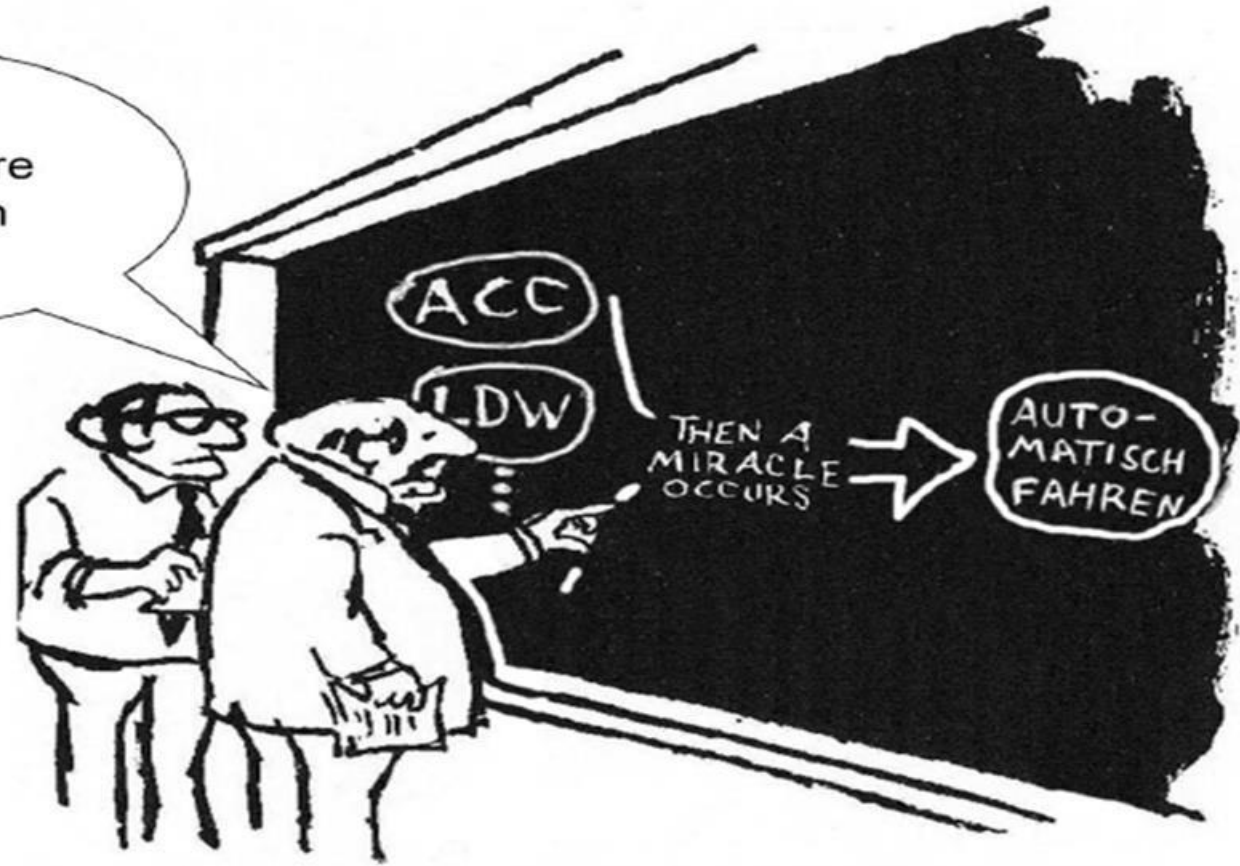


# Challenges on data necessary to serve Automated Driving

Jean-Charles Pandazis, ERTICO - ITS Europe  
SIP-adus workshop, dynamic map session  
Tokyo, 14/11/2017

I think you should be more explicit here in step two.



modified according to Sidney Harris

# Challenges on Data Necessary to Serve Automated Driving

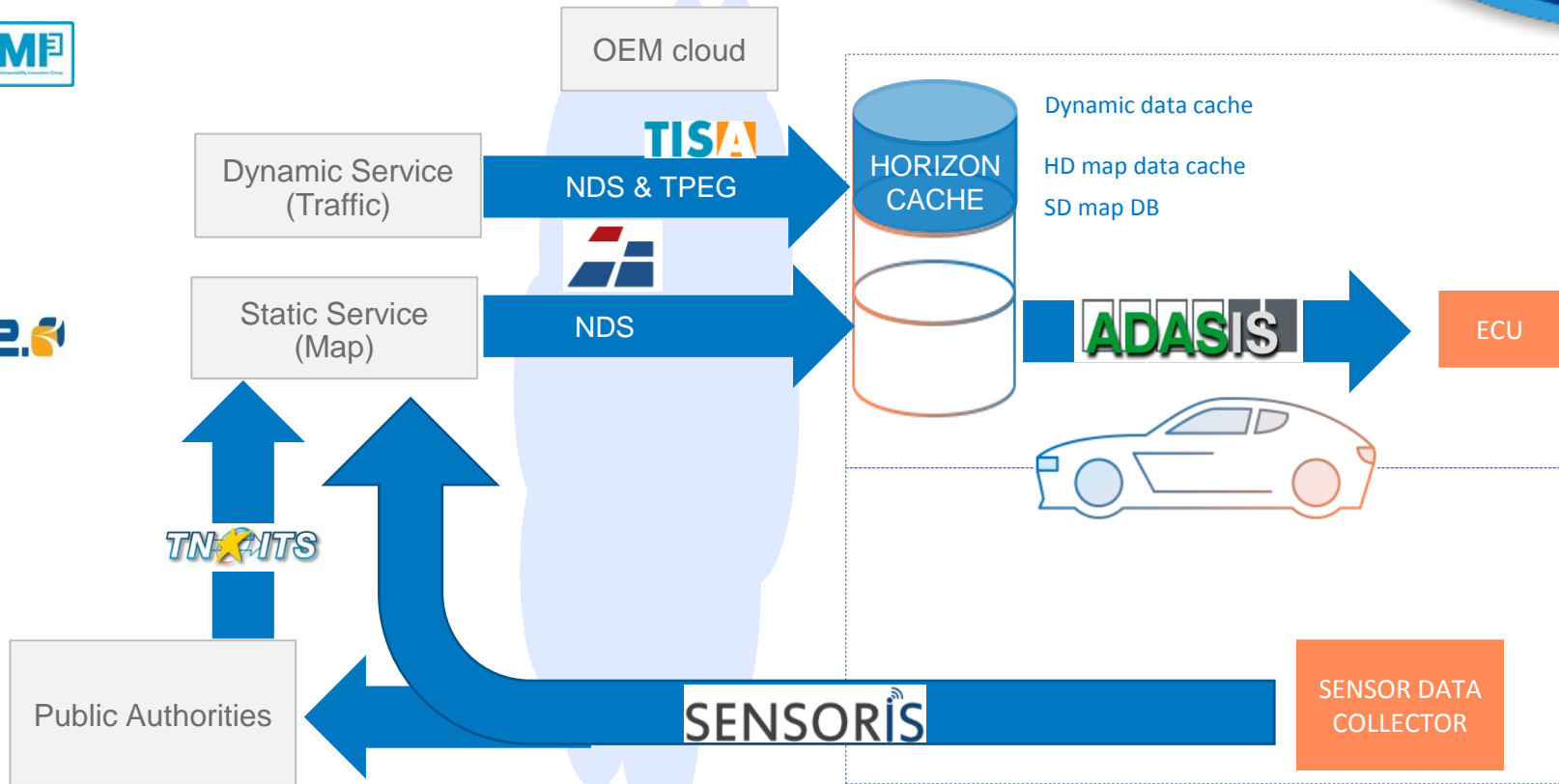
Data/Information is key and a common denominator, but what do we have today?

- many initiatives around Automated Driving
- many stakeholders with different views
- many use cases involving data of different kind
- standards fragmentation

What do we need?

- harmonisation and coherency
- same understanding of the data eco-system

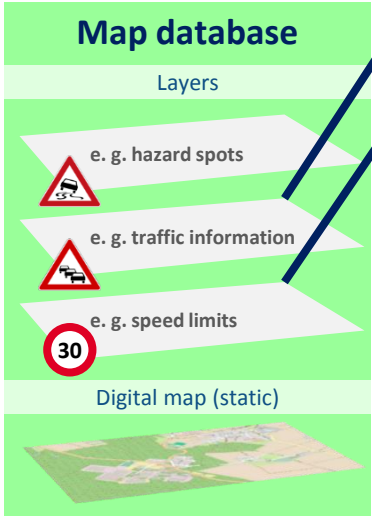
# Automated driving data chain, ecosystem and beyond





TPEG: Traffic Information

NDS: Incremental Map Update



Map data  
(e.g. NDS Format)

- ▶ Determination of location and most probable path (MPP)
- ▶ Enrichment of MPP with road information (e.g. topography, speed limits)
- ▶ Conversion into ADASIS format

Relevant information  
for road ahead  
(ADASIS Format)





## Energy Efficiency

- ▶ Reduced fuel consumption by linking topographic and speed limit information to other control units (e.g. cruise control, intelligent gearbox management)
- ▶ Improvement of battery consumption through driving strategies for (hybrid) electric vehicles



## Connectivity & Assistance

- ▶ Increased safety and comfort for driver through predictive, real-time road information
- ▶ Enhanced performance of driver assistance systems
- ▶ More precision for electric vehicle range estimation



## Automated Driving

- ▶ Provision of road information beyond reach of vehicle sensors is a key requirement for automated driving systems
- ▶ Enhanced performance of automated driving systems
- ▶ Enabling precise localization

**ADASIS horizon addresses all major future mobility trends: connected, electrified and automated**

## Vehicle Manufacturers (16)

BMW  
 China FAW-RDC\*\*  
 CRF (FCA)\*\*  
 Daimler \*  
 Ford \*  
 Ford-Otosan  
 Honda \*  
 Hyundai Motor Company  
 Jaguar  
 Opel \*  
 Nissan  
 Renault  
 Toyota Motor Corp.  
 Volkswagen  
 Volvo Car Corp.  
 Volvo Tech. Dev. Corp.

## ADAS Manufacturers (17)

Autonomos  
 Continental Automotive \*  
 CTAG  
 Delphi Automotive systems\*\*  
 Denso  
 dSPACE  
 Fujitsu Ten (Europe) \*\*  
 Hitachi  
 Ibeo  
 IPG  
 Knorr-Bremse\*\*  
 LG Electronic  
 Magna Electronic Europe  
 Magneti Marelli  
 Novero  
 TRW (ZF)  
 Valeo

## Navigation System Manufacturers

AISIN AW (13)  
 Alpine  
 Autoliv  
 Elektrobit Automotive  
 Garmin  
 Harman  
 Mappers Co.\*\*  
 Mitsubishi Electric Europe  
 MXNAVI  
 NNG LLC  
 Panasonic  
 Robert Bosch GmbH \* (ADASIS Chair)  
 Telenav

\* Steering Board Members

\*\* New Members since 06/2016

## Map & Data Providers (10)

AND	GeoDigital Automotive**	Wuhan Kotei Informatics**
AutoNavi Holding	Here *	Zenrin
Baidu Netcom**	Navinfo Co	
eMapgo Technologies**	TomTom *	





New ADASIS v3 specifications supports different aspects of autonomous driving

- Support of HAD maps (NDS)
- supporting long range horizon without any restrictions
- update & erasure mechanism for dynamic data



Copyright: Here.com

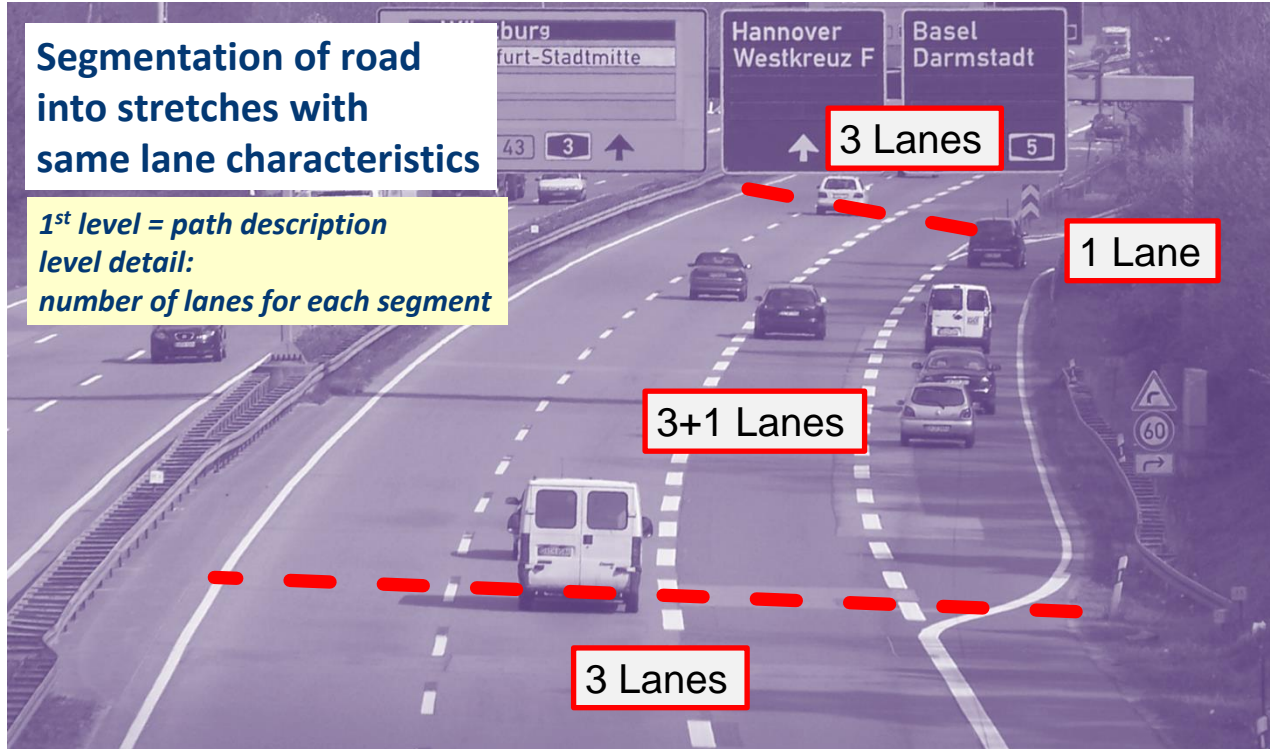


Lane model & Geometry

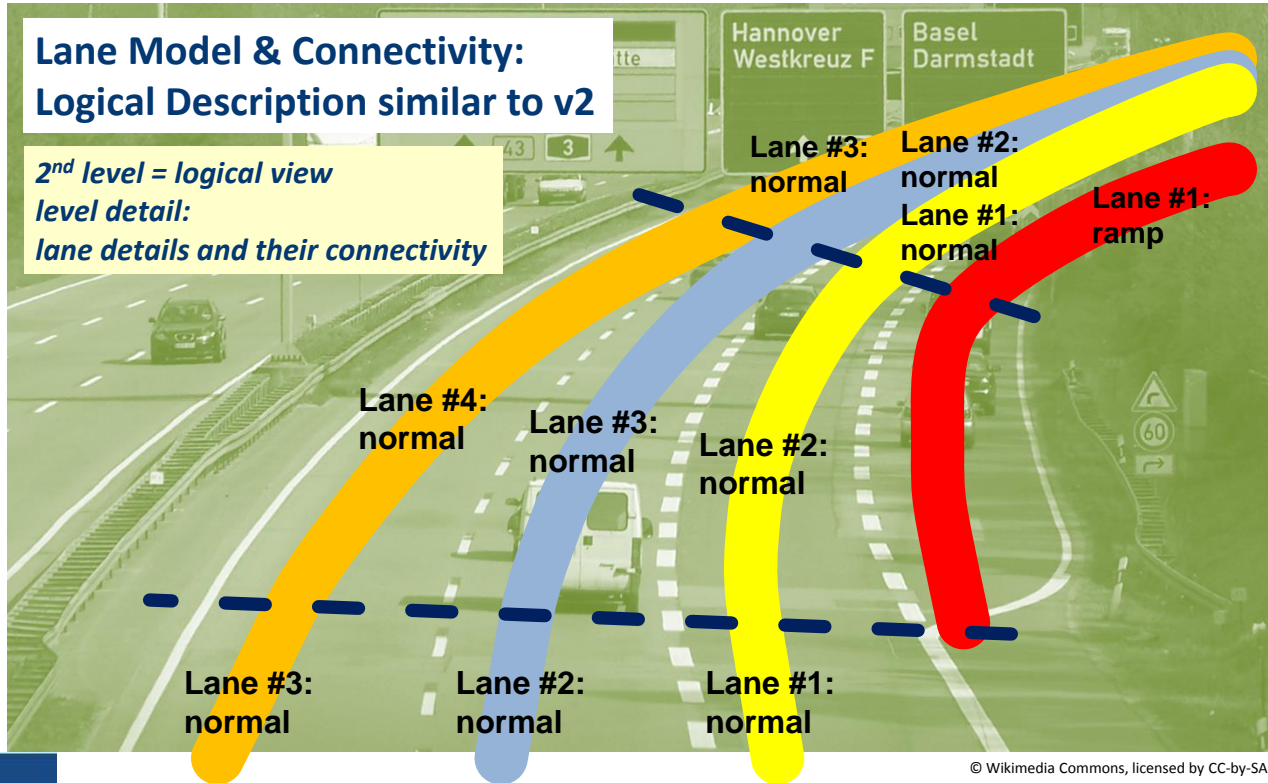


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## Lane model & road segmentation

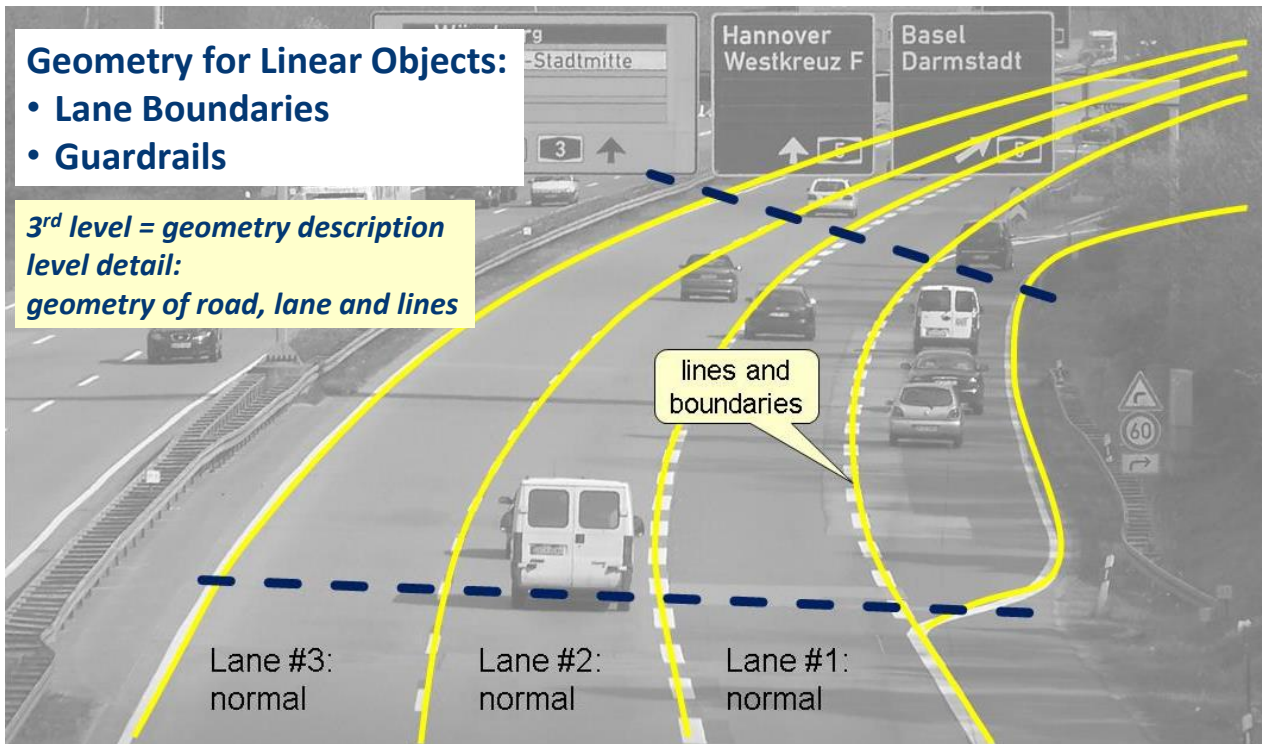


## Lane model & connectivity



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## Lane model & geometry



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# ADASIS Next steps

- v3 specifications currently under review within ADASIS
- Release of ADASIS v3 specifications to all ADASIS members (Q1/2018)
- Public release planned one year after (Q1/2019)
- Development of a reference implementation for ADASIS members only
- Initiate cooperation with ITS Japan and other ITS organisations to wider inform on ADASIS

# SENSORIS - Vehicle based Sensor Data Interface

- Initiated by HERE, coordinated by ERTICO, Constituted on June 2016
- Open group from the global vehicle industry and suppliers who joined forces to standardise open specifications for vehicle based sensor data interface
- Focus on Sensor Data upstream
- Part of Open AutoDrive Forum => alignment with NDS, ADASIS and TISA
- Liaison with other Sensor Data specifications, e.g. Ko-HAF project (BMBF)
- 1st specifications planned for Q1/2018, Public released planned Q1/2019
- Initiate cooperation with ITS Japan and other ITS organisations to wider inform on SENSORIS

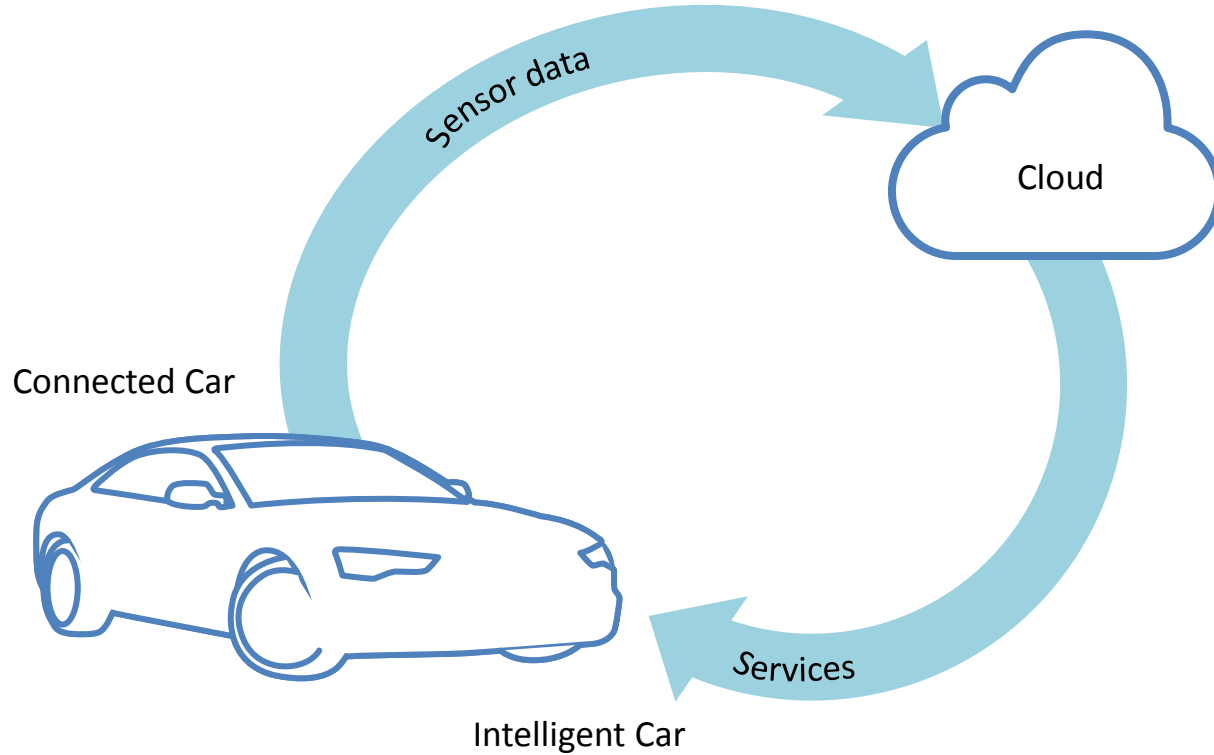


# SENSORIS members (26 including 5 Japanese members)

Main membership category	SENSORIS member	Main membership category	SENSORIS member
<b>Vehicle manufacturers</b>	Audi	<b>ADAS manufacturers</b>	AISIN AW
	BMW AG		Continental Automotive GmbH
	Daimler AG		Fujitsu Ten (Europe) GmbH
	Jaguar Land Rover Limited		LG Electronics
	Volvo Car		Valeo Comfort and Driving Assistance
<b>Location content &amp; Service providers</b>	AutoNavi Software Co. Ltd.	<b>Navigation System Suppliers</b>	DENSO
	Baidu		Elektrobit Automotive GmbH
	HERE Global B.V. (Chair)		Harman
	INRIX Inc.		Hyundai Mnsoft
	NavInfo Co.Ltd.		NNG
	TomTom International B.V.		PIONEER Co.
	Zenrin		Robert Bosch Car Multimedia GmbH
<b>Telecom &amp; Cloud Infrastructure Providers</b>	IBM	<b>Other</b>	ICCS

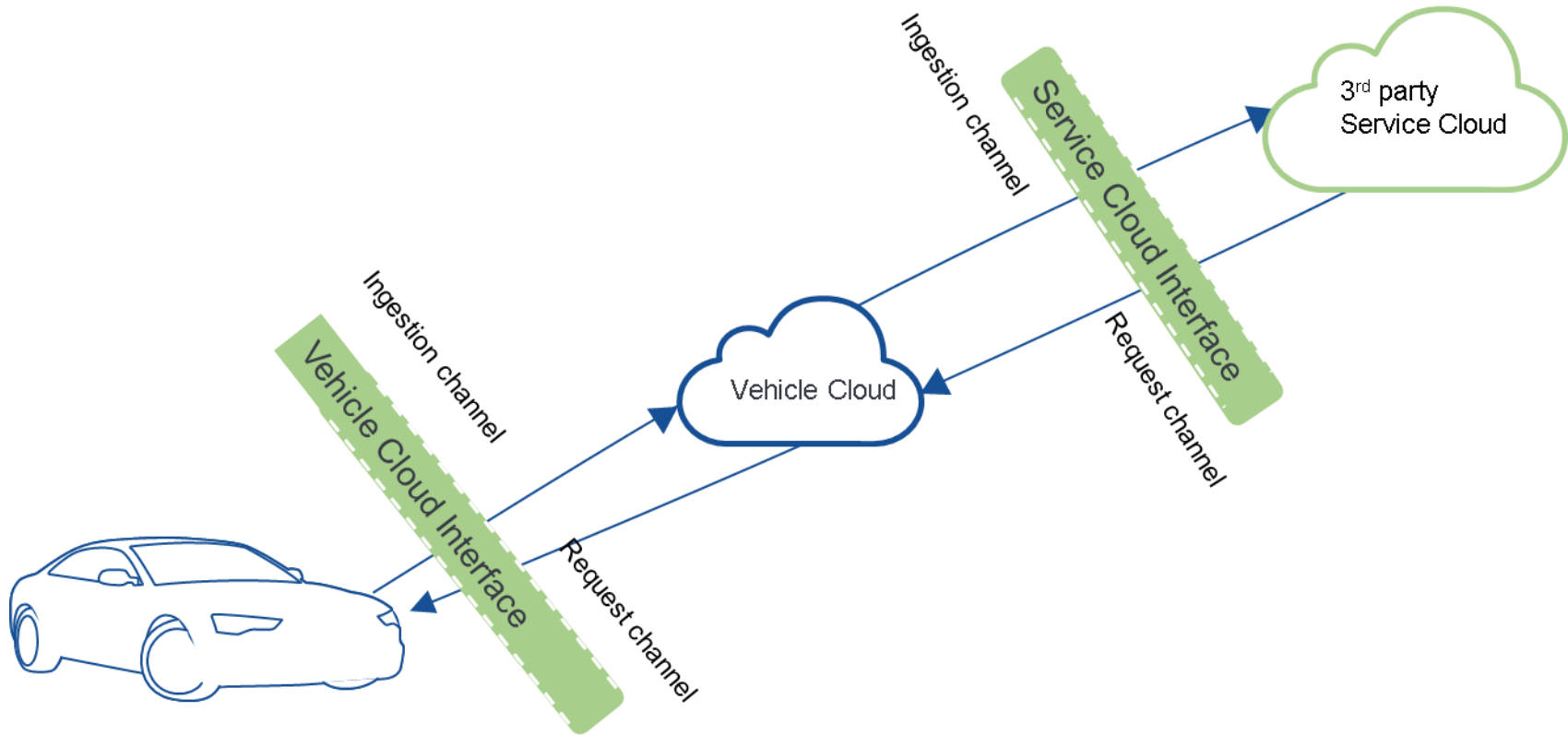


# SENSORIS <sup>IS</sup> Closed feedback loop between car and cloud

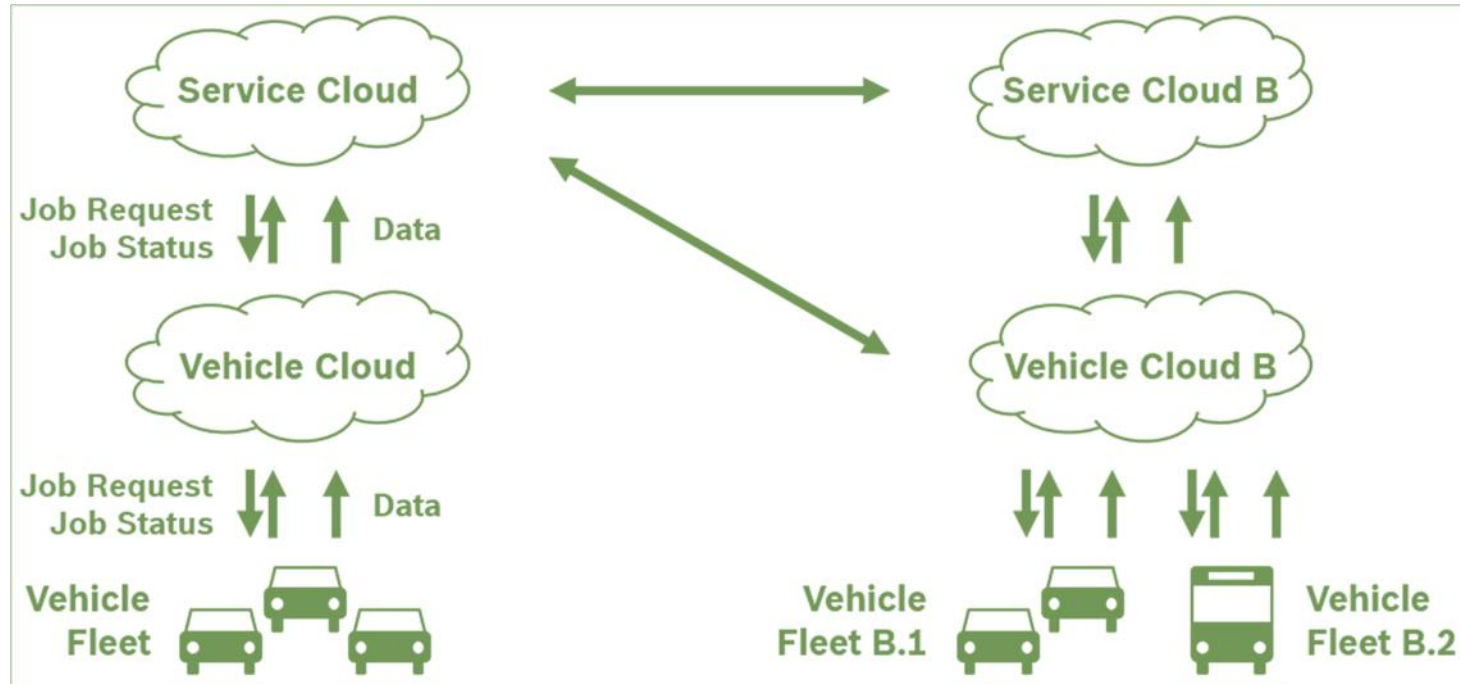




# SENSORIS the sensor data interfaces



# SENSORIS<sup>®</sup> architecture: Multi-role model



# SENSORIS Use case: Real-time services



Traffic flow  
Traffic incidents



Hazard warnings

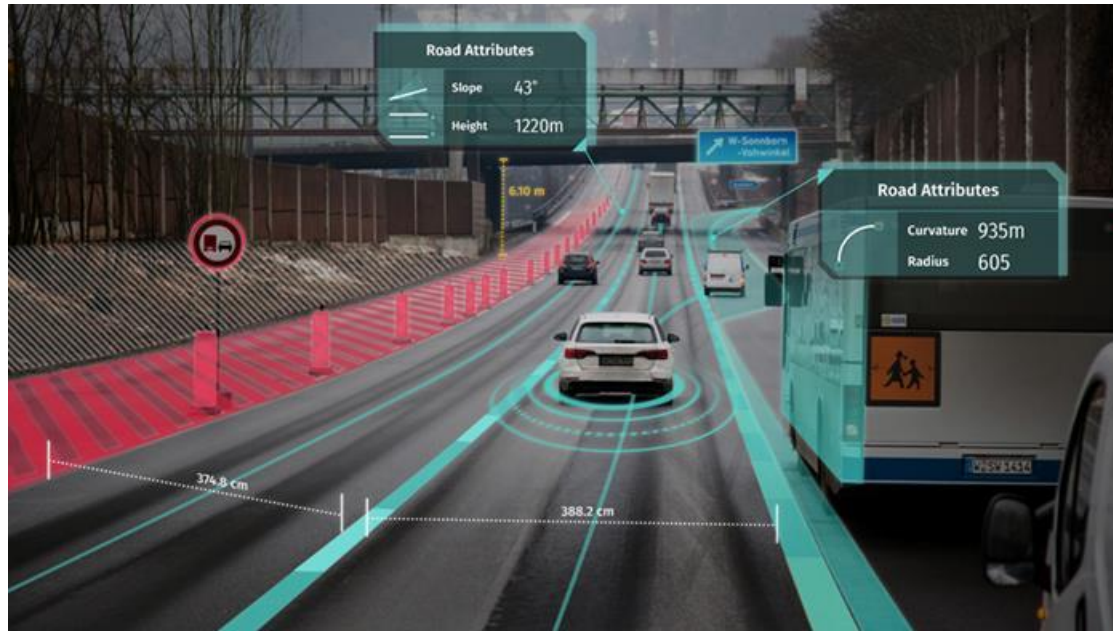


Environmental conditions



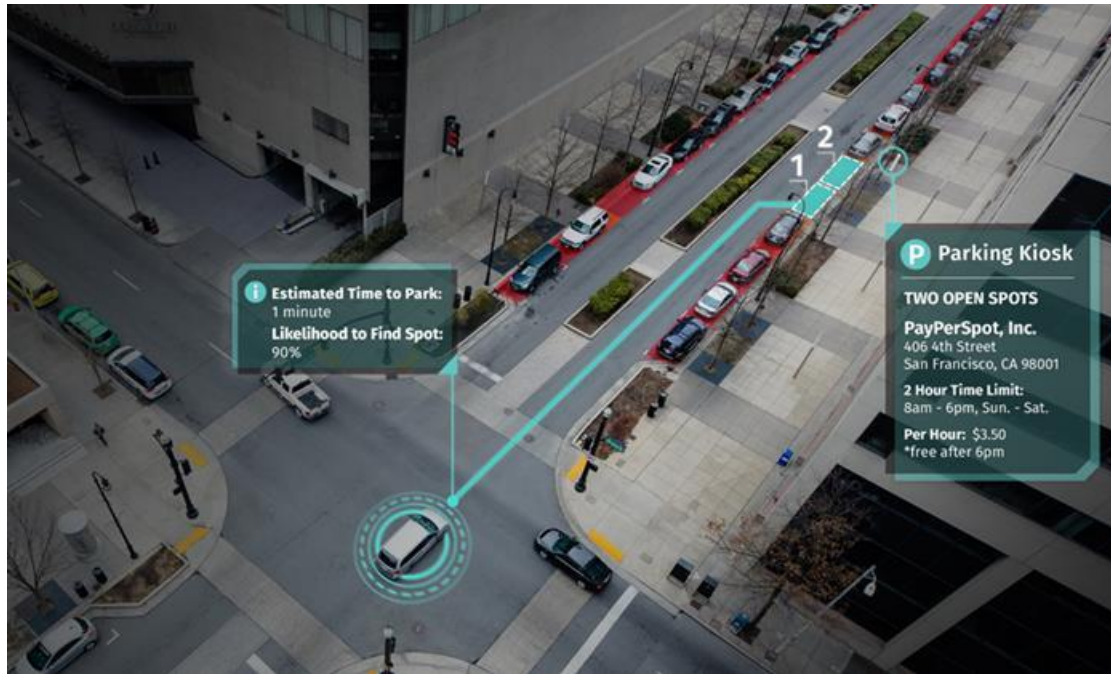
Traffic signage

# SENSORIS Use case: Self-healing map



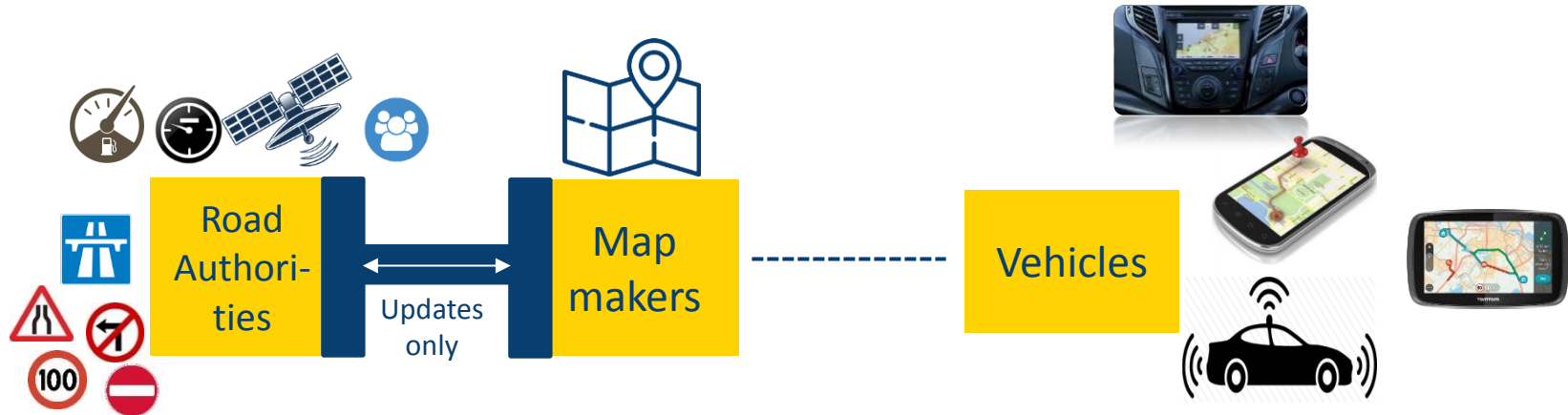
- Road geometry and attributes
- Lane geometry and attributes
- POI entries and exits
- Road condition

# SENSORIS Use Case: Statistical analysis



- Historical and real-time data analysis
- Personal preference learning
- POI recommendations

# The data chain in a nutshell



Map data is obtained from vehicles, public authorities and various other sources (social media, satellites, etc.)

Mapmakers assemble all these to provide the most efficient maps and navigation advice

Drivers can benefit from up-to-date fresh map data in their in-vehicle system, stand-alone navigation device or smartphones

## Vision

Bringing fresher map data to intelligent transport services

## Mission

Facilitate and foster the exchange of ITS-related spatial road data between road authorities as trusted data providers and data users as map makers and other parties



## Standardisation

Define & maintain  
TN-ITS specifications in  
CEN/TC 278 WG7

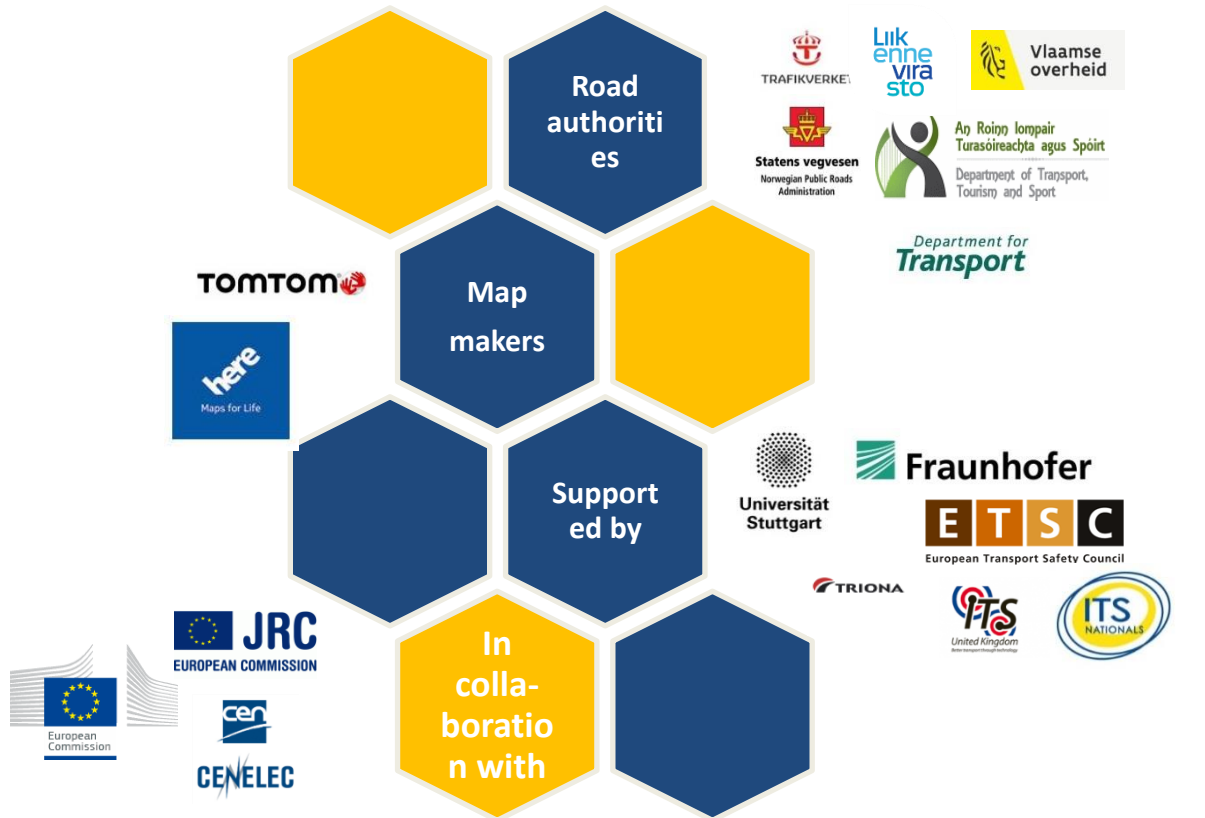


## Implementation

Provide guidelines, tools and  
services to support  
implementation in **Belgium,**  
**Finland, France, Ireland, Norway,**  
**Sweden, and United Kingdom**

**(NL, HU, CY, SL, EE, LT, PT, ES, GR)**





# Conclusion

- ERTICO platforms have a clear focus on data interface enabling industrial solutions
- Harmonisation is needed and succeed today under the OADF
- Include other standard organisation beyond Automated Driving ecosystem
- Initiate cooperation with ITS Japan and other ITS organisation to achieve world-wide awareness

# Thank you for your attention!

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