

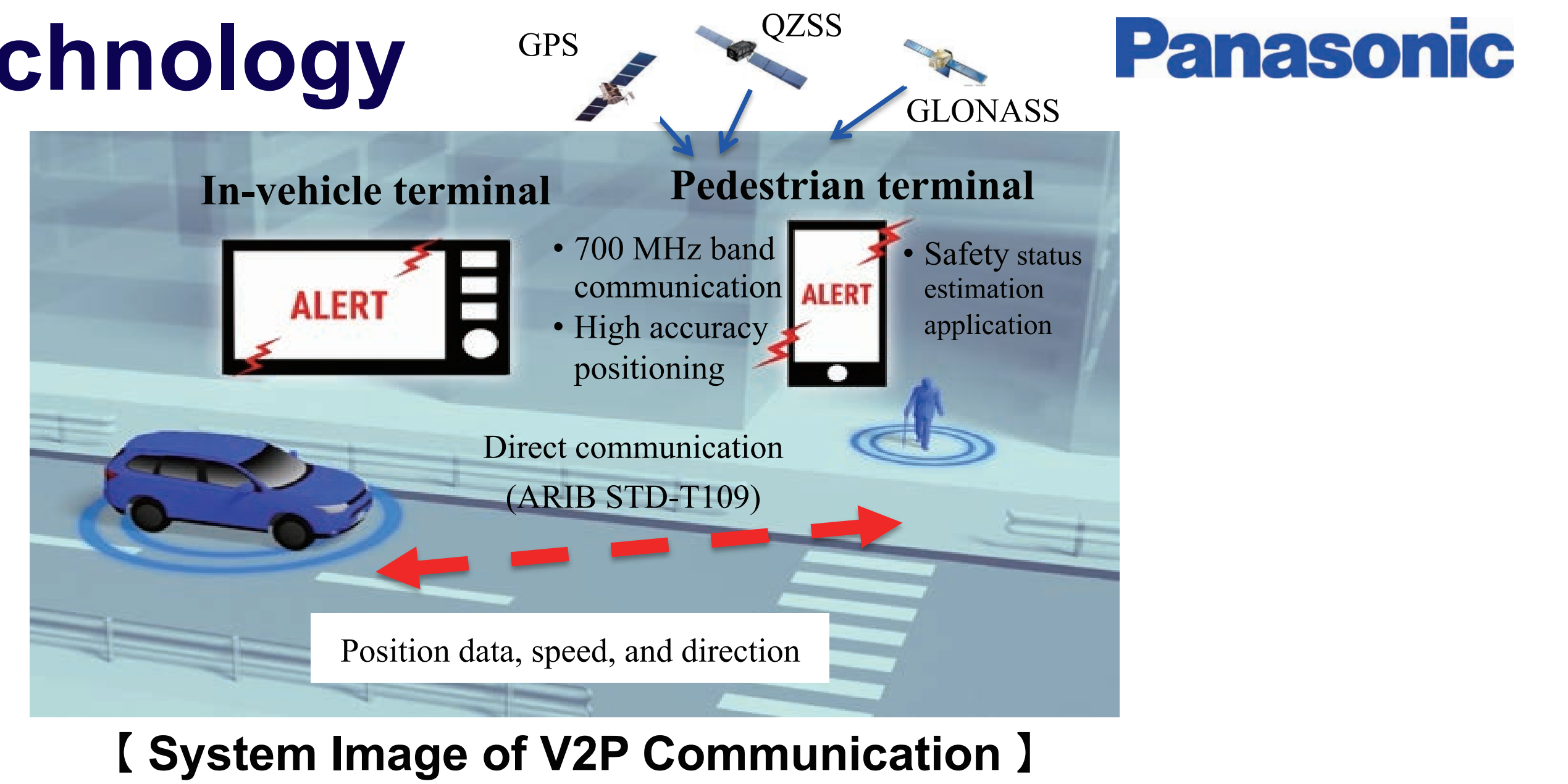
Impact Assessment Efforts to reduce pedestrian traffic accidents

Objective

Vehicle to Pedestrian(V2P) Communication Technology

Realization of a safety support system for pedestrians to reduce traffic fatalities

- Alert pedestrian or driver timely under potential dangerous situations
- Positional message exchange between terminals via direct communication



Research and Development

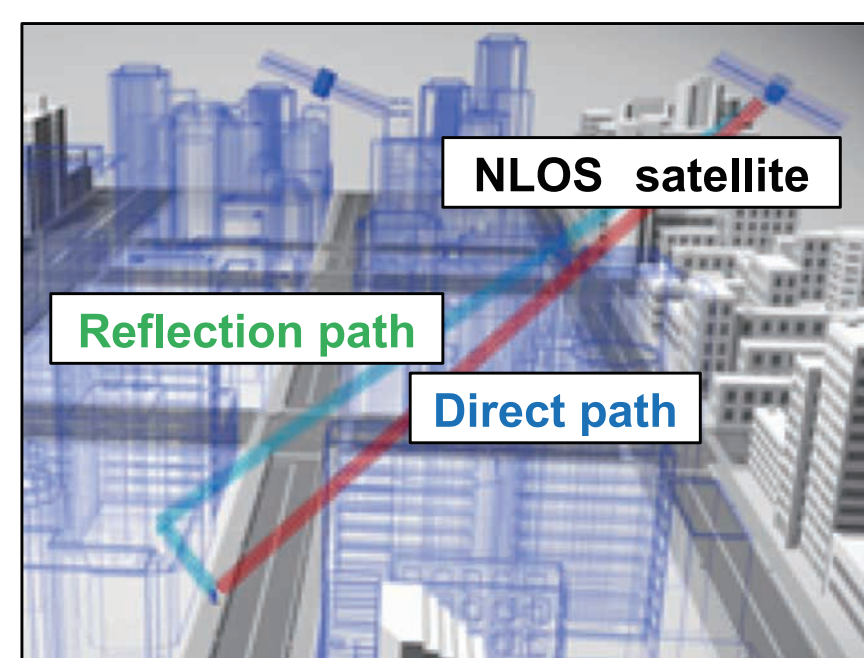
Realization of effective prototype terminal for pedestrian support

Pedestrian Positioning

Improvement in high-rise building areas

[Method]

Based on 3D map with height information of buildings, reflection path with respect to building walls being used for positioning.*1



*1: Technology and license supplied from the University of Tokyo
Source : Urban Pedestrian Navigation Using Smartphone-Based Dead Reckoning and 3D Map-Aided GNSS

[Evaluation results] target: horizontal error ≤3m

Obvious effect obtained →(3m level at Hitotsubashi)

	Shinjyuku	Hitotsubashi	Shinagawa	Odaiba
without 3D Map (GPS, GLONASS, QZSS, Galileo)	10.1	4.1	9.4	5.7
with 3D Map (3D: GPS, GLONASS, QZSS)	5.7	3.7	6.5	5.6

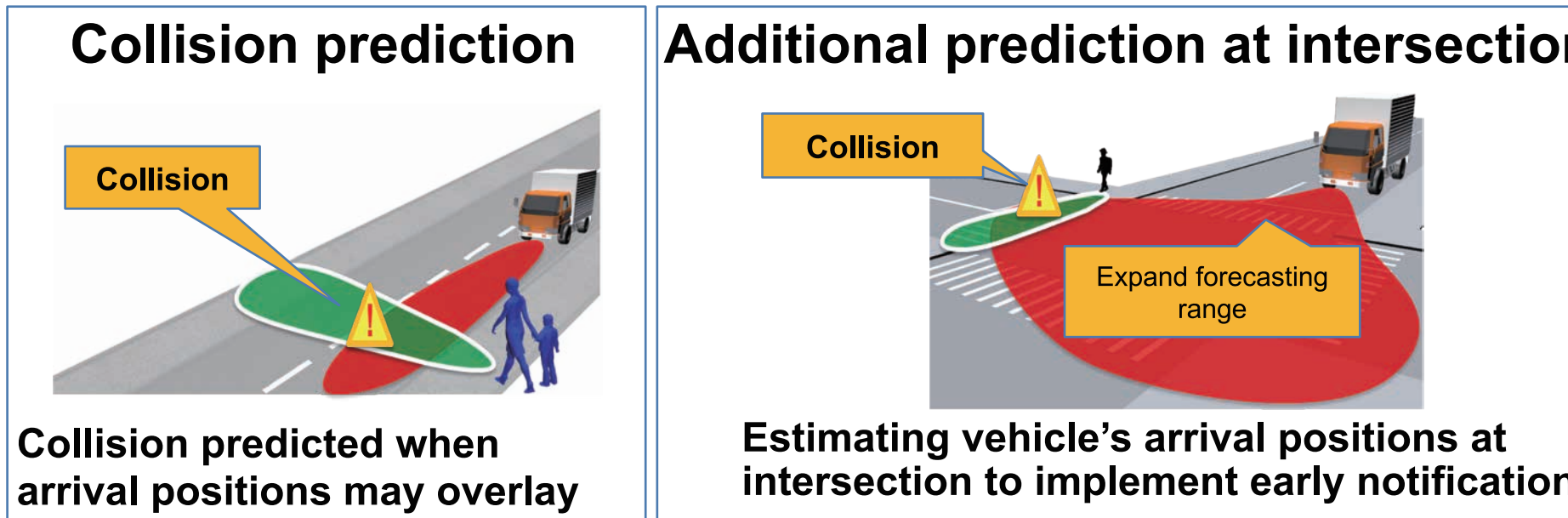
Cumulative frequency(68%) [m]

Safety Status Estimation

Alert timely under potentially dangerous situations

[Scenes Supported]

Collision prediction → notification ON



[Scenes Not Supported]

State prediction → notification OFF

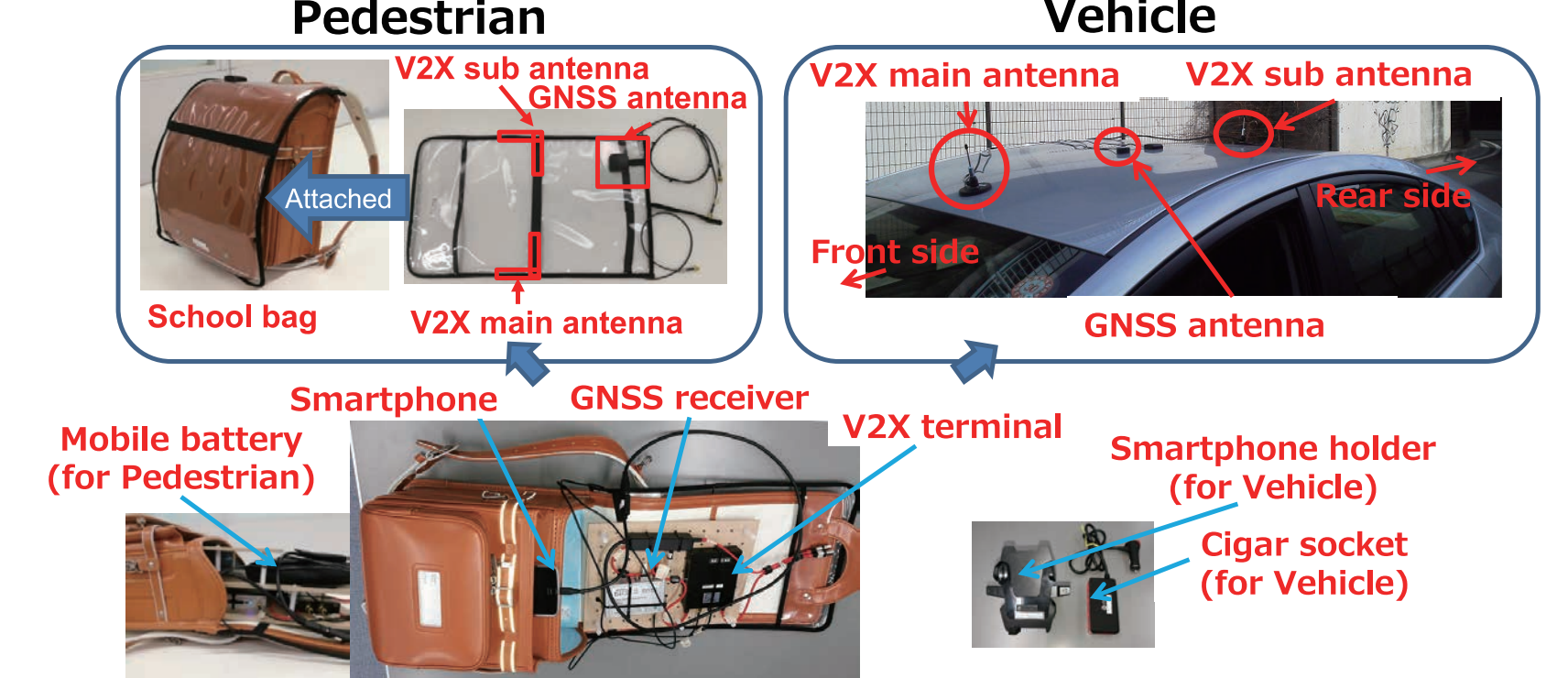
Scenes	Method
Inside vehicle	<ul style="list-style-type: none"> Moving Speed ≥ 20 km/h Satellite signal strength estimation Moving state estimation
Inside building	<ul style="list-style-type: none"> Satellite signal strength estimation Radio elevation angle estimation
At overpass	<ul style="list-style-type: none"> Map and position information Altitude estimation by embedded air pressure sensor
Walking in sidewalk	<ul style="list-style-type: none"> Sidewalk link map Walking direction estimation

Terminal Prototyping

Performance (portability, antenna) fulfilled for 2018 large-scale demonstration

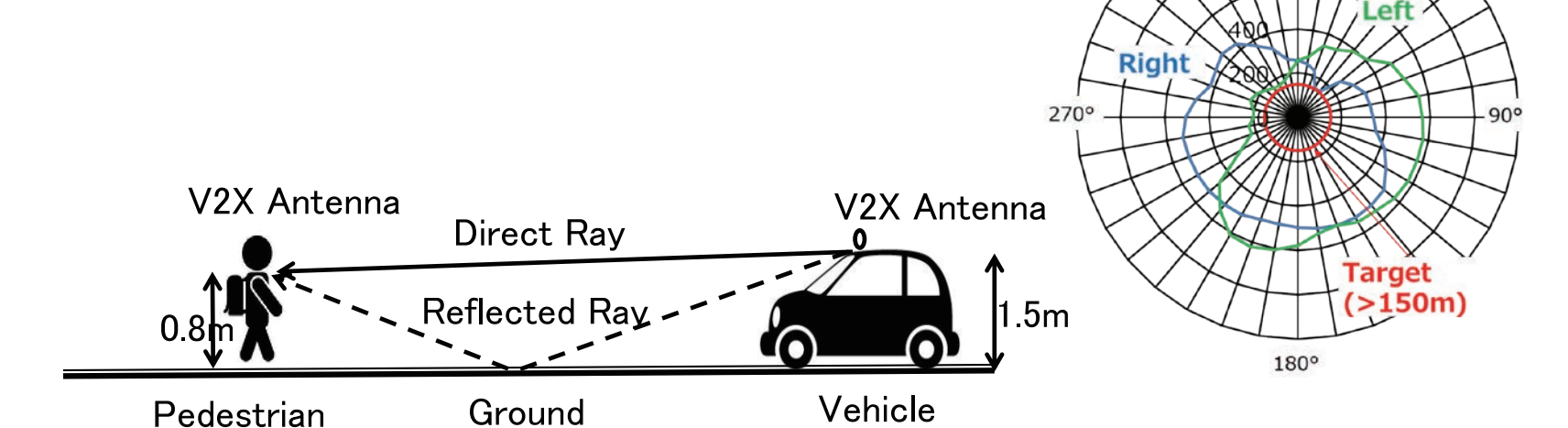
① Prototype Terminals:

All devices contained in a compact ruck sack with fine portability



② Communication distance:

V2P target distance of ≥150m verified



Large-scale Demonstration Experiment

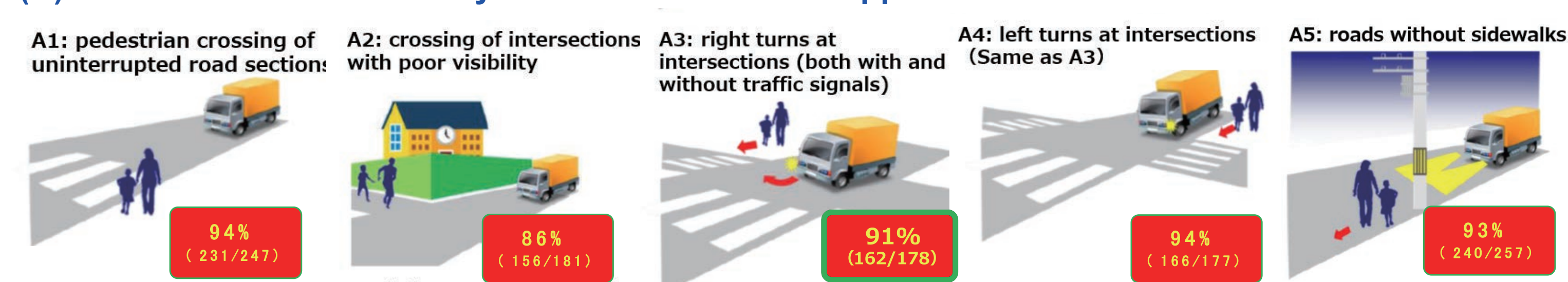
Verification of mutual attention function & Verification of effectiveness under the actual traffic environments

NIPPON KOEI

Verification of mutual attention function

Repeat verification of proper operation for scenes pedestrian assistance is necessary/unnecessary

(A) Rate that worked correctly in a situation where support is needed



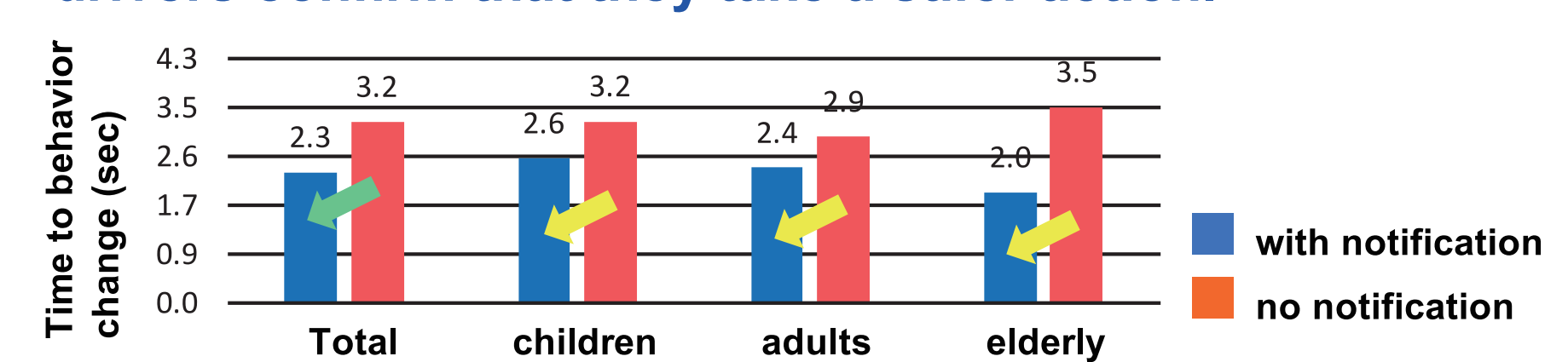
(B) Rate that worked incorrectly in a situation where support is unneeded



Verification of effectiveness under the actual traffic environments

Experiment with senior citizens, adults and children as monitors in the Tokyo Odaiba area

As a result of using V2P terminal, pedestrians and drivers confirm that they take a safer action.



Many people are expecting service of V2P

