

# Human Factors

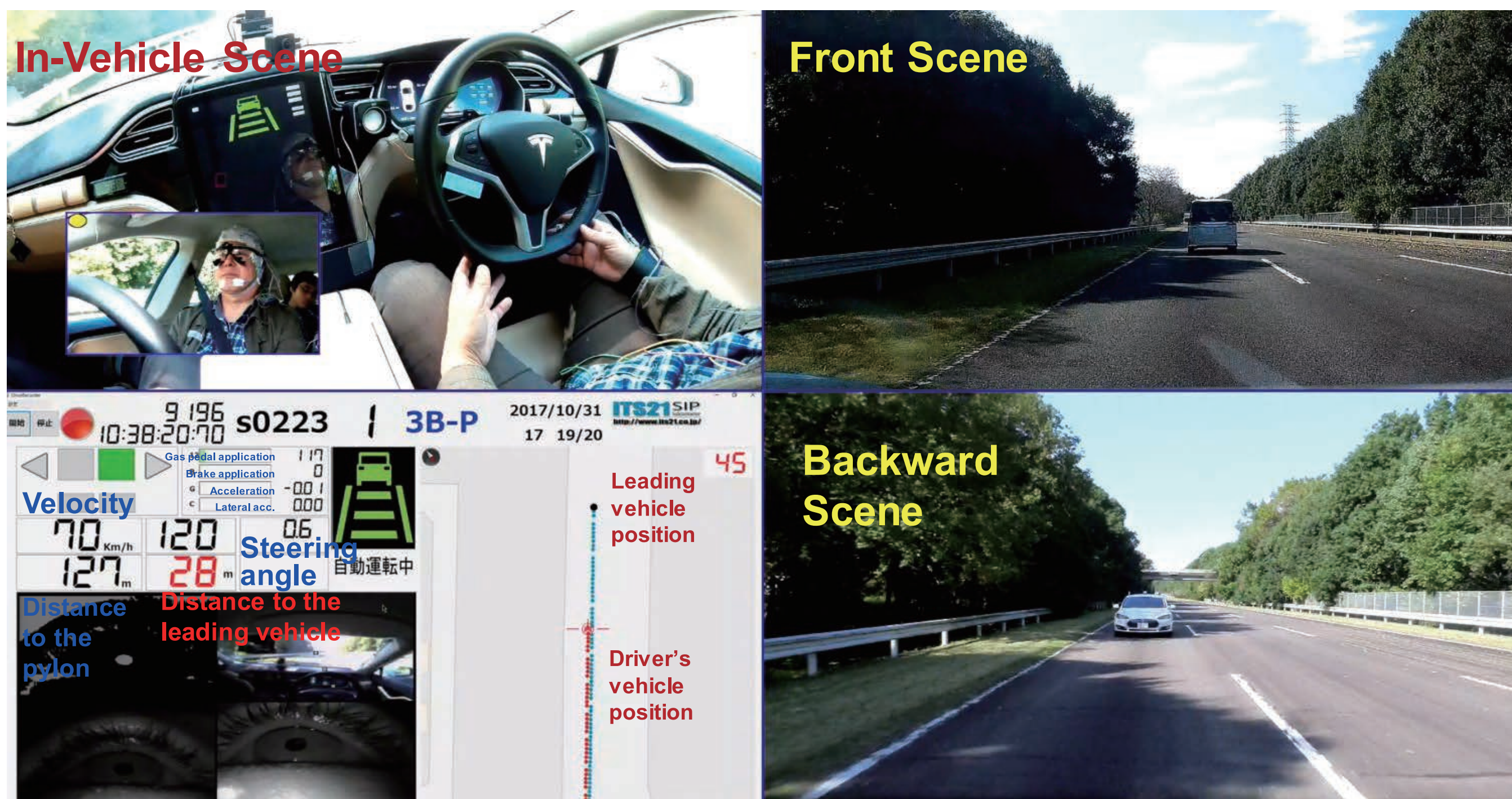


## Task B

### Assessment of driver states in automated driving and Investigation of driver controllability in transition from automated to manual driving

FY2016: Driving simulator experiment

→ **FY2017: Proving ground experiment**



Rtl (Request to Intervene) [6sec before reaching to the pylon]

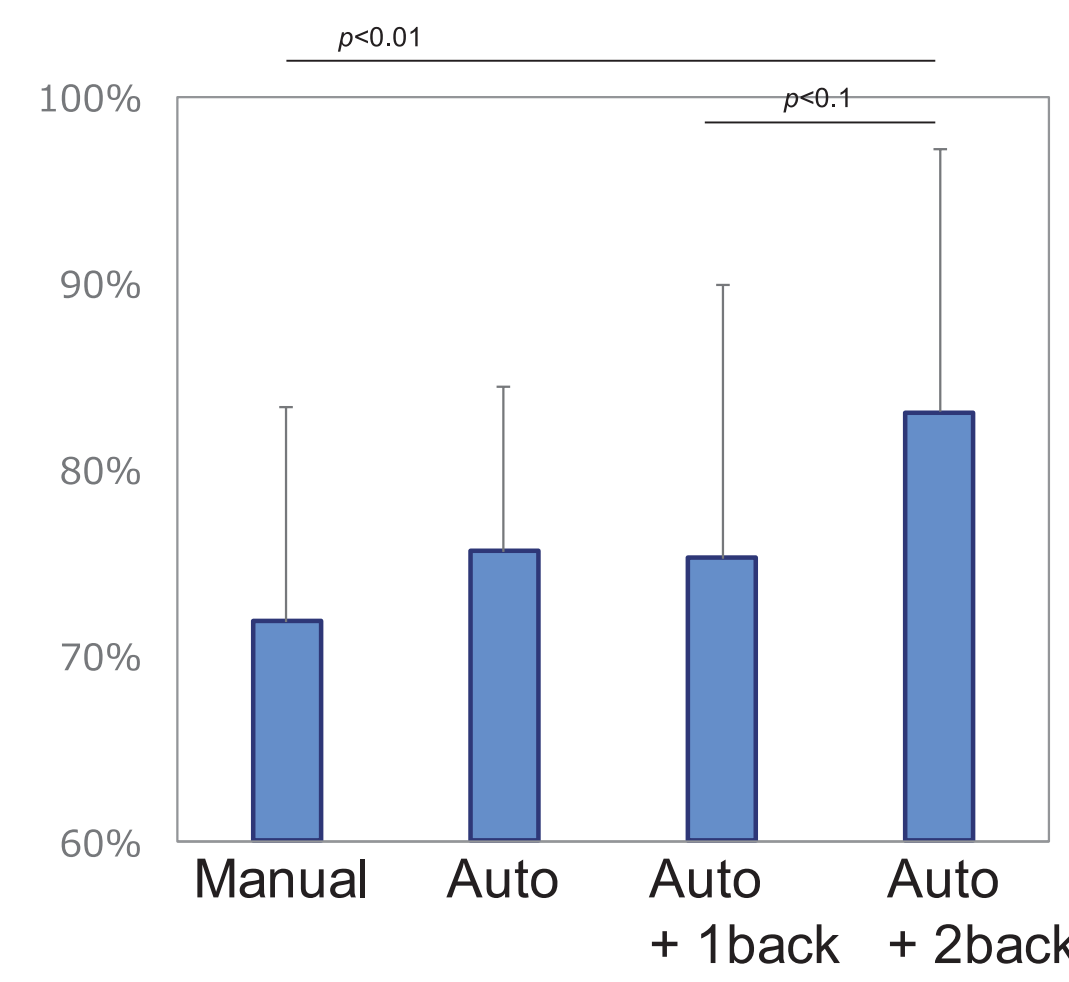
**Automated Driving** → **Manual Driving**

- Following the lead vehicle
- Cognitive load (N-back task) or Visual-manual load (SuRT task)
- 4 experimental conditions per one participant (manual, automated, automated with easy non-driving task, automated with difficult non-driving task)
- Measuring driver's visual behaviors
- Avoiding the pylon manually after the lead vehicle changes lane
- Measuring driver's operational behaviors



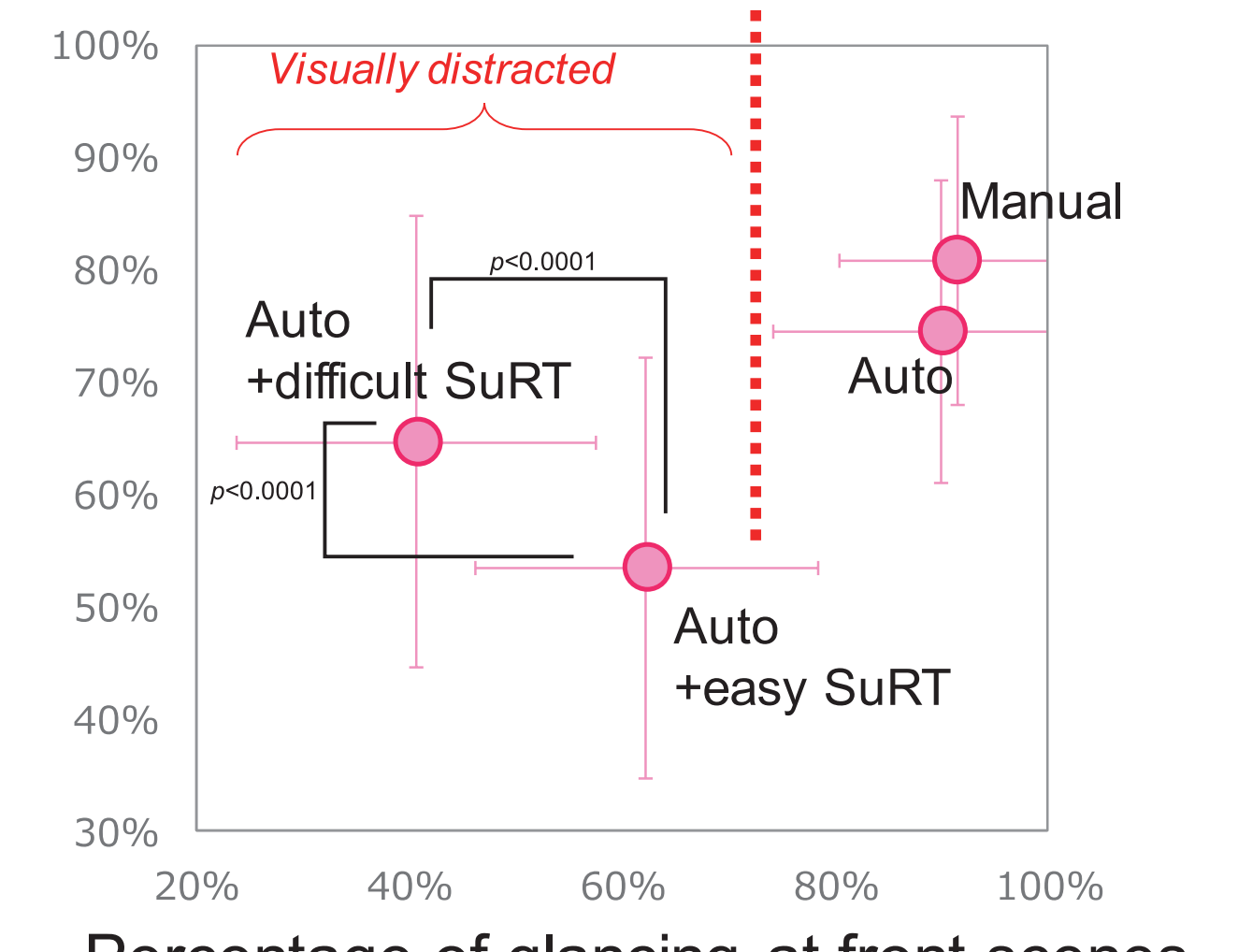
### Results of driver's conditions before Rtl

Percentage of frequency of saccades (5 to 16 degrees) in all saccades for 1 minute before Rtl



Cognitive load

Percentage of frequency of saccades (5 to 16 degrees) in all saccades for 1 minute before Rtl

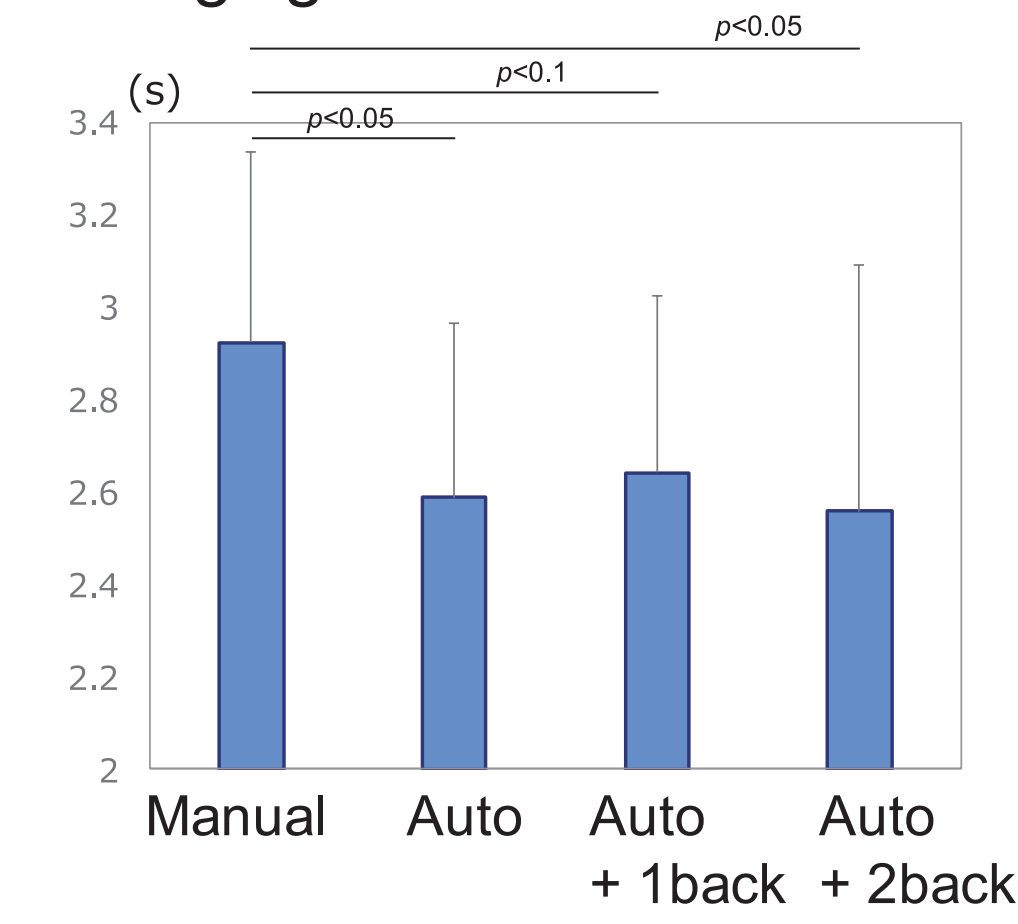


Percentage of glancing at front scenes

Visual-manual load

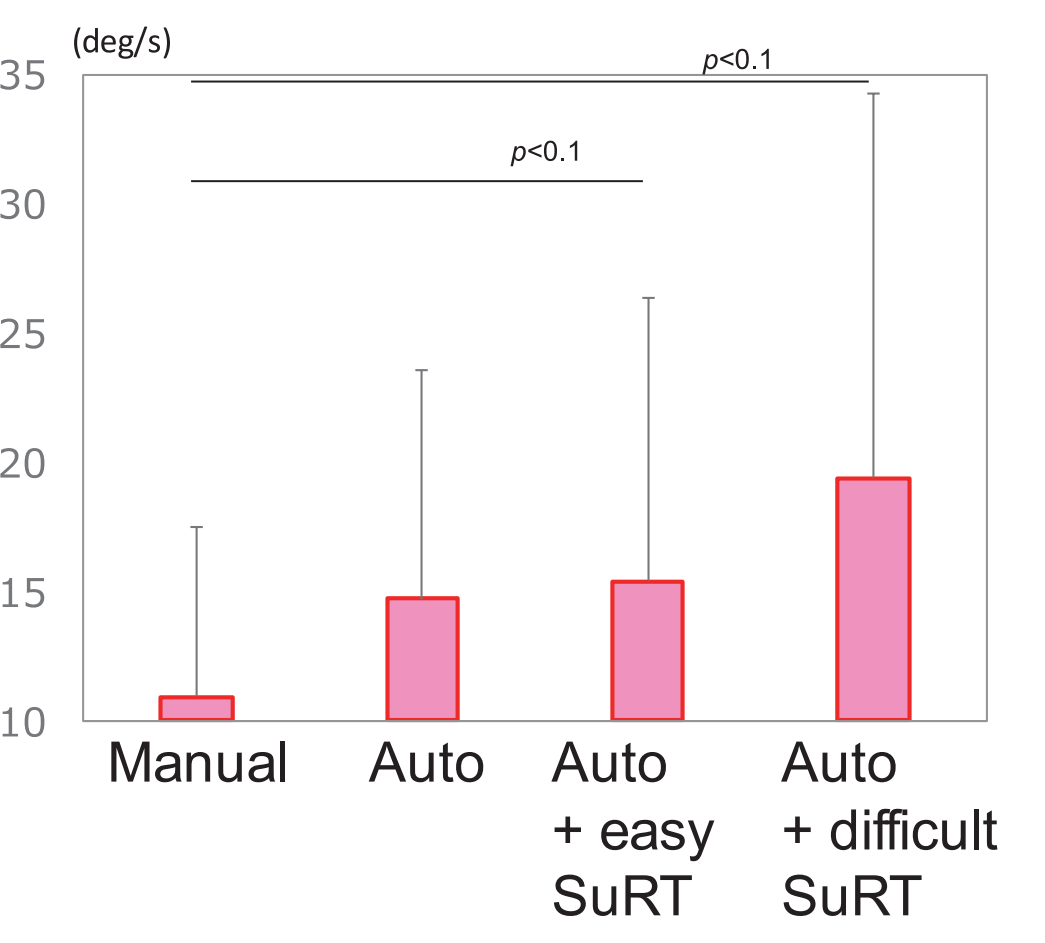
### Results of driving behaviors after Rtl

Time margin to the pylon when changing the lane



Cognitive load

Steering speed during the maximum steering angle



Visual-manual load

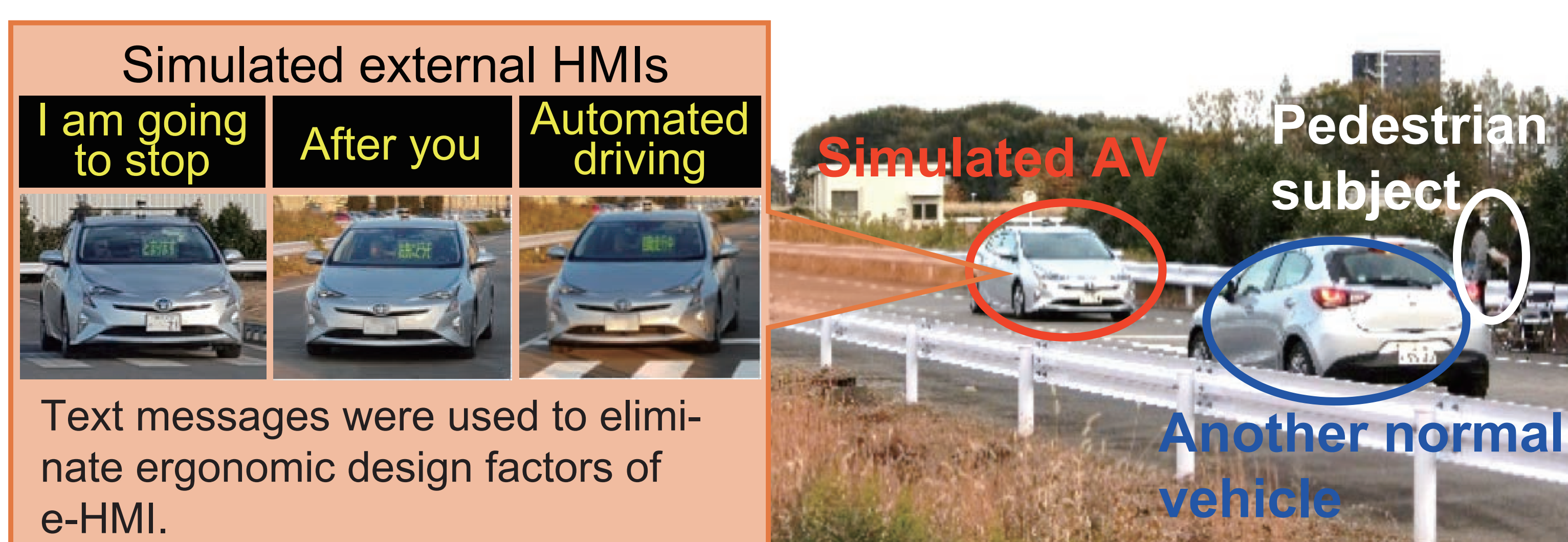
Findings obtained from the proving ground experiment are similar to those in the simulator study

## Task C

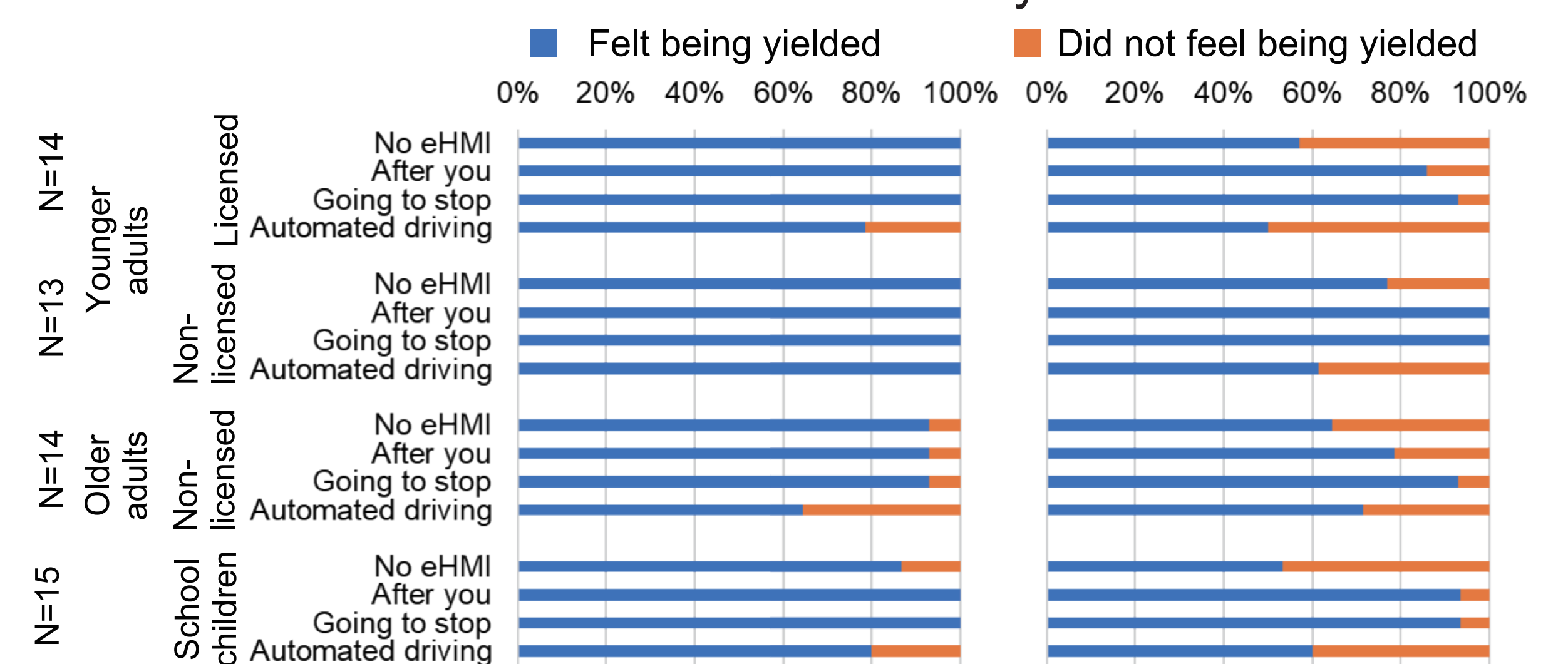
### Experiment on recommendations for on-road communication measures of AV

- Vehicle behavior is the primary communication cue to surrounding pedestrians.
- External HMI can be an additional cue to clarify AV's intention to yield when vehicle behavior is not clear enough.
- Different types of pedestrians responded to the external HMIs differently. The design of external HMI needs to be "Universal".
- Meaning for an external HMI signal needs to be selected carefully to magnify the positive effects.

An experiment in a closed track



Did the participants feel the approaching AV yielded to them? - Results for Efficiency -



Large deceleration: 25→10km/h Small deceleration: 25→15km/h