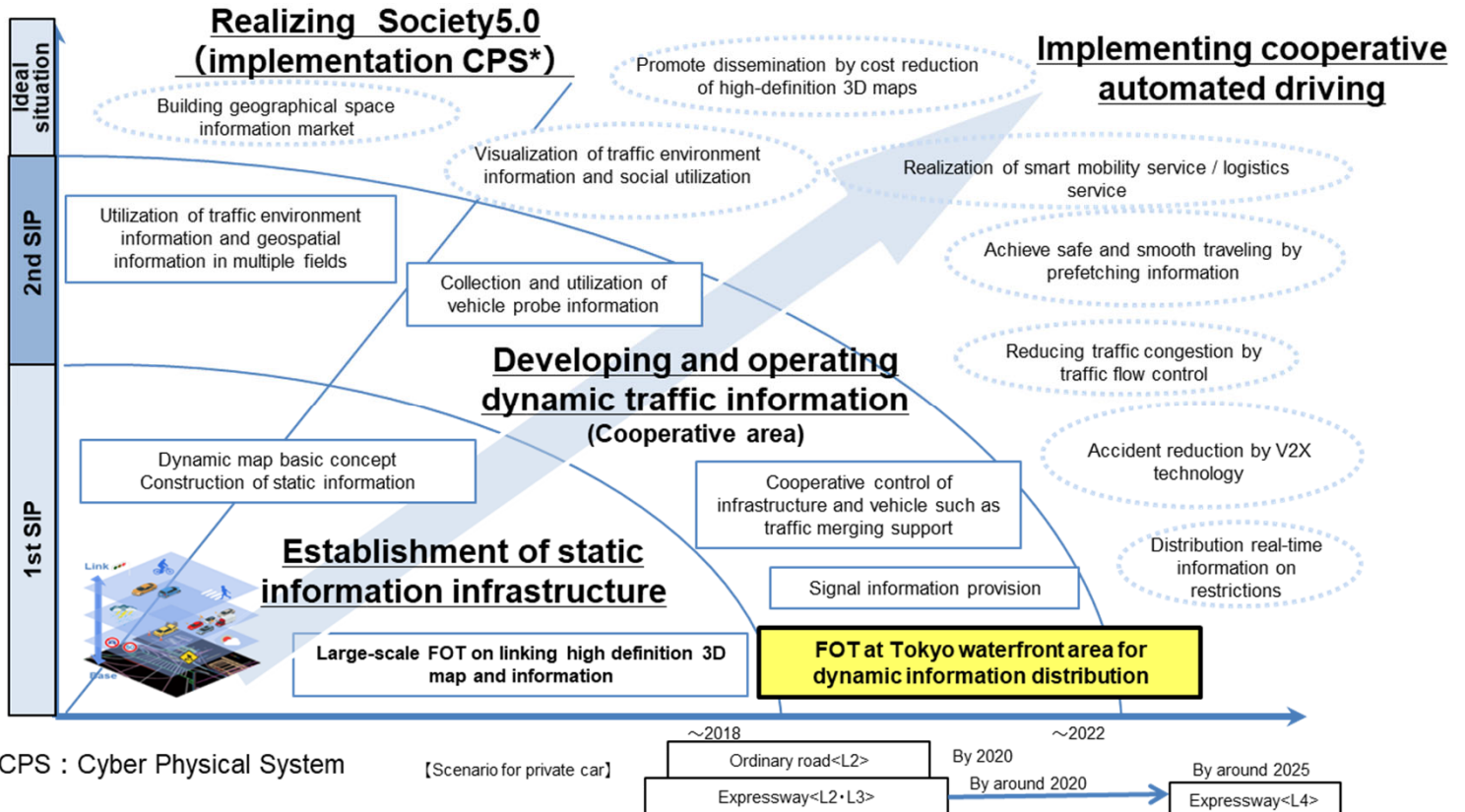
## Structure of ADS



Technology development in cooperative areas

Realization of Society 5.0

## Building the Traffic Environmental Info. Framework



\*CPS : Cyber Physical System

[Scenario for private car]

# FOTs in Tokyo waterfront area

## Focus

- Promoting standardization in an internationally open experimental environment under public roads and mixed traffic
- Promoting R&D by drawing out private investment through a matching fund format with industry-academia-government collaboration
- Improving measures to foster public acceptance with planning test drive events, etc. in connection with the Tokyo Olympics and Paralympics



Orange : Tokyo Waterfront City area  
Blue : Haneda Airport area  
Green : Metropolitan Expressway



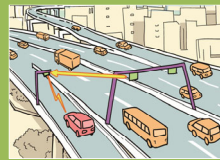
### (a) Tokyo Waterfront City area

- Traffic signal information from ITS roadside unit.
- HD 3D map linked with signal info. etc



### (b) Haneda Airport area

- Traffic signal information from ITS roadside unit.
- Magnetic marker
- Bus stop, designated lane for bus service



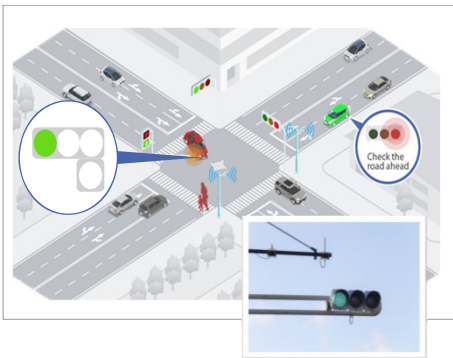
### (c) Metropolitan Expressway

- Merging assistance at main lanes of expressway
- ETC gate open/close info.
- Lane level traffic flow regulation info. Etc.

Participants from 29 institutions, including domestic and overseas automobile manufacturers, suppliers, universities, and other institutions.  
※As of 2020

## (a) Tokyo Waterfront City area

- Demonstrated the effectiveness of providing **signal information** via V2I

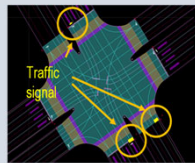


Installed V2I (760MHz) equipment at 33 intersections in Odaiba

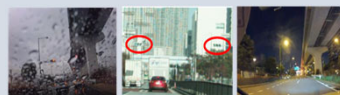


- Confirmed that **signal recognition** can be performed stably under various conditions based on **V2I information**.

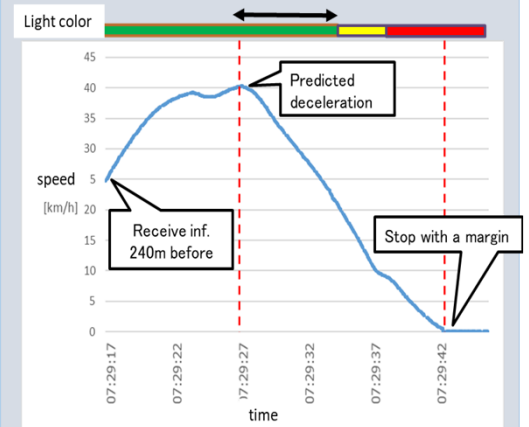
Superimpose display of the received V2I information on a high-precision 3D map



Ex.) Traffic signal color (green/yellow/red)



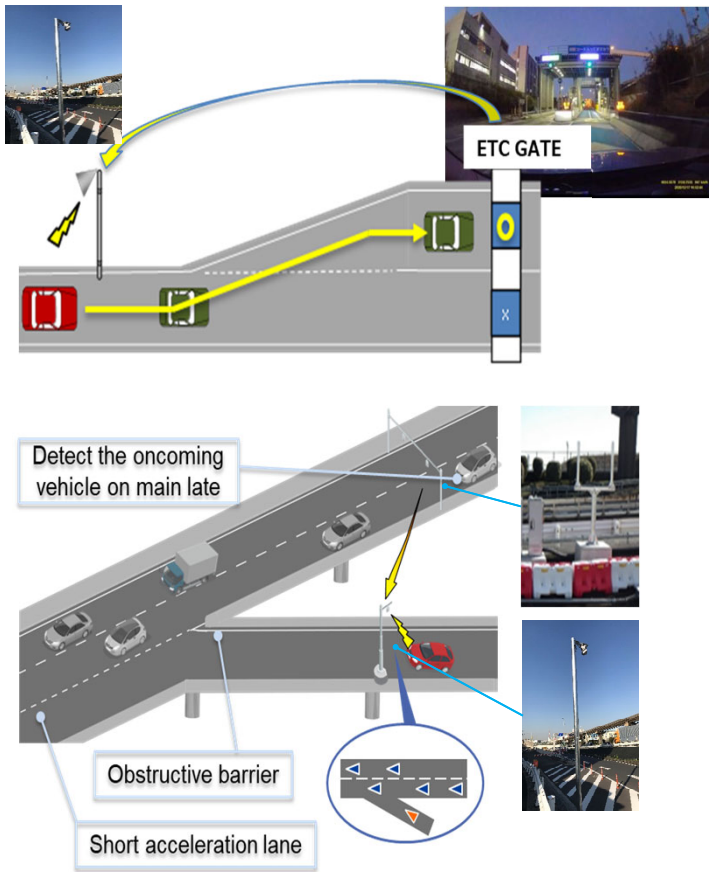
- Confirmed that the **dilemma zone\*** can be avoided by V2I remaining seconds information



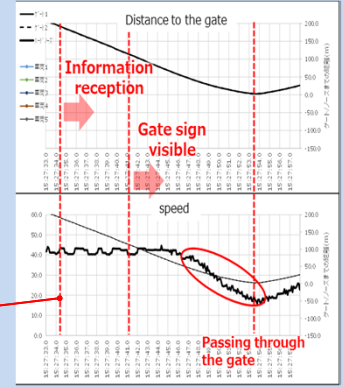
\* It is the timing which the vehicle cannot pass the stopping line, and stop without sudden braking in yellow light.

# (b) Tokyo metropolitan expressway

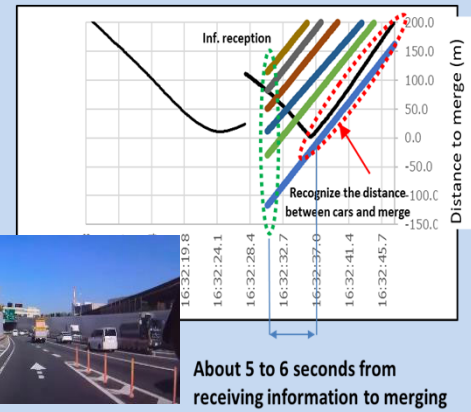
➤ Demonstrated the effectiveness of **merging support information** via V2I



➤ **Smooth course change and gate passage** due to early recognition of operating gates.

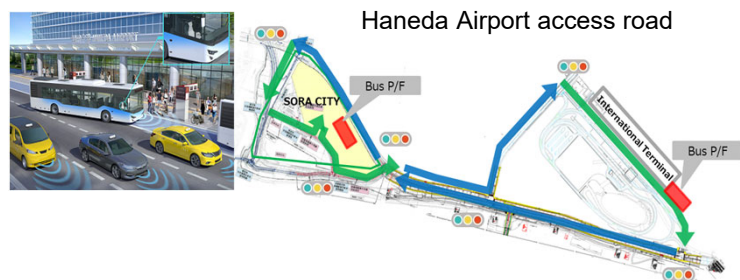


➤ Confirmed the possibility of **merging judgment and speed control** aiming at the gap by automated driving control.



# (c) Metropolitan Expressway

➤ Demonstrated the realization of **next-generation ART\*** using AD technology under mixed traffic.



**Road vehicle coordination equipment**



Track guidance magnetic marker



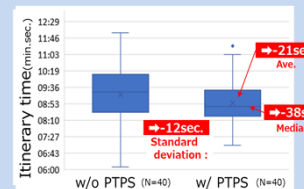
PTPS\*\* & Signal info. via V2I



Dedicated bus lane

(\*\*PTPS: Public Transport Priority system)

➤ Demonstrated **level 4 AD bus** that does not require driver intervention and **on-time express delivery** by road-vehicle cooperation.



➤ Demonstrated a bus that is friendly to all people by gentle acceleration / deceleration and **precise docking for accessibility** (45mm± 10 mm) by AD control.



Achieves reproducibility with standard deviation of less than 10 mm

# ② Safety Assurance

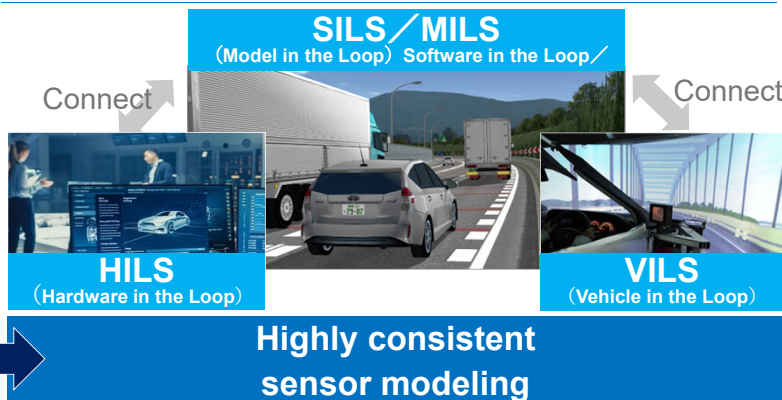
## Focus

- Developing a simulation platform that replaces real vehicle evaluations with sensor modelling that is highly consistent with real phenomena, in order to perform reproducible safety evaluations of automated driving in various traffic environments.

### Real experimental test

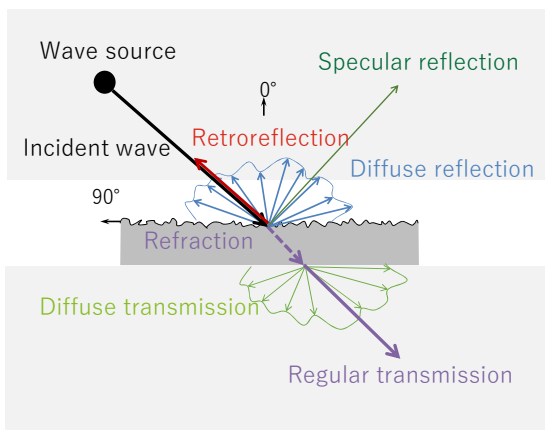


### Virtual test



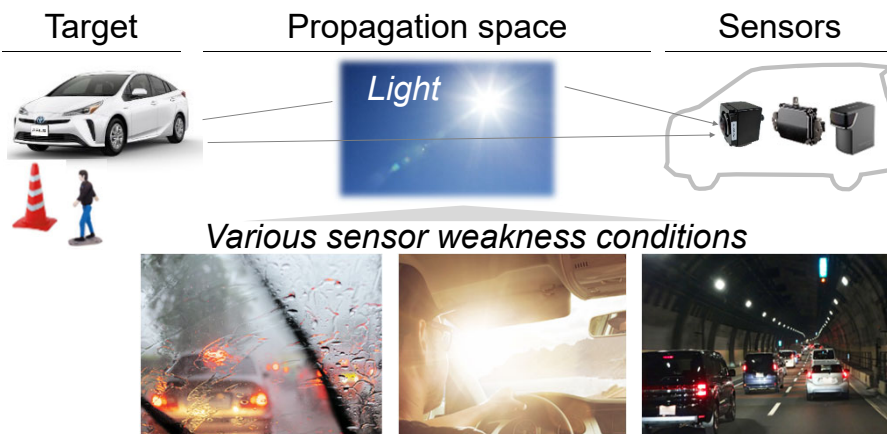
### Measurement base modeling

- 3-sensor electromagnetic wave characteristics measurement



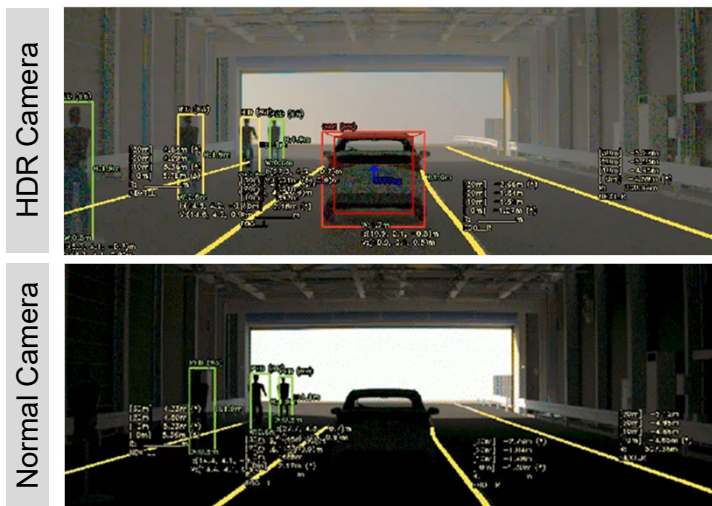
### Sensing physics base simulation modeling

- Sensing physics based detailed simulation modeling realize various sensor weakness conditions such as rain, backlit, multi-pass ,etc



### Sensor validation

- Precise environment & sensor pair modeling able to validate perception for safety assurance



### German Japan international collaboration

- DIVP and VIVALDI from Germany launched VIVID collaboration project for Safety assurance standardization

VIVID Partners for VIVID collaboration



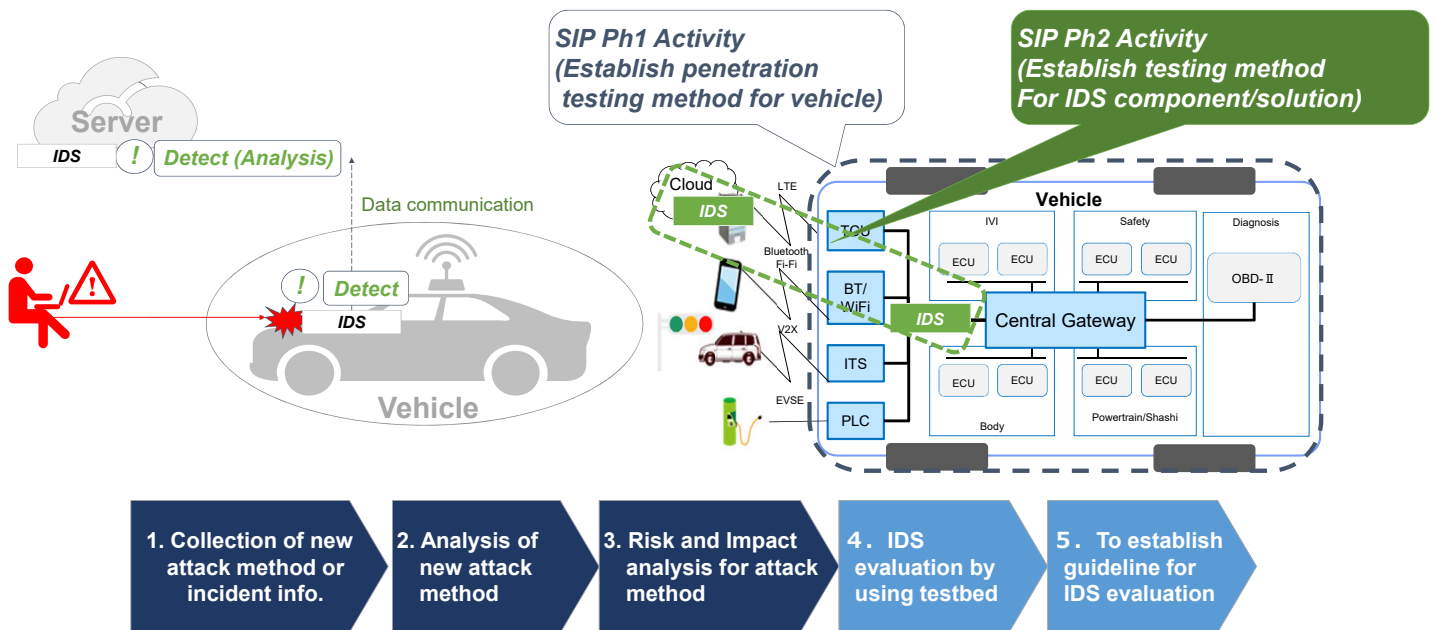
Objectives

- How safe is safe enough?
- How realistic is realistic enough?

# 3 Cybersecurity

## Objective

➤ To Establish **evaluation method for Intrusion Detection System(IDS) components/ solutions** provided by various security vendors from the view point of user(OEM).

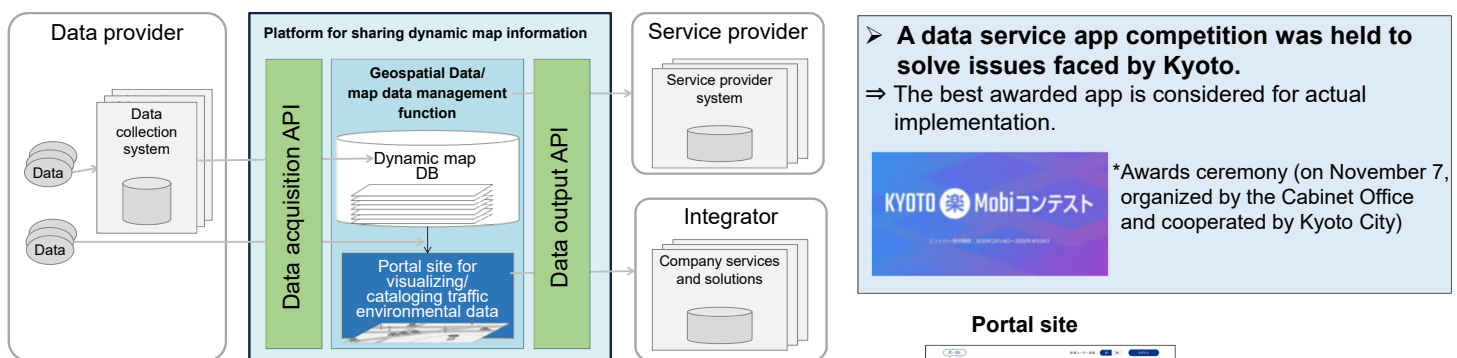


Efforts will be made to **establish guidelines** in cooperation with an industry organization (JASPAR).  
 JASPAR (Japan Automotive Software Platform and Architecture)

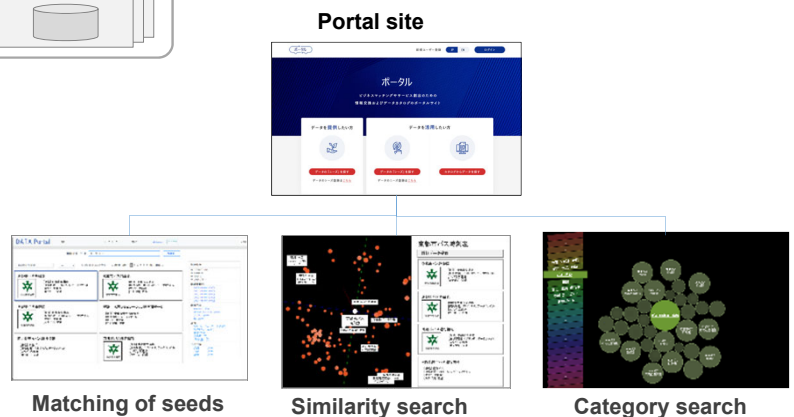
# 4 Geospatial dynamic data utilization

## Objective

➤ **Enabling relation and sharing of data by compiling and structuring data** possessed by business operators in **various fields to solve social Issues and create new services**



- **Data providers are matched with data users** on the portal site to **promote data sharing** by using an open API.
- **The portal site has been made accessible by limited users on a trial basis (first phase)** since the end of October 2020. It **will be made publicly available in spring 2021**.
- Collaboration will be made to **increase the number of partners (supporters)** of data providers and data users, respectively.



Start from September 2019

## Human Factors



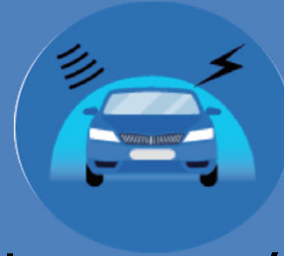
## Impact Assessment



### JPN-GER Cooperation



## Safety Assurance



## Cybersecurity

Start from October 2020

Start from November 2020

## Objective



### Human Factors

- Accelerate successful introduction of safe automated vehicle technology by this collaboration.
- Increase social acceptance of automated systems for broader international markets based on cross-cultural comparisons and considerations of obtained results.



### Impact Assessment

- Expectation of the deployment of automated driving vehicles (ADs) to solve several social problems.
- ADs are necessary to be installed with equate consent by people and society.



### Safety Assurance

- Define open standard Interfaces, to establish 'reference platform' with reasonable verification level, especially, for sensor modeling, and to establish the Environment & Sensor pair model-based approach for Validation & Verification reality.



### Cybersecurity

- Establish evaluation method for Intrusion Detection System(IDS) components/ solutions provided by various security vendors from the view point of user(OEM).

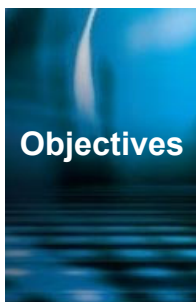
# Event announcement : SIP-adus Workshop 2021



✓ **Date : November 09-10, 2021**

✓ **Format : Virtual conference**

✓ All sessions will be streamed live on line, additionally streamed in Central European Time and Eastern Standard Time(U.S.) for worldwide participants.



To share the latest reports as below from global experts to find out our future views and seeds of further cooperation towards Society 5.0 with higher possibilities, by exchanging opinions through thematic sessions and workshops

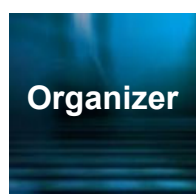
- Reports by industry and academia research partners on the achievements of SIP-adus projects in Japan.
- Presentations by global experts on recent global progress and the status of R&D themes focusing on automated driving and connected vehicles.

## Session Theme

<b>Regional Activities</b>	Introduction of regional activities regarding automated driving
<b>Service and Business Implementation / FOTs</b>	Business model and planning scheme for accessible automated driving
<b>Dynamic Map</b>	Dynamic contents distribution/exchange with Dynamic Map and the updates
<b>Connected Vehicles</b>	Trends in Cooperative Driving Automation
<b>Safety Assurance</b>	Safety Assurance Virtual Testing Requirement and Validation
<b>Cybersecurity</b>	Utilization of IDS/IDPS* for the realization of cyber-safe automated driving
<b>Human Factors</b>	Human factors in automated mobility services
<b>Impact Assessment</b>	Social Impact of Automated Driving technologies

\* IDS / IDPS : Intrusion Detection System / Intrusion Detection and Prevention System

As of September 6, 2021



Cross-Ministerial Strategic Innovation Promotion Program, Council for Science, Technology and Innovation, Cabinet Office, Government of Japan  
New Energy and Industrial Technology Development Organization (NEDO)  
Supported by ITS Japan

For the latest information

<https://en.sip-adus.go.jp/evt/workshop2021/>