

# SIP-adus Workshop 2018

## Human Factors

“What have we found? What’s the next?”

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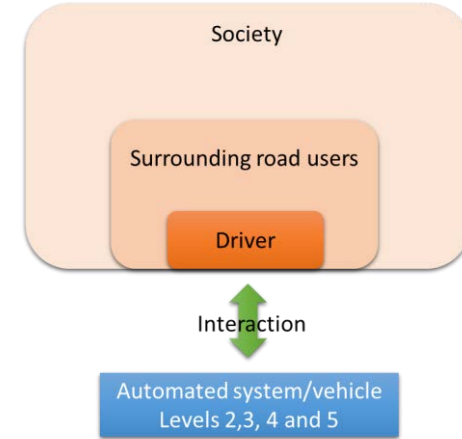


# **What have we found?**

**SIP-adus Human Factors Research Project  
FY2016-FY2018**

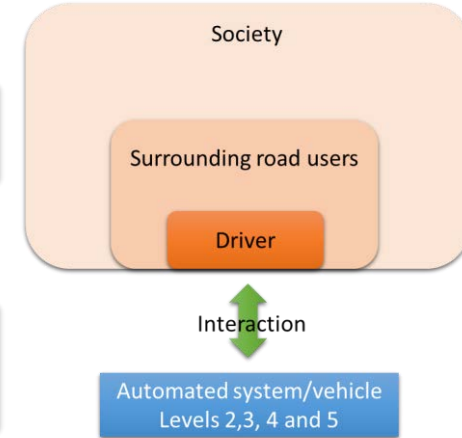
# Extraction of Potential Human Factor problems

Interactions and related issues		Level 1	Level 2	Level 3	Level 4	Level 5
Vehicle - Driver	System use					
	A-1	Understanding system functions	How to avoid over trust, over reliance, misunderstanding of functional limitations?			
	A-2	Understanding system states	How to avoid misunderstandings of system's current state and future actions.			
	A-3	Understanding system operations	How to improve usability of complicated HMI (switches)?			
	A-4	Understanding system behavior	How to avoid worries and discomfort for system's driving manner differing from individual driver's manner?			
	Driver's state					
	B-1	Driver state with automation		How to maintain required driver's state with automation?		
	B-2	Transition from automation to fully manual		How to avoid degraded response action of the driver unready to take over the vehicle control?		
	B-3	User benefits of automation		How to overcome the negative benefit of fight against drowsiness /boredom?	How to overcome the negative benefit of interruption of non-driving related activities?	How to compensate for the decreased value of homogenized brands and car performance?
	Vehicle - Surrounding road users	C-1	Communication between the automated vehicles and surrounding drivers		How to enable automated vehicles to communicate with surrounding drivers in intersections, merging, lane change and others?	
C-2		Communication between the automated vehicle and surrounding vulnerable road users		How to enable automated vehicles to communicate with pedestrians standing by a cross-walk, pedestrians in parking, in shared space and in other situations?		
C-3		Mediation between formal rules and traffic efficiency		How to mediate conflicts between yielding and priority, traffic speed and speed limit regulation, and others?		
Vehicle - Society	D-1	Social value and acceptance of the automated vehicles		How to design functional deployment over time to raise social acceptance?		
	D-2	Liability		How to define liability for crashes considering limitation of human ability?		
	D-3	Licensing		Does licensing need to be modified?		



# Extraction of Potential Human Factor problems

Interactions and related issues		Level 1	Level 2	Level 3	Level 4	Level 5	
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	A-1	Understanding system functions	How to avoid over trust, over reliance, misunderstanding of functional limitations?			<b>Task A</b>	
	A-2	Understanding system states	How to avoid misunderstandings of system's current state and future actions.				
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	Driver's state						
	B-1	Driver state with automation	How to maintain required driver's state with automation?		<b>Task B</b>		
	B-2	Transition from automation to fully manual	How to avoid degraded response action of the driver unready to take over the vehicle control?				
	B-3	User benefits of automation	How to overcome the negative benefit of fight against drowsiness /boredom?	How to overcome the negative benefit of interruption of non-driving related activities?			
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# Summary of on-going SIP-adus HF research project

**Task A** investigates effects of system information (knowledge and dynamic state) on drivers' takeover performance for Levels 2 &3 (conducted at U of Tsukuba).

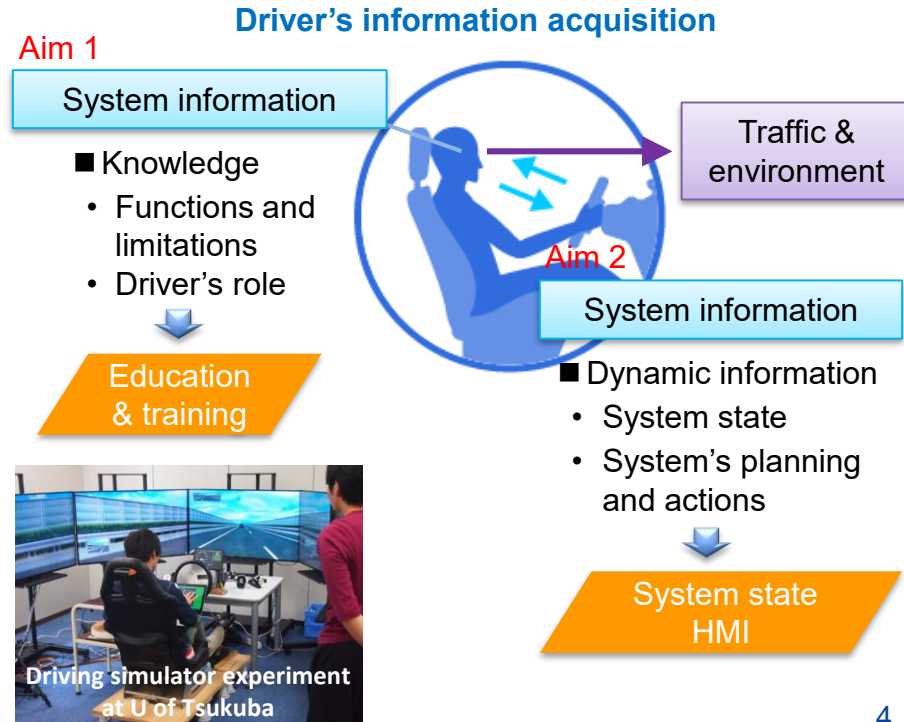
## Findings

### ■ Aim 1: Knowledge

- Knowledge required for successful takeover was clarified.
- Experiencing takeover situations improved performance of successive takeovers.

### ■ Aim 2: Dynamic information

- Some information of dynamic state of the system was found to be effective to improve takeover performance.
- Fundamental requirements for HMIs to display the dynamic information of the system were clarified.



# Summary of on-going SIP-adus HF research project

**Task B** investigates effects of driver state (readiness) on his/her takeover performance for Levels 2 & 3 and extracts metrics of readiness for driver monitoring (conducted at AIST).

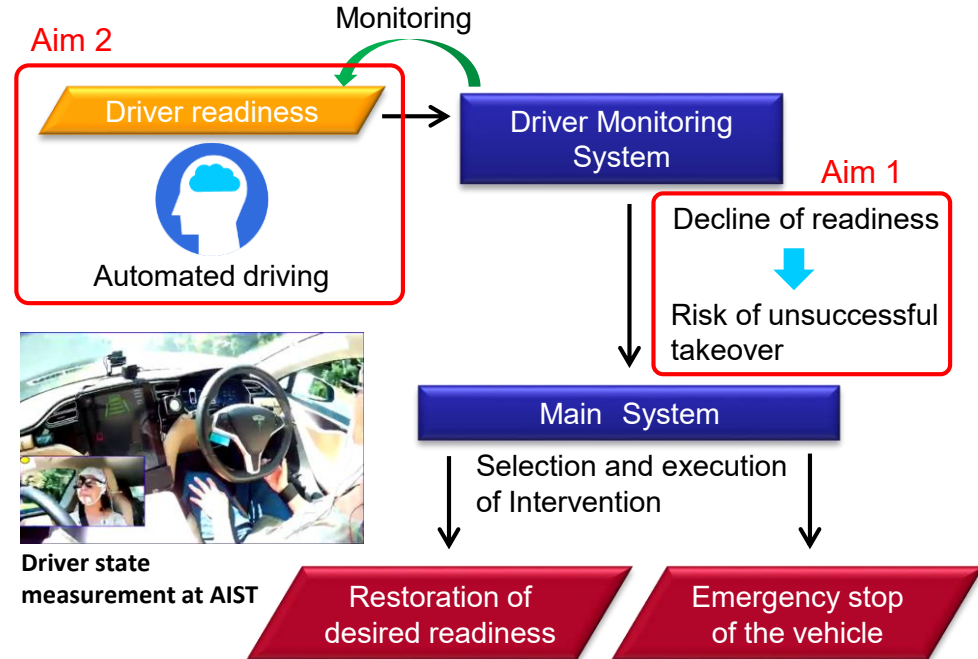
## Findings

### ■ Aim 1: Effects of driver state on takeover performance

- Low arousal, cognitively loaded and visually loaded state of the driver degraded driver's takeover performance in different ways.

### ■ Aim 2: Metrics of readiness

- Frequency of saccadic movements of the eyes, blinking frequency, percent time of forward looking, and Perclos were extracted as metrics of readiness for driver monitoring.



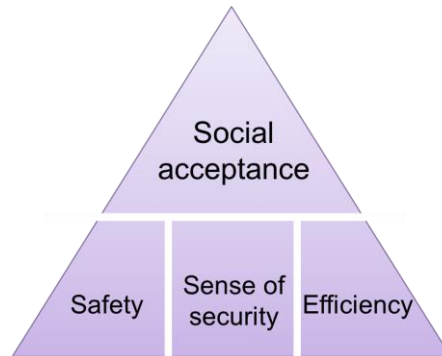
# Summary of on-going SIP-adus HF research project

**Task C** investigates effective ways to functionalize the automated vehicle to communicate surrounding road users for Levels 2 & above (conducted at Keio U).

## Findings

### ■ Aim 1: Current on-road communication

- Vehicle behavior was found to be the primary communication cue when yielding to other road users; the most frequent case.
- Benefits of on-road communication was defined as safety, sense of security, efficiency and social acceptance.



### ■ Aim 2: Considerations/recommendations for external communication of AV

- External HMI was found to be an additional cue and effective when deceleration was small.
- On-road communication was influenced by attributes of road users and social norms. Universal design and standardization of external HMI need to be considered.
- It was observed that some external HMI also induced unsafe behavior of some pedestrians. (further investigation is on-going).

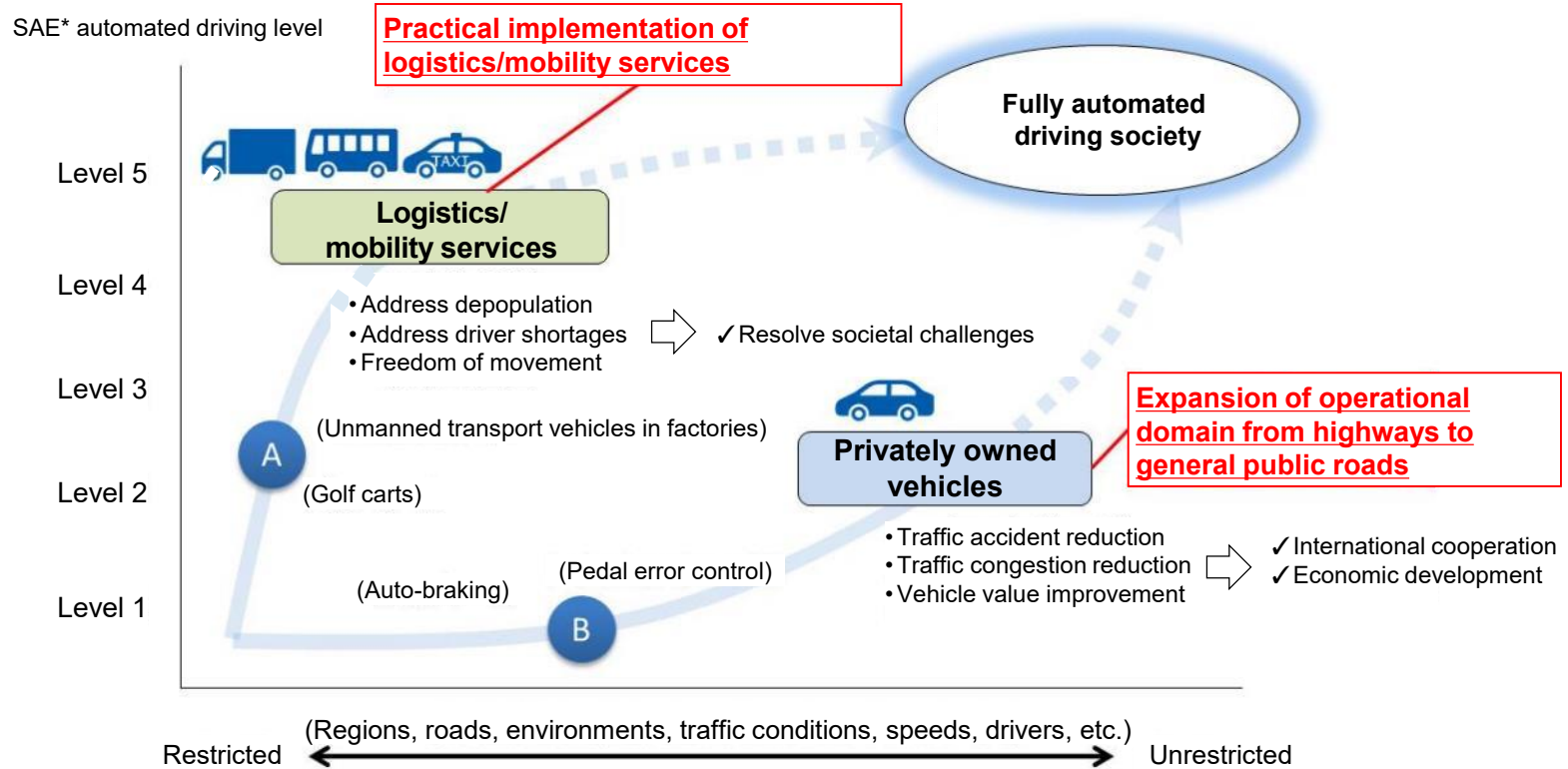




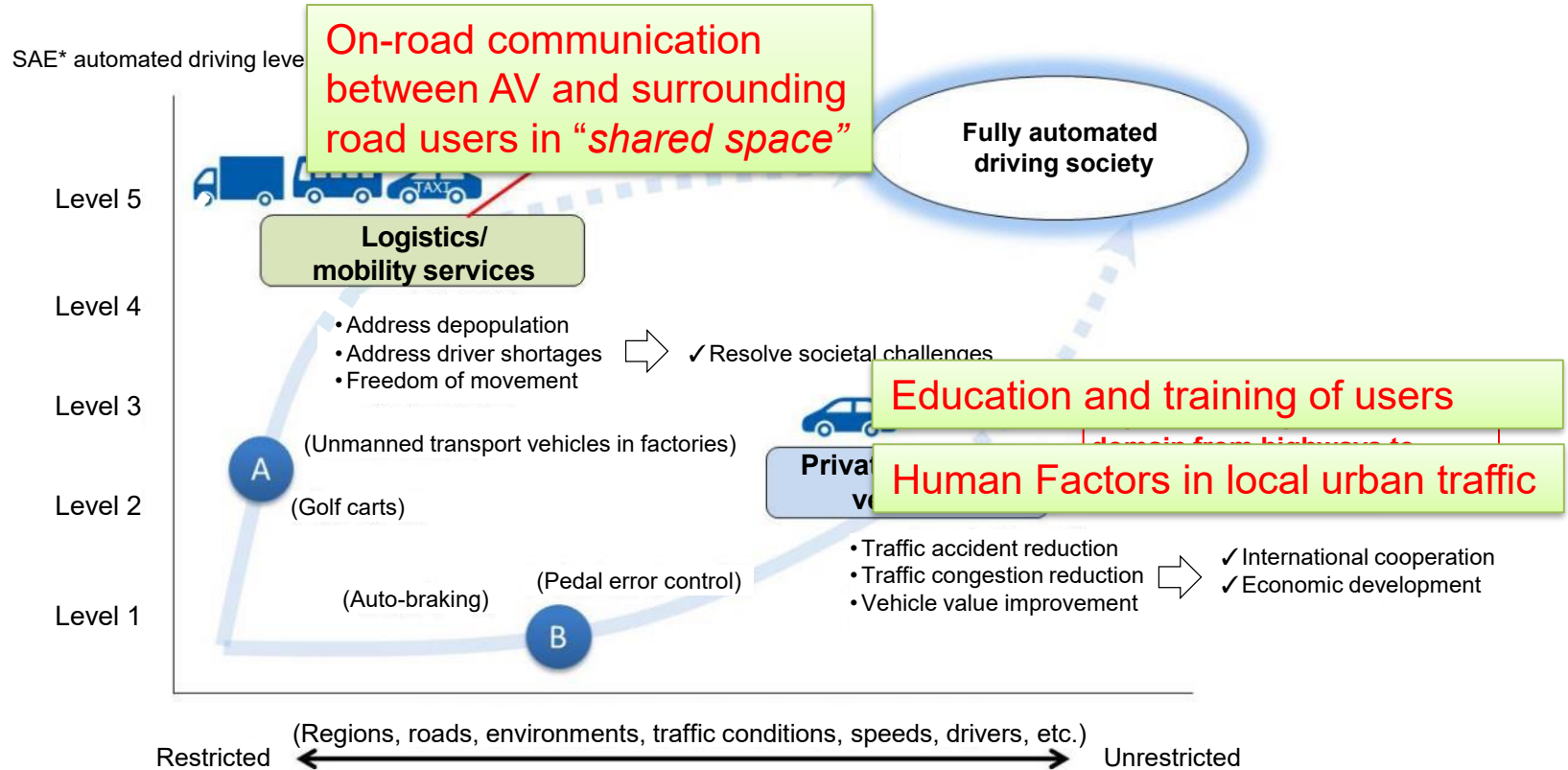
**What's the next?**



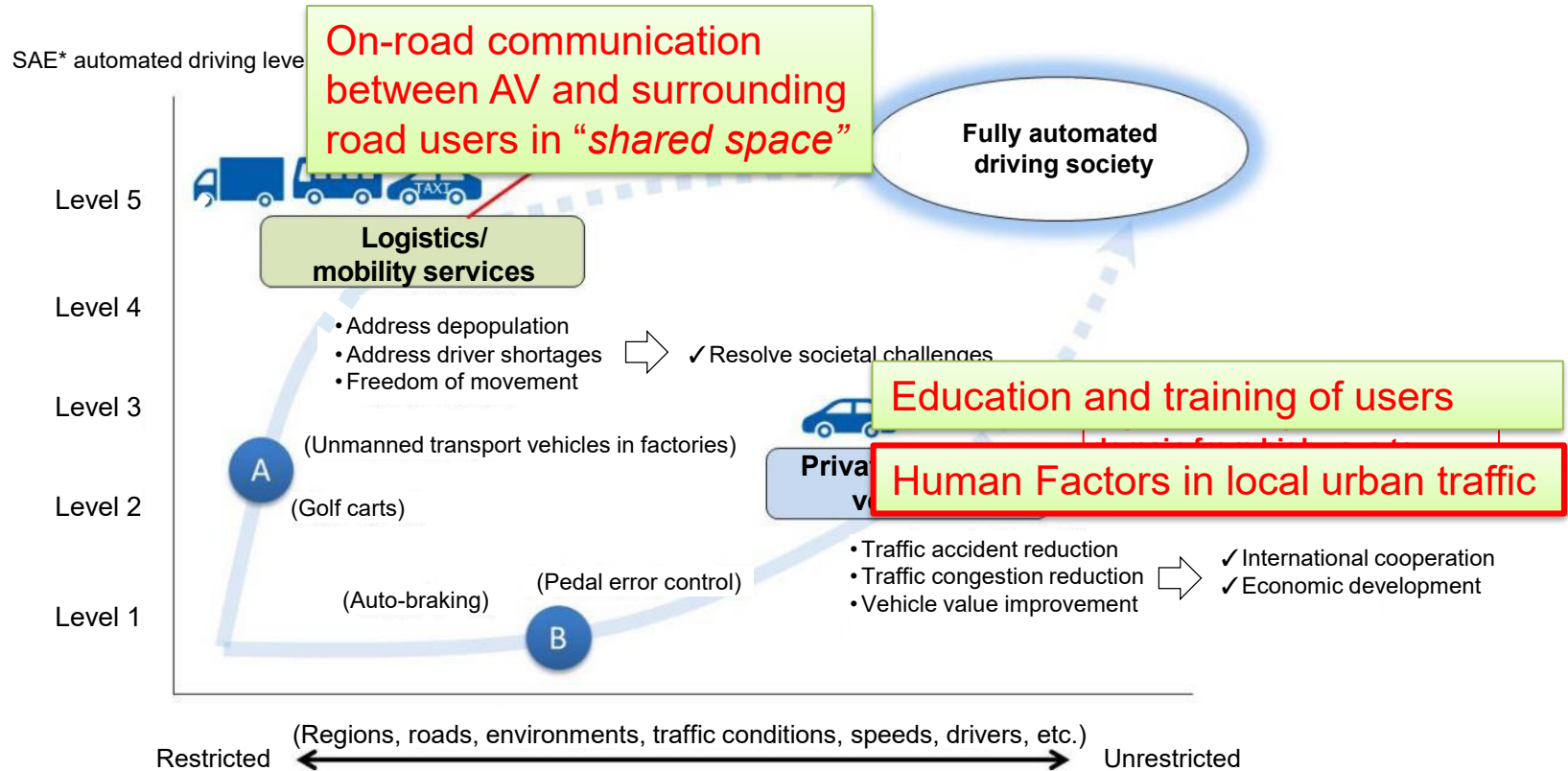
# SIP Phase II Roadmap



# Challenges on the SIP Phase II Roadmap

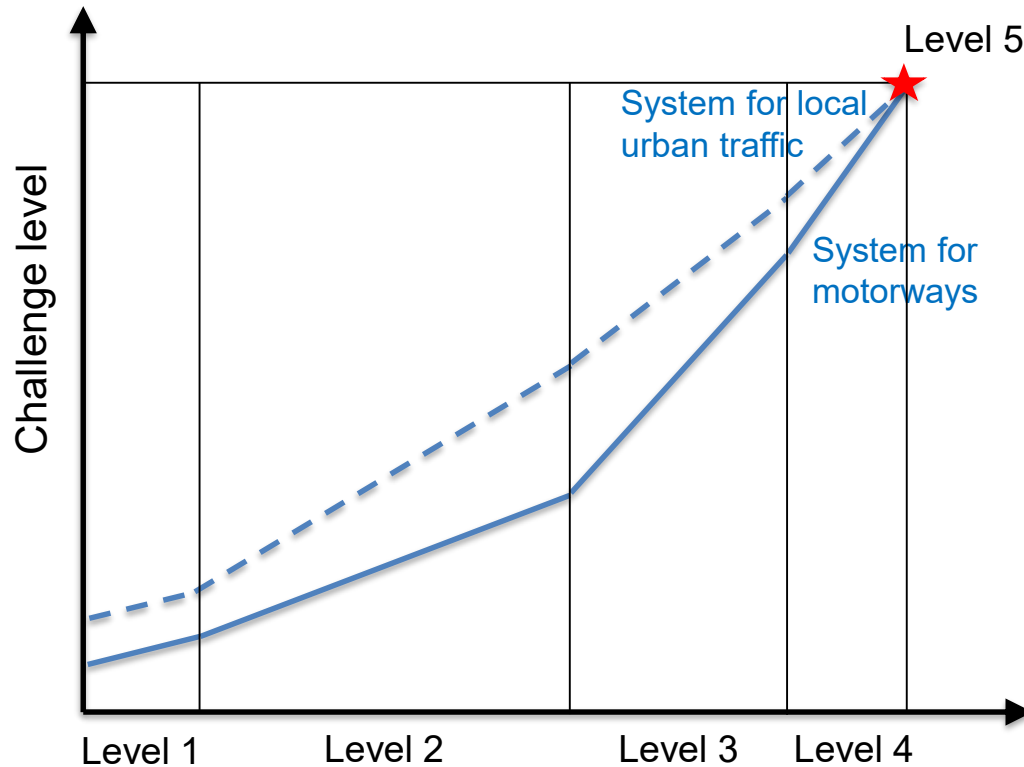


# Challenges on the SIP Phase II Roadmap



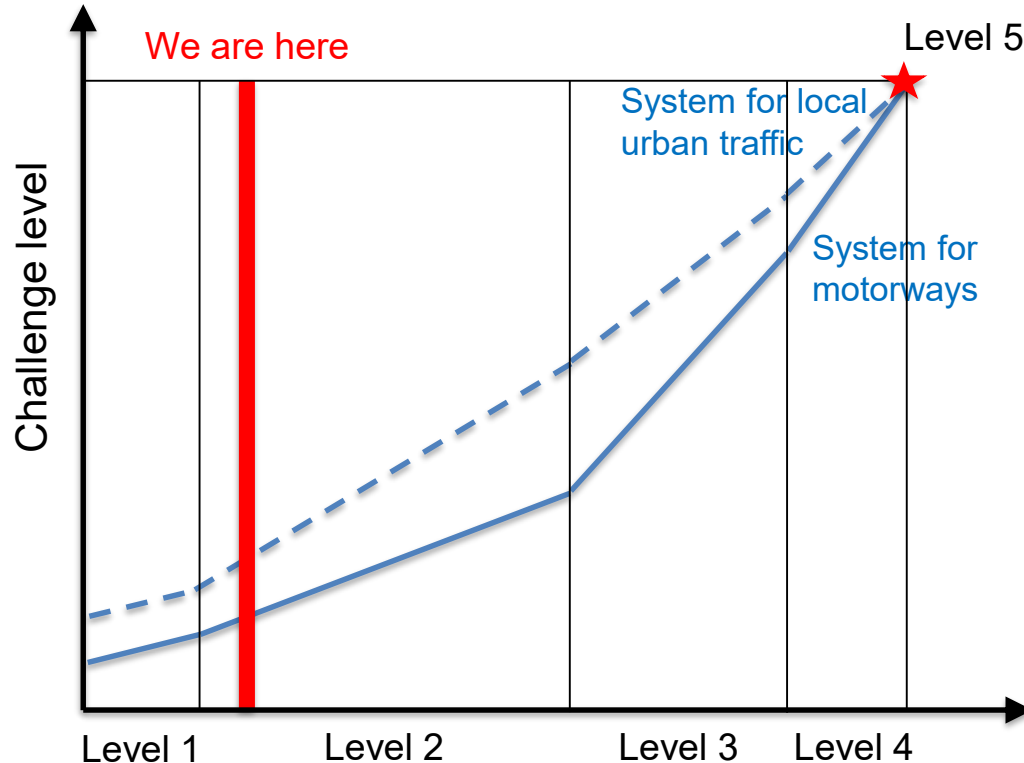
# Challenges in System and Human Factors towards Level 5

Challenges in System development will increase towards Level 5 with more challenges for expanding ODD to local urban traffic.



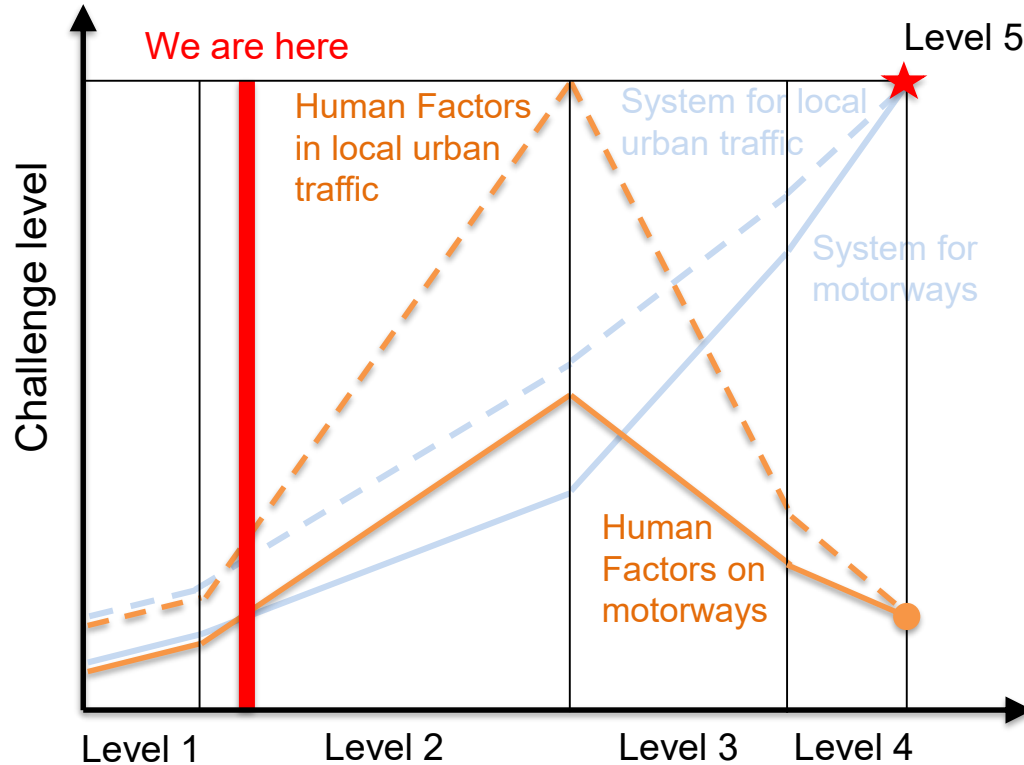
# Challenges in System and Human Factors towards Level 5

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# Challenges in System and Human Factors towards Level 5

Challenges in human factors may be the largest with higher Level 2 especially for expanding ODD to local urban traffic.

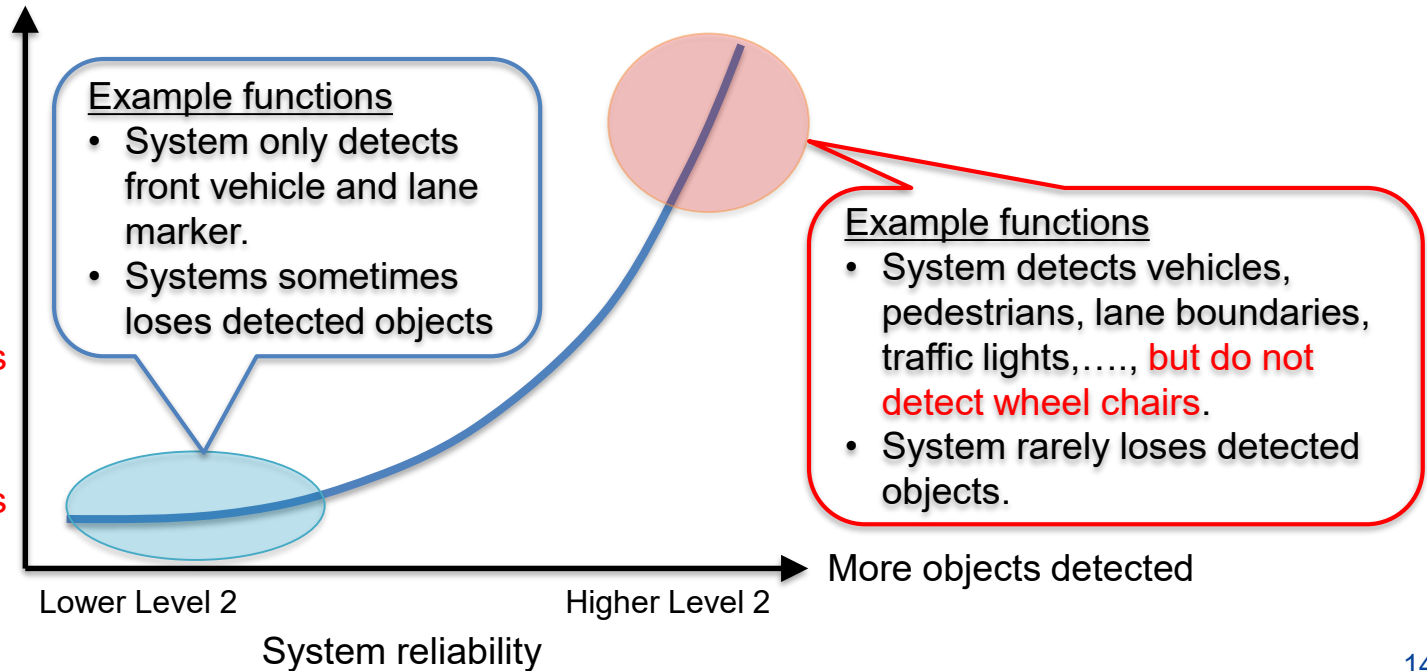


# OEDR in local urban traffic with Level 2 systems

- How can human work with the system for OEDR?
- How HMIs, education and training can help the driver to understand system limitations and compensate for them?

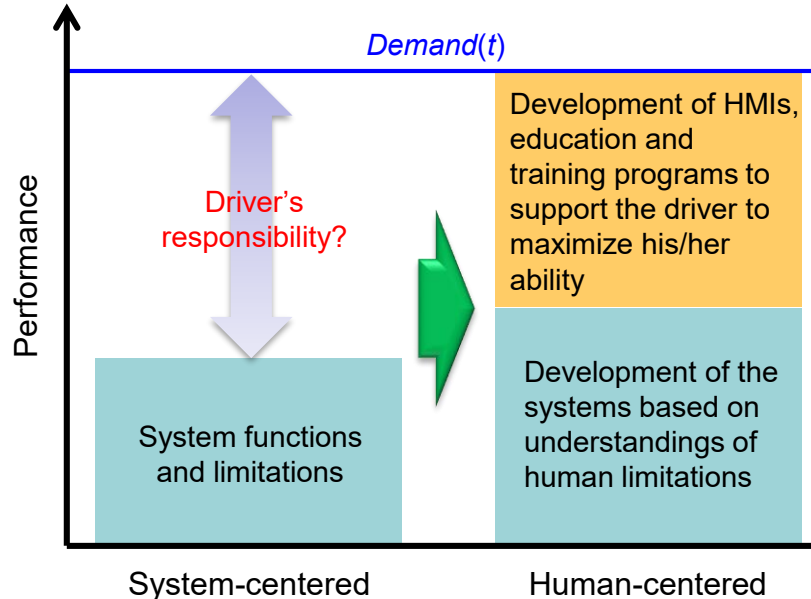
## ■ Trust

- Difficulty to generate an appropriate mental model
- Difficulty to understand system limitations
- Difficulty to respond for system limitations



# Human-centered Strategy

- To understand human limitations in use of the systems and clarify requirements to the system based on the human limitations.
- To develop HMIs to support the driver to maximize his/her abilities.
- To consider education and training of users as well.





The background of the slide is a long-exposure photograph of a tunnel at night. The lights from the tunnel walls and ceiling are blurred into long, vibrant streaks of yellow, orange, and white, creating a sense of motion and depth. The perspective is from the center of the tunnel, looking towards the vanishing point.

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2018**

**Thank you**

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