



PEGASUS Method for Assessment of Highly Automated Driving Function



Supported by:



on the basis of a decision
by the German Bundestag

Project for the establishment of generally accepted quality criteria, tools and methods as well as scenarios and situations for the release of HAD functions.

42 Months Term

January 1st, 2016 – June 30th, 2019

17 German Partners

- OEM: Audi, BMW, Daimler, Opel, Volkswagen
- Tier 1: Bosch, Continental
- Test Lab: TÜV SÜD
- SMB: fka, iMAR, IPG, QTronic, TraceTronic, VIREs
- Scientific institutes: DLR, TU Darmstadt

12 Subcontracts

- i.a. IFR, ika, OFFIS

Project Volume

- approx. 34,5 Mio. EUR
- Subsidies: 16,3 Mio. EUR

Personnel Deployment

- approx. 1.791 man-month or 149 man-years

Resulting Starting Position – Automated Driving



Together with electric driving, automated driving is tomorrow's subject matter.

Basic functionality is technologically given
Has been demonstrated in various projects

High standards regarding quality and performance of the automated vehicle
→ Measures that product needs to meet

Existing measures for testing and release are insufficient, too cost-intensive and too complex

→ Consequently, the introduction of highly automated driving features today can only be achieved with great expenditure.

Major Questions of the Project

What level of performance is expected of an automated vehicle?
How can we verify that it achieves the desired performance consistently?



Scenario Analysis & Quality Measures

- What human capacity does the application require?
- What about technical capacity?
- Is it sufficiently accepted?
- Which criteria and measures can be deducted from it?



Implementation Process

- Which tools, methods and processes are necessary?



Testing

- How can completeness of relevant test runs be ensured?
- What do the criteria and measures for these test runs look like?
- What can be tested in labs or in simulation? What must be tested on proving grounds, what must be tested on the road?



Reflection of Results & Embedding

- Is the concept sustainable?
- How does the process of embedding work?

*PEGASUS approach
to answer the question*

**How safe is safe enough and
how can we verify that it achieves the
desired performance consistently?**

is:

**Method for Assessment of
Highly Automated Driving Function**

Argumentation

Evidence

Safety
argumentation

Safety
evidence

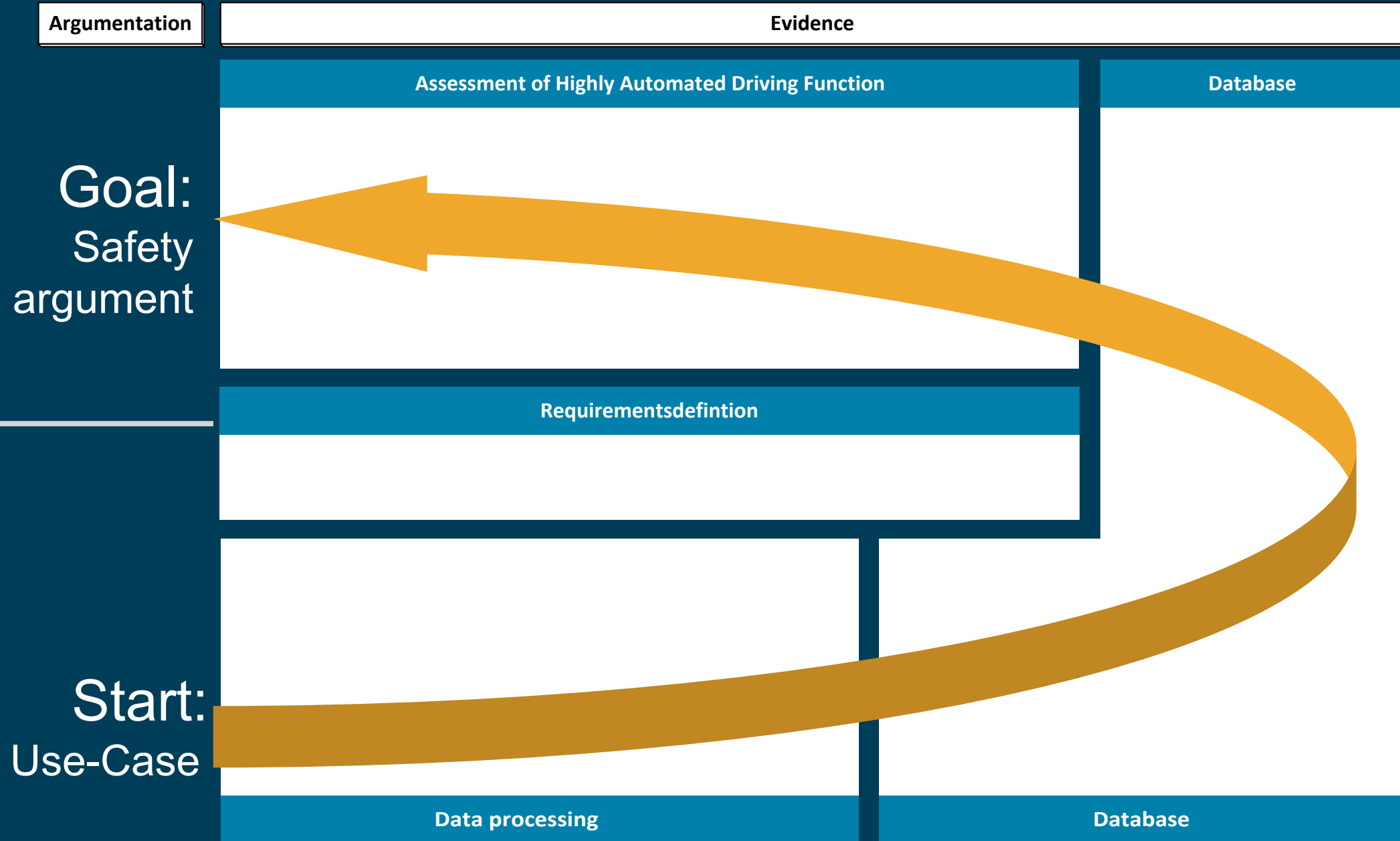
Argumentation

Evidence

Goal:
Safety
argument

Start:
Use-Case





Argumentation

Evidence

Assessment of Highly Automated Driving Function

Database

Requirementsdefinition

Use Case,
Knowledge,
Data

Data processing

Database

Use Case

- Safeguarding of Level 3 (Highly Automated Driving) function
- Based on an application-oriented example, highway chauffeur
 - Basic function:
 - ✓ Highways or highway-like roads incl. road markings
 - ✓ Speed 0 - 130 km/h
 - ✓ Automated following in stop & go traffic jams
 - ✓ Automated lane changing
 - ✓ Automated emergency braking and collision avoidance
 - ✗ Construction sites
 - ✗ Automated exiting off the highway
 - ✗ Extreme weather conditions



Argumentation

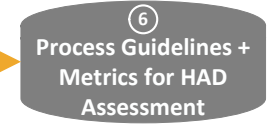
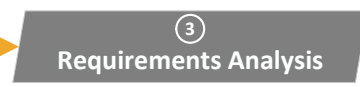
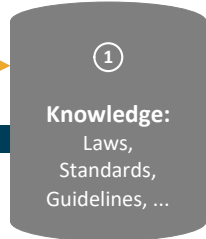
Evidence

Assessment of Highly Automated Driving Function

Database

Requirementsdefinition

**Use Case,
Knowledge,
Data**

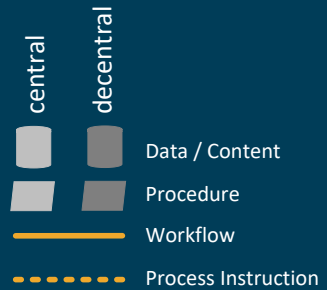


Source of Information

Evaluation & Conversion

Data processing

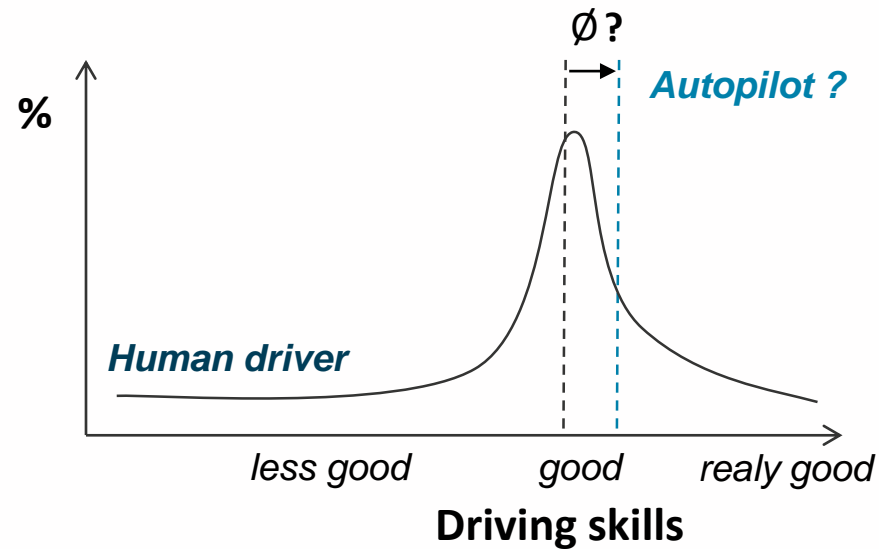
Database



Social acceptance

How good is good enough?

- Which functional performance does a highly automated driving function need to reach a social acceptance?

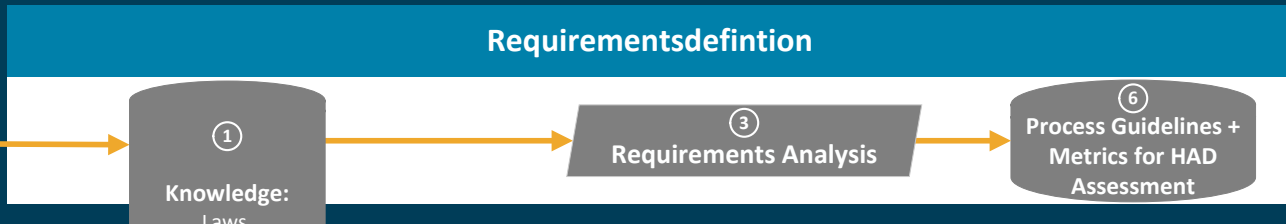


Argumentation

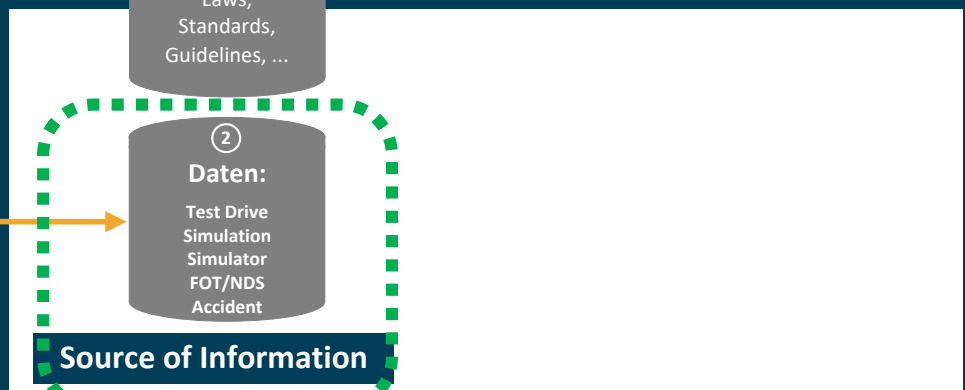
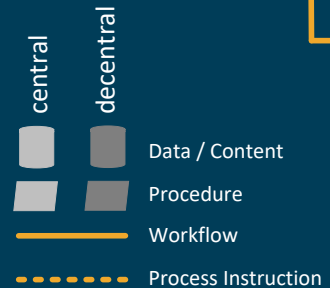
Evidence

Assessment of Highly Automated Driving Function

Database



Use Case,
Knowledge,
Data



Data processing

Database

Input data

NDS / FOT



Simulation



Simulator



Real world



Argumentation

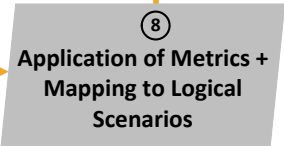
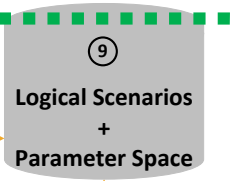
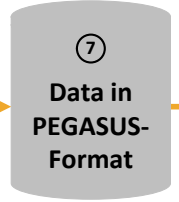
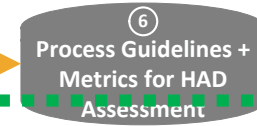
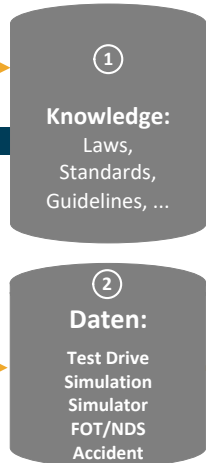
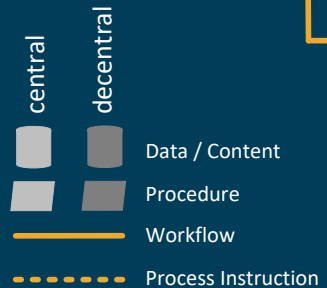
Evidence

Assessment of Highly Automated Driving Function

Database

Requirementsdefinition

Use Case,
Knowledge,
Data



Source of Information

Evaluation & Conversion

Scenarios

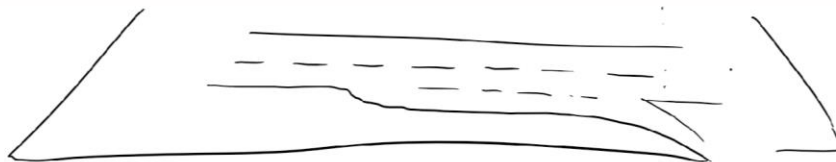
Data processing

Database

Scenarios and possibilities for description

Layer model

①



Argumentation

Evidence

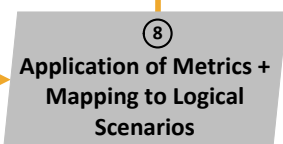
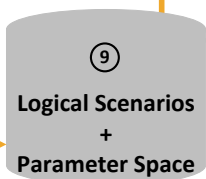
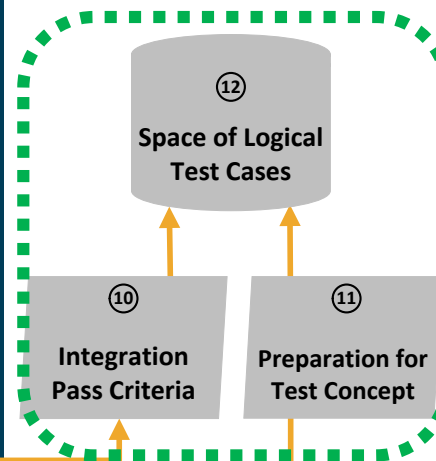
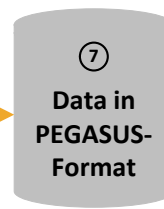
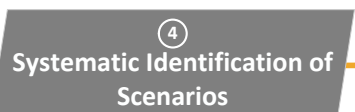
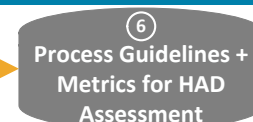
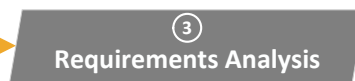
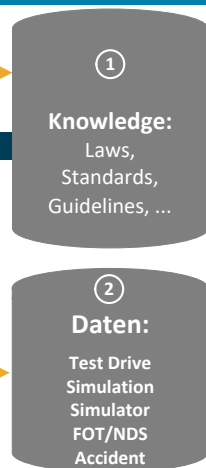
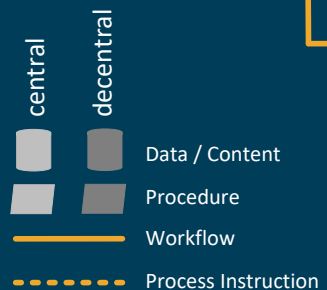
Assessment of Highly Automated Driving Function

Database

Processing

Requirementsdefinition

**Use Case,
Knowledge,
Data**



Source of Information

Evaluation & Conversion

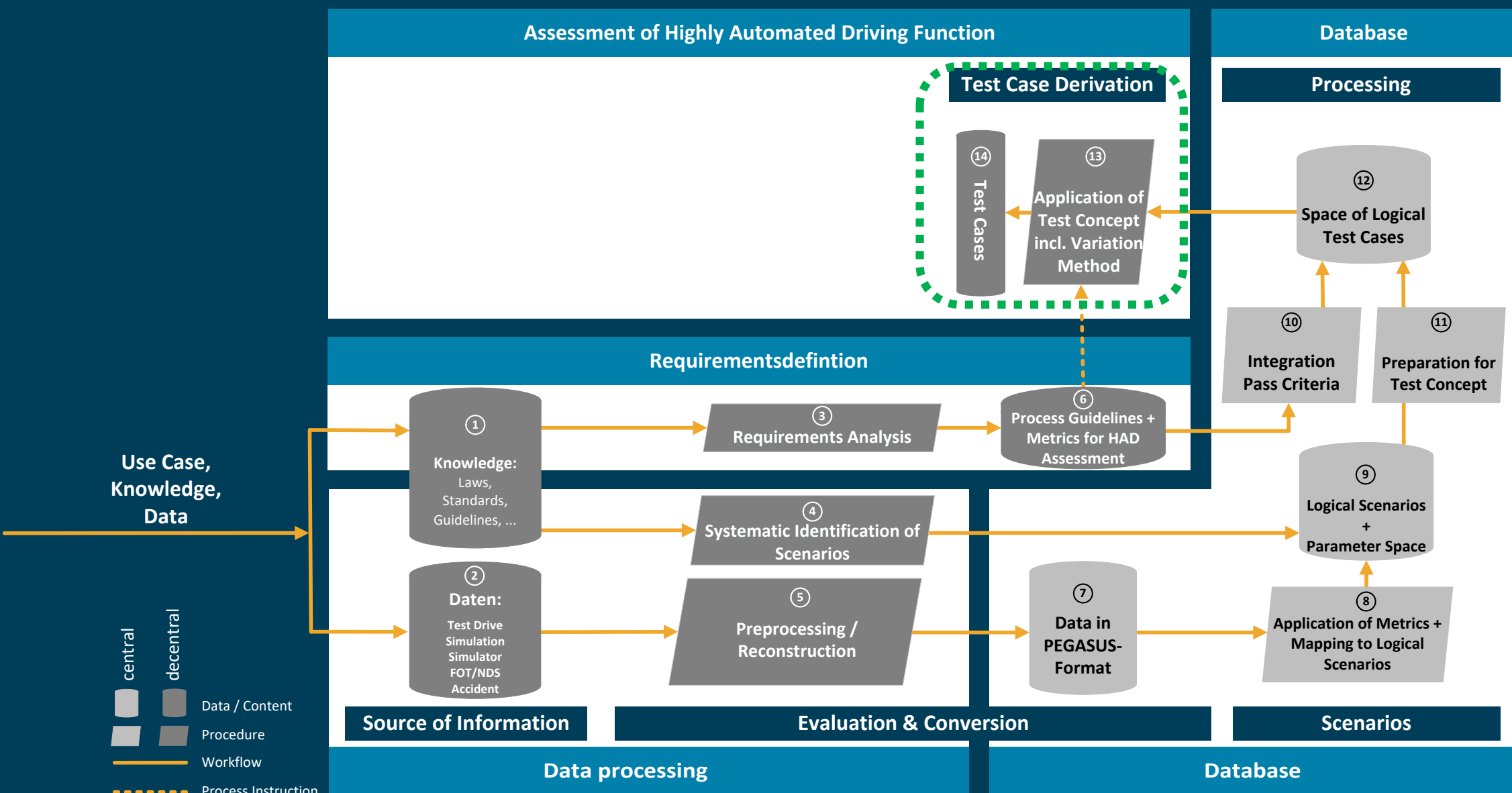
Scenarios

Data processing

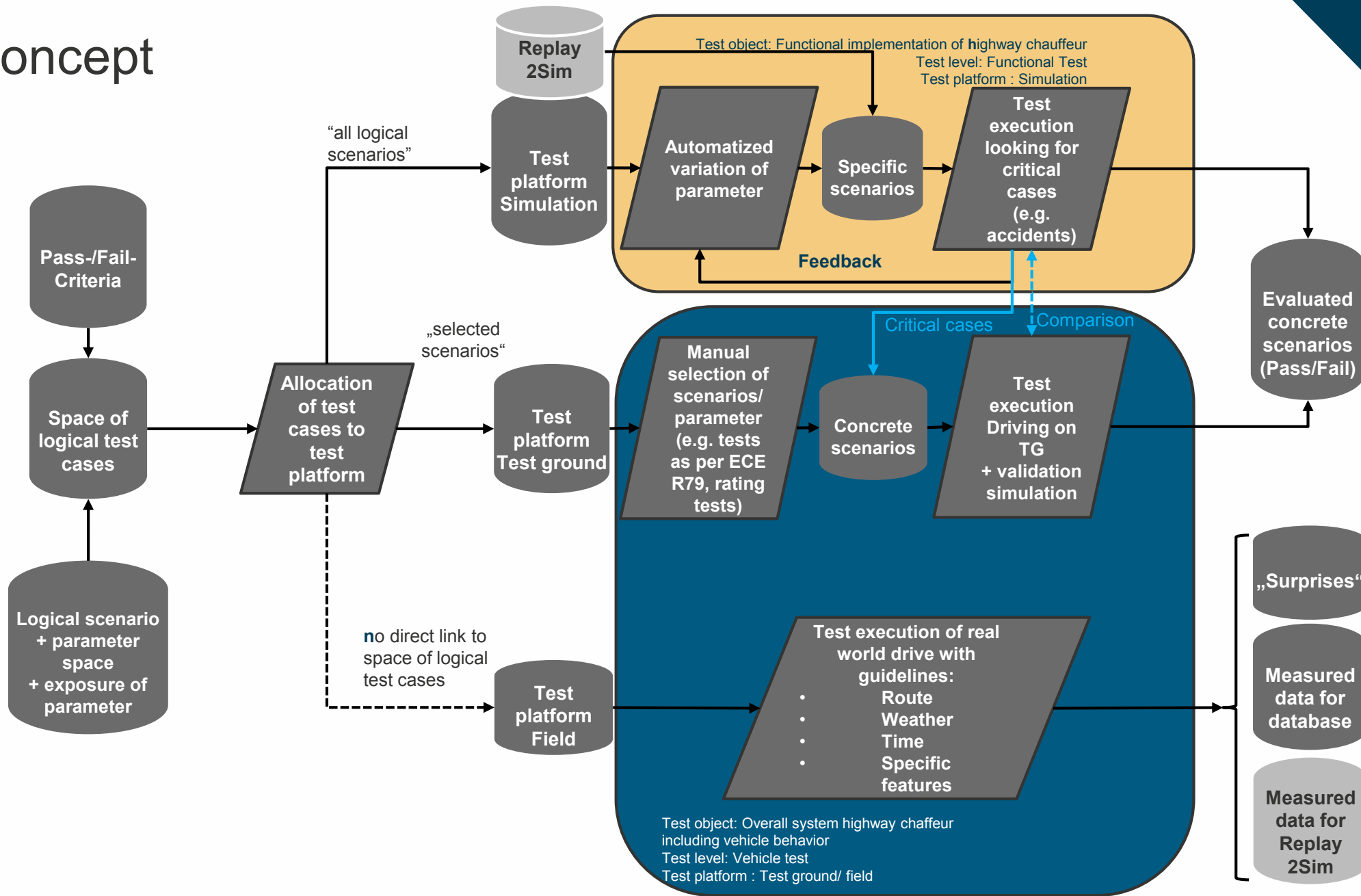
Database

Argumentation

Evidence

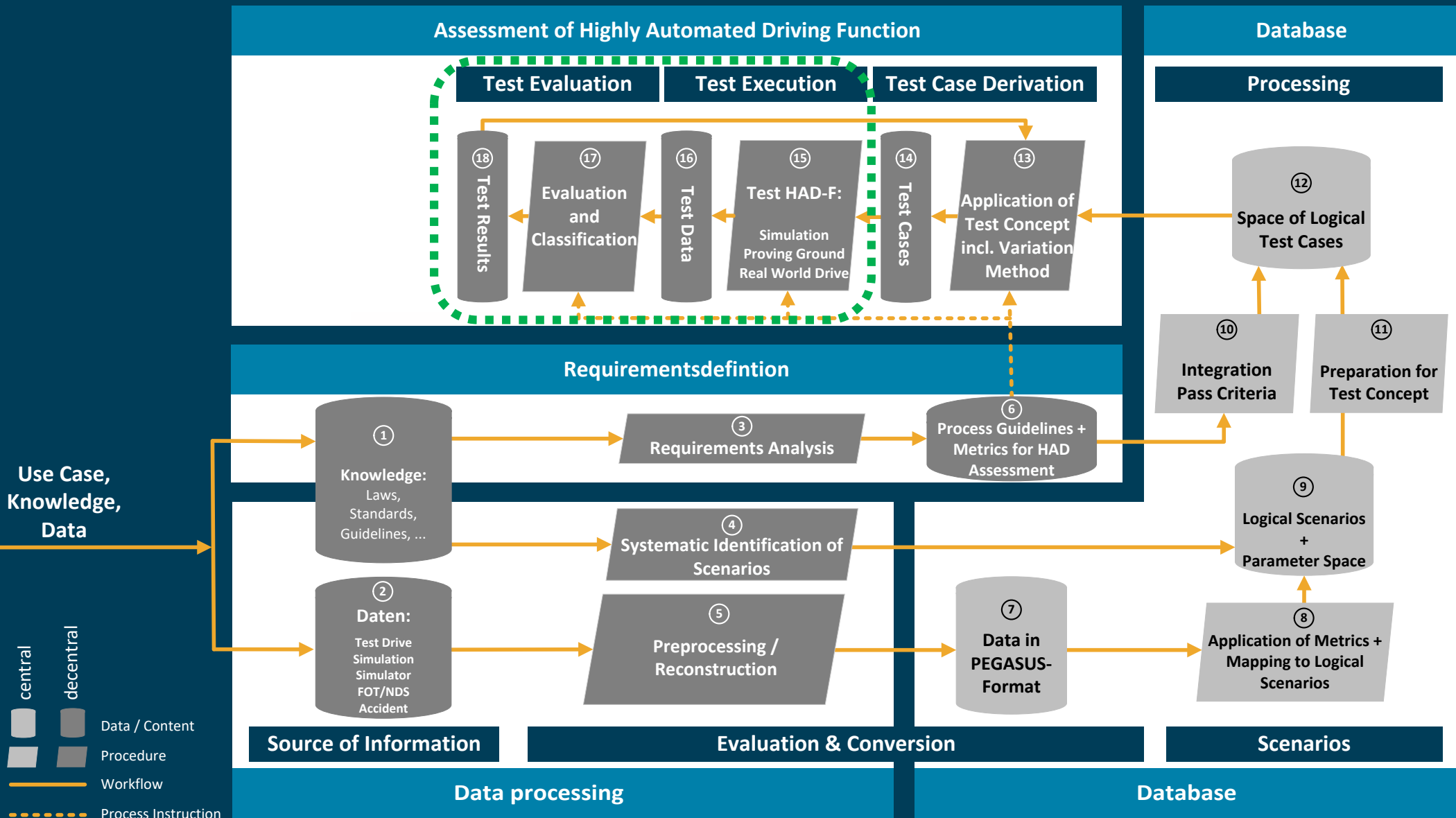


Test concept

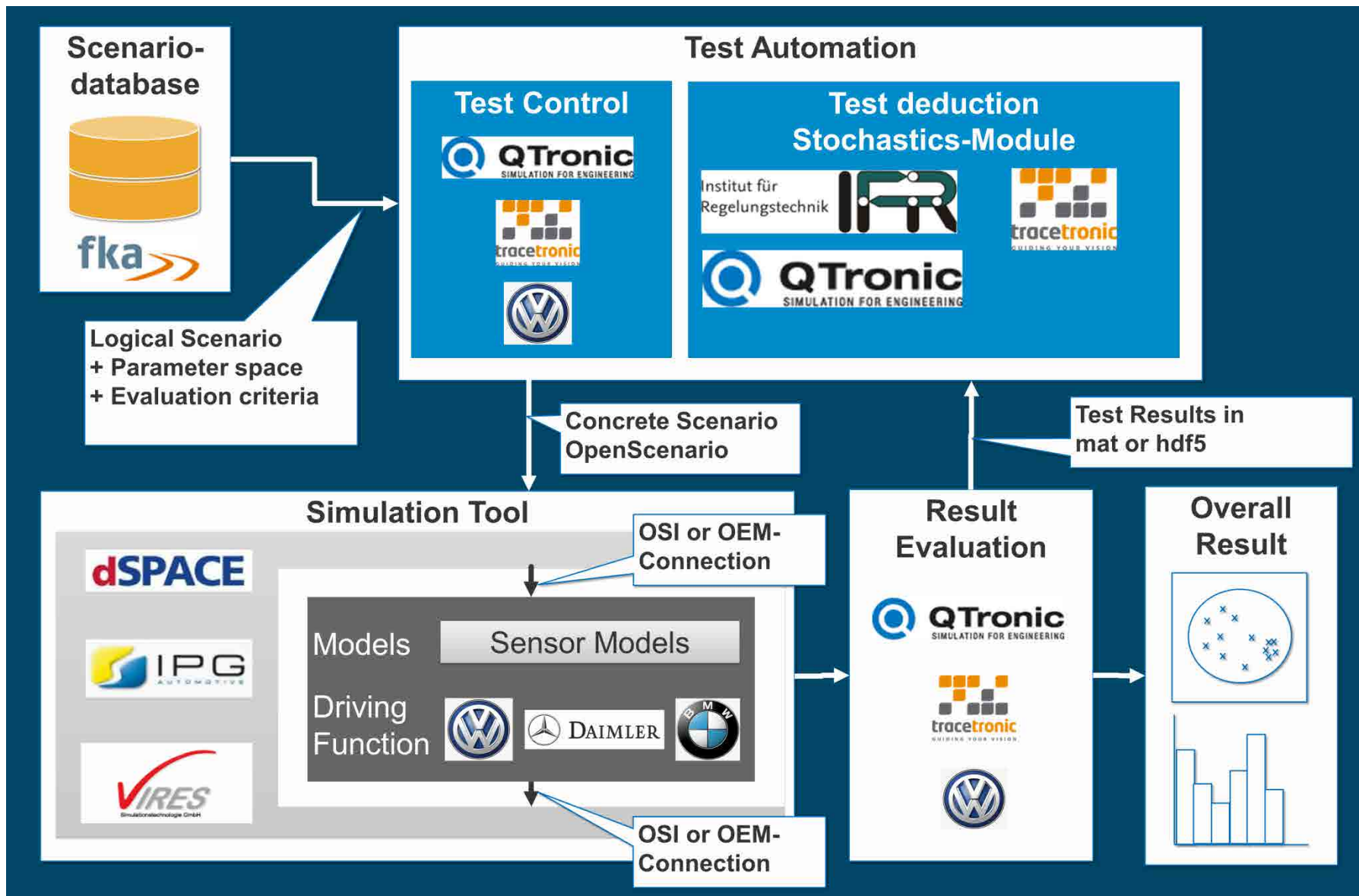


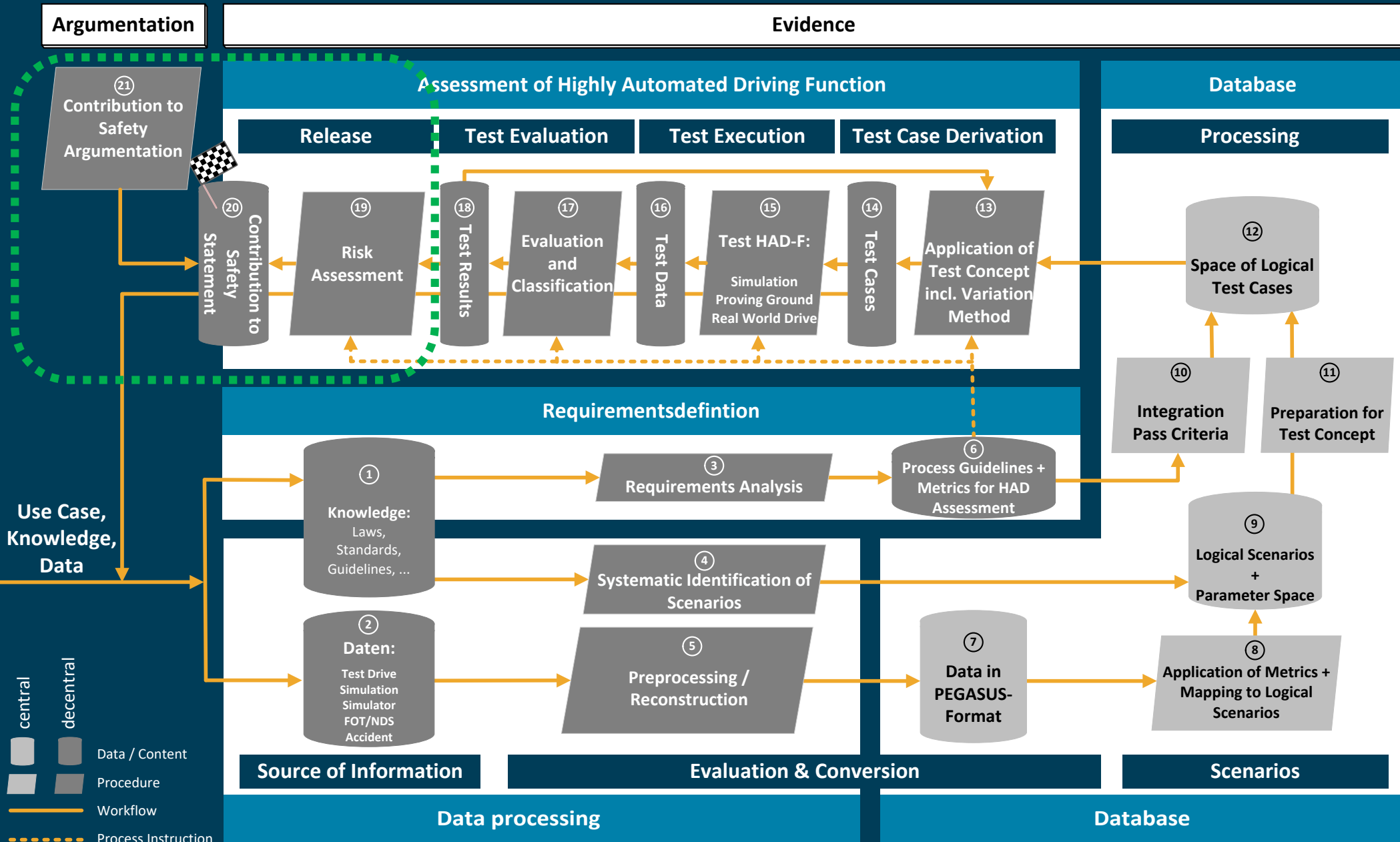
Argumentation

Evidence



Example: Software in the Loop







Contact:

Prof. Dr.-Ing. Thomas Form

Head of Vehicle Technology and Mobility Experience,

Group Research

Volkswagen AG

Thomas.Form@volkswagen.de

www.pegasusprojekt.de

