

An aerial view of a city intersection featuring several autonomous vehicles, including a white van, a white car, and a large white truck. The vehicles are surrounded by blue circular sensor fields and red sensor waves emanating from them, indicating their detection of the environment. The road has white zebra crossings. The background is a light blue and green grid pattern.

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CCAM in Austria

Strategies – Actions – Priorities

#SIP-ADUS 2019, Tokio

Martin Russ, AustriaTech

Aktionspaket Automatisierte Mobilität

2019-2022



1_National Actionplan

2nd edition

2019-2022

65 Mio.€

34 Measures

All modes

Developed with 300 Stakeholders

as a priority

ation

the legal framework

controlling the impact of
ty in the interests

the co-creation influence of

research and development and
domestic competencies

nable use of infrastructure

petencies in the area of
interaction as a key to value
text of transport safety

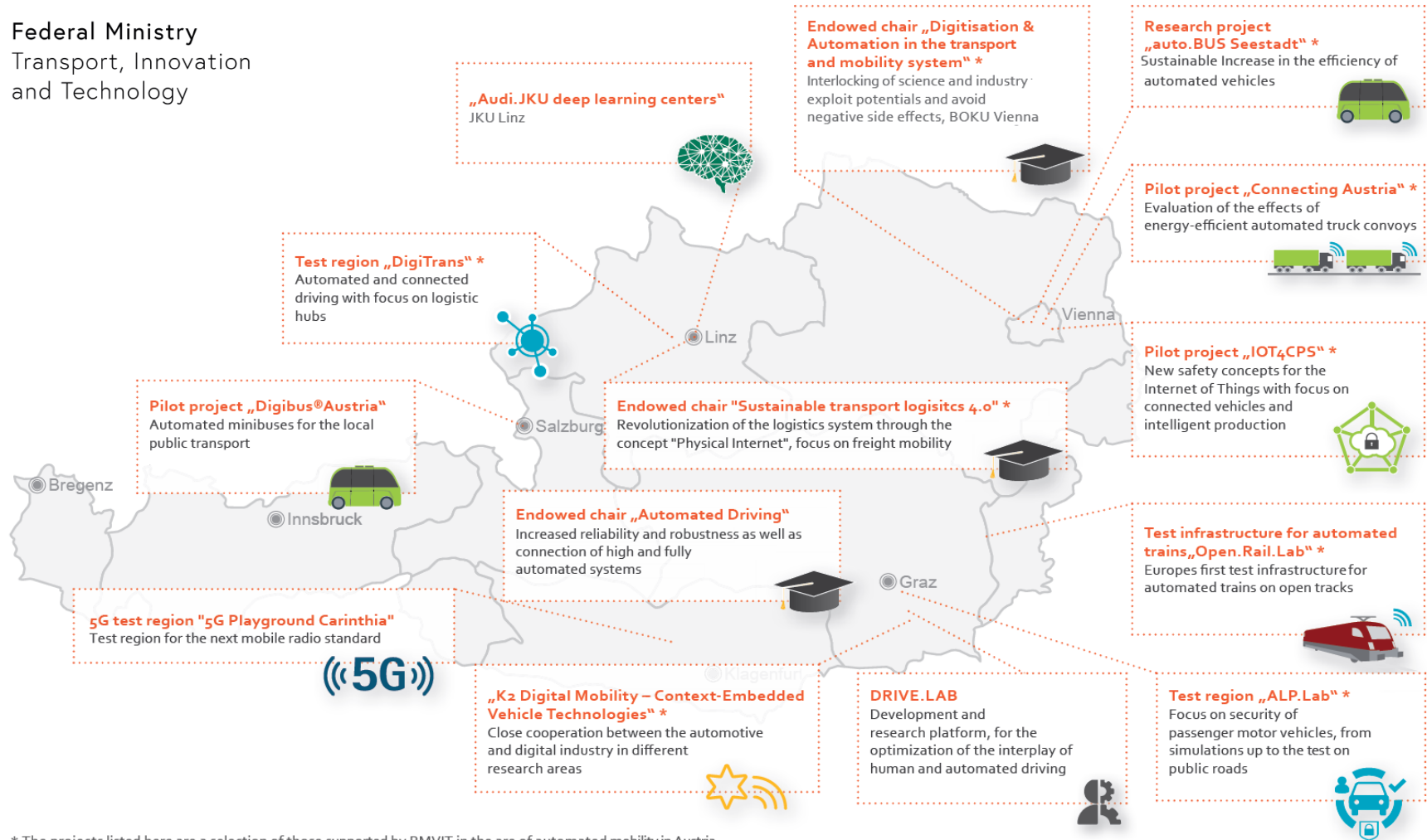
Measures

- ① Transparent information
- ② Amendment of the legal framework
- ③ Assessing and controlling the impact of automated mobility in the interests of sustainability
- ④ Strengthening the co-creation influence of the public sector
- ⑤ Promotion of research and development and strengthening of domestic competencies
- ⑥ Smart and sustainable use of infrastructure
- ⑦ Establishing competencies in the area of human-machine interaction as a key to value added in the context of transport safety

Field of action I:
Transparent information,
active participation of
the public sector and
strengthening of
societal dialogue on
automated mobility



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* The projects listed here are a selection of those supported by BMVIT in the area of automated mobility in Austria. In addition, BMVIT supports a large number of interdisciplinary projects in the fields of information and communications technology, mobility and security research.

Key initiatives in Austria - Overview



3 Test Environments

- Alp.Lab
- DigiTrans
- AIRLab Austria



4 R&D & Pilot Projects

- Shuttles:
- Digibus® Austria
 - Auto.Bus – Seestadt
 - SURAAA – Carinthia
- Platooning
- Connecting Austria



3 Centers of Competence

- K2 Digital Mobility – Context-Embedded Vehicle Technologies
- Audi.JKU deep learning center
- DRIVE.LAB



3 Endowed Chairs

- Automated Driving Technologies
 - Digitisation & Automation in the transport and mobility system
 - Sustainable transport logistics 4.0
-

2_A Matter of Trust

Engage with Citizens

Explain what to expect

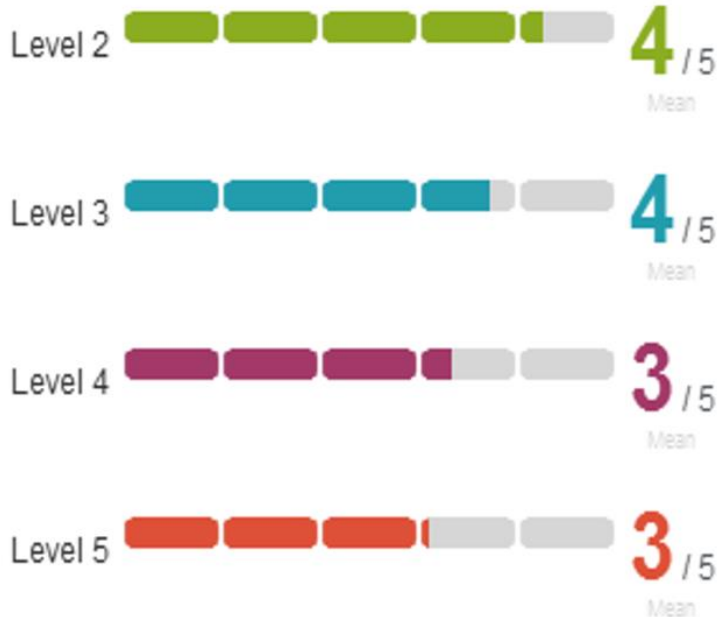
Give guidance on policy targets

Build collaboration



Get in touch with with Citizens/Users

Acceptance/Trust Level



Seien auch Sie dabei – Jede Meinung zählt!



GRAZ
PÖRTSCHACH
LINZ
SALZBURG
WIEN
6. April 2019

>> www.austriatech.at/Citizensdebate

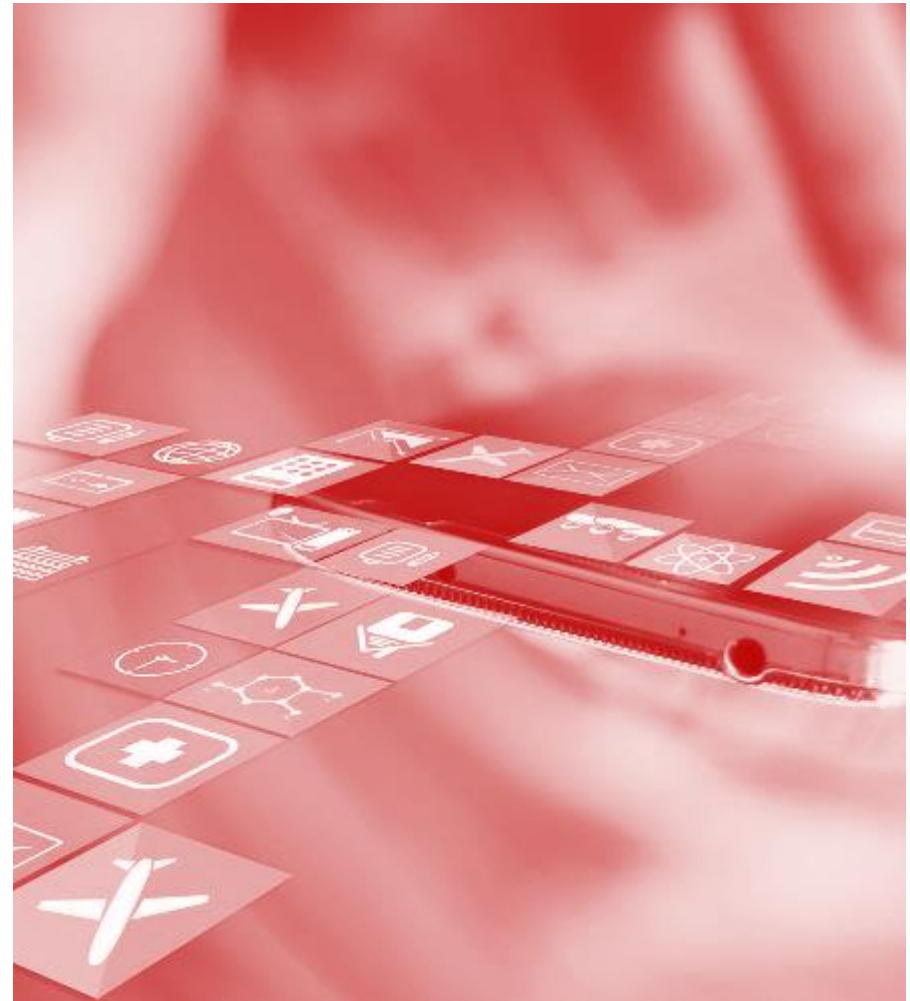
3_Building Blocks for integrated & automated Mobility

Integration needs Differentiation

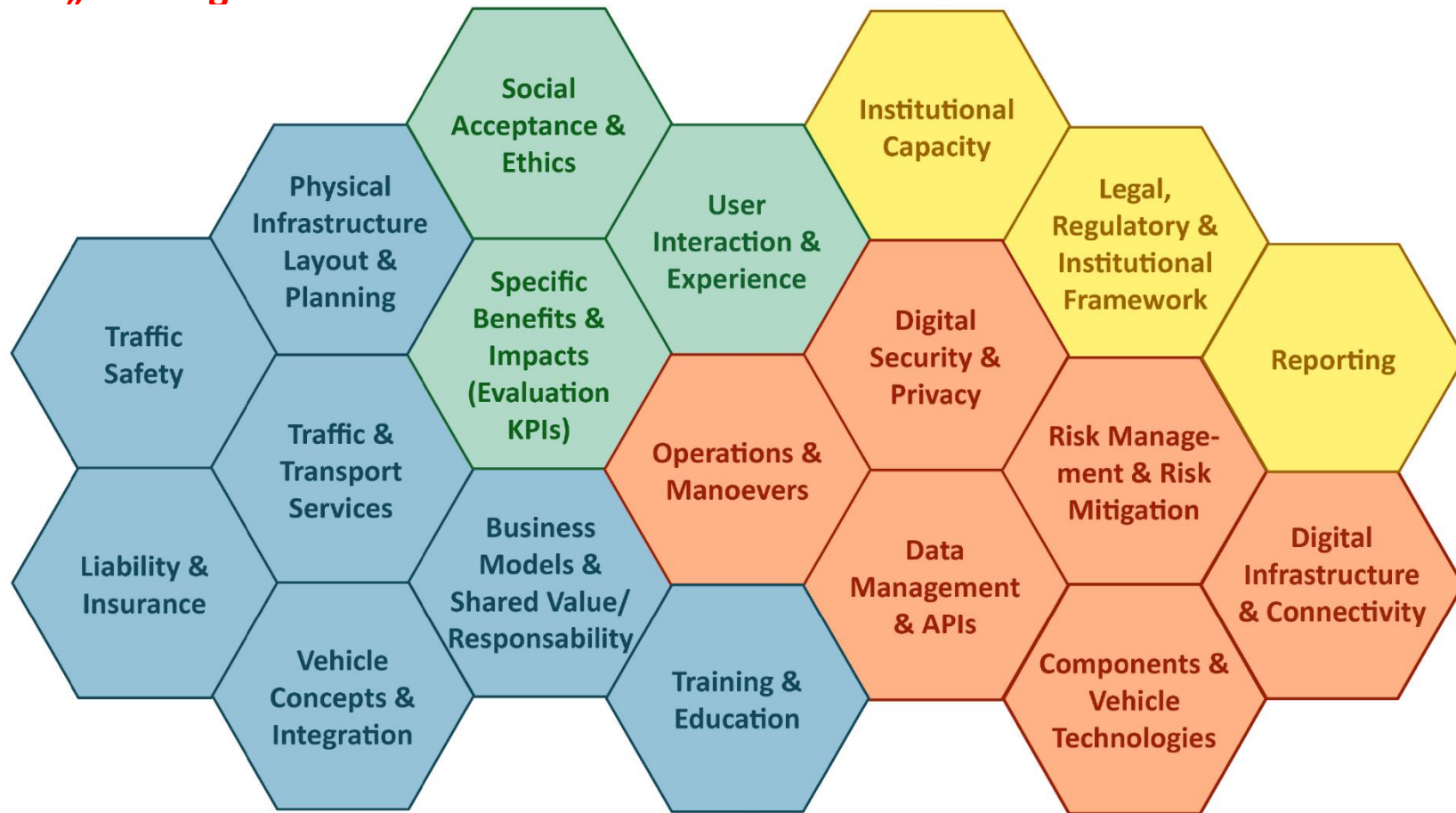
Understanding needs Perplexity

Testing needs Comparability

Scenarions need Application



Scenario „Building Blocks“



CORE ASPECTS...FROM EU MEMBER STATES

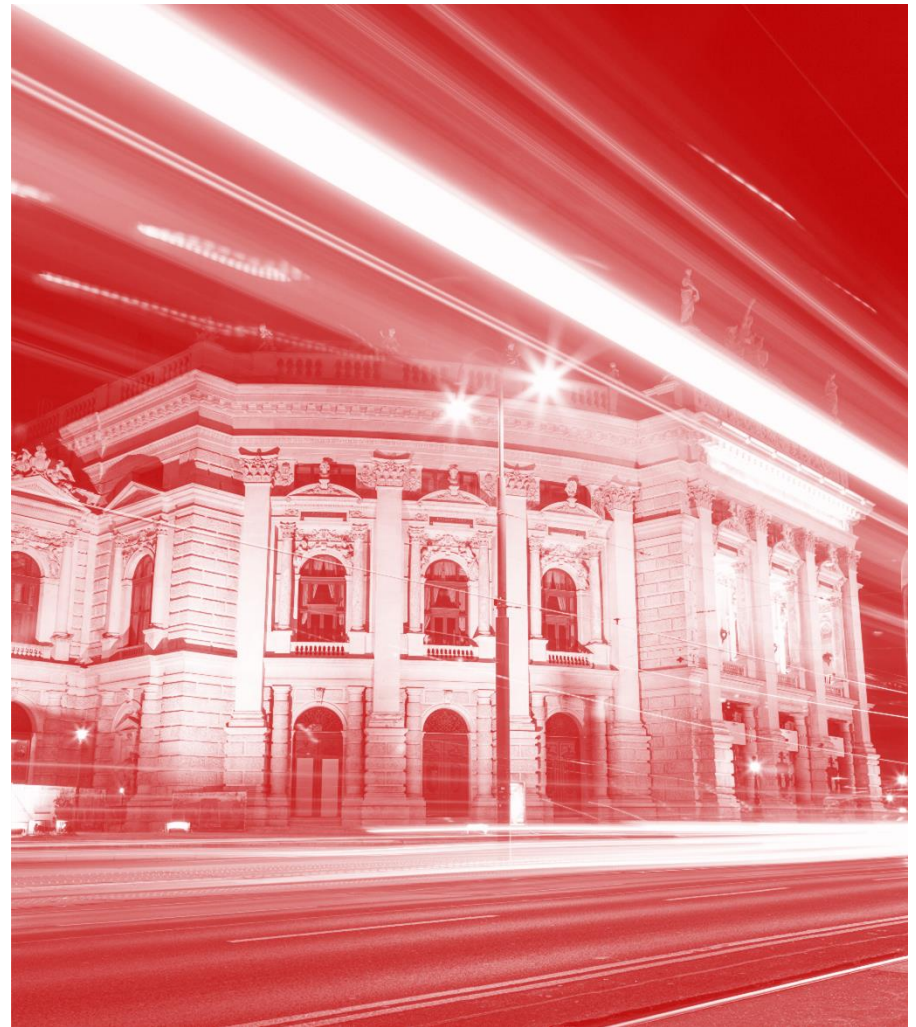
- Common pathway for **policy makers**
- Be specific on **goals** and how to **measure impacts**
- Effective frameworks for **sustainable business**
- A common **knowledge base** on building blocks
- Effective frameworks for **experiments**
- Aim for **consistency** and **interoperability**

Top Building Blocks:



4_Engaging with Cities

**Collaboration Framework of
States & Cities (& Stakeholders)
Austria, Germany & Switzerland**



Collaboration Frame: Connected and automated Mobility in Cities

Strategic
Alignment

Common
measures
&
common
ressources

Learning
and
knowledge
exchange

Common
positions &
Anwareness



New Partners



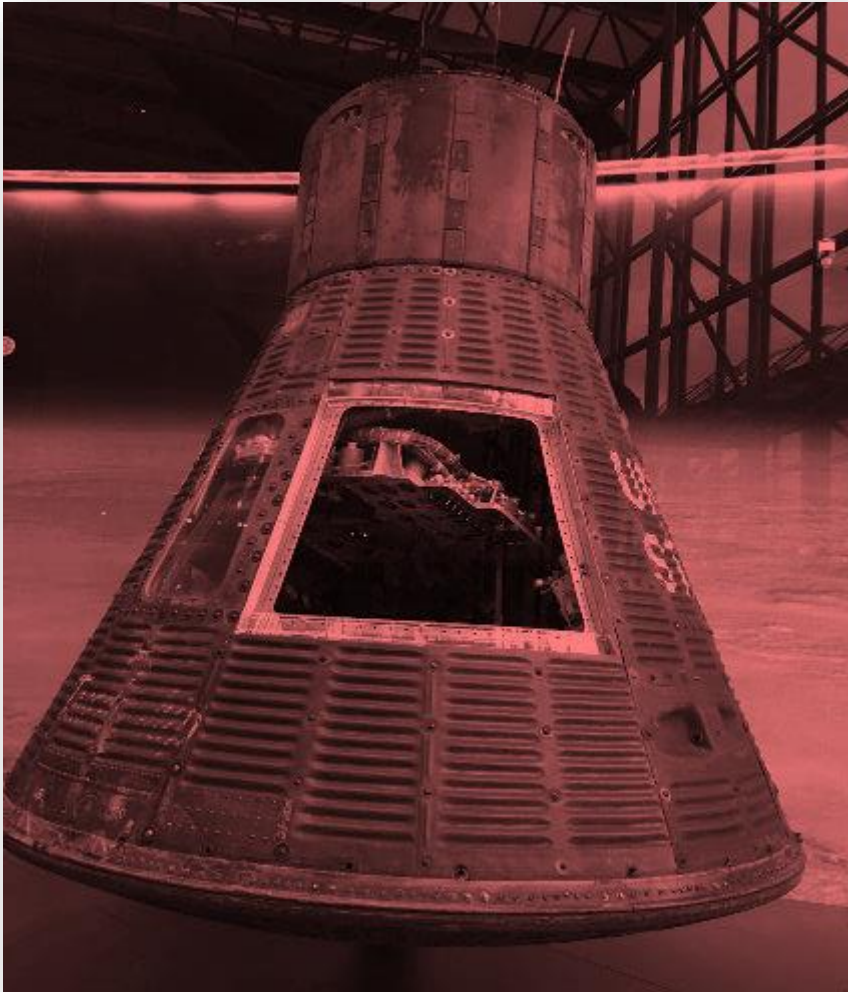
New Spaces



New Data



New Governance



5_legal moonshots

legal framework for create **efficient and effective testing** environments

Operations = next...

Safety, data protection & human obligations as actual challenges

“**sandboxes**” for future tests and **performance based regulation**

Sensors/
Actuators Behavioural
Competences Manouvers/
Edge Cases

Vehicle/
Component

Driver/
Operator
Interaction

**Safe
Testing**

Infrastructure/
Traffic MM

Digital
Road Code

(Test-)driver
skills
Failure
h

Criteria Catalogue & Maturity Levels

Context/
Environment

Weather LoS Mix

6_ Examples

Experiments & Learning



The flagship project Digibus® Austria

Digital infrastructure & connectivity

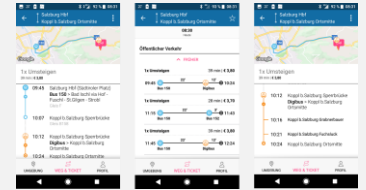


Digibus® Austria



Source: Salzburg Research / wildbild

Automated mobility system & passenger interaction



Driving scenarios & interaction with other road users



Reference model for planning, deployment & operation of automated shuttles

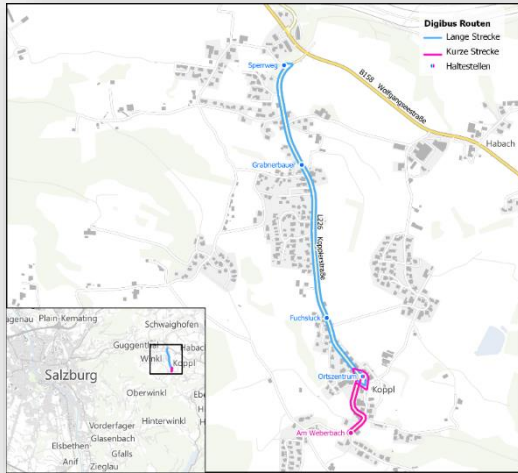
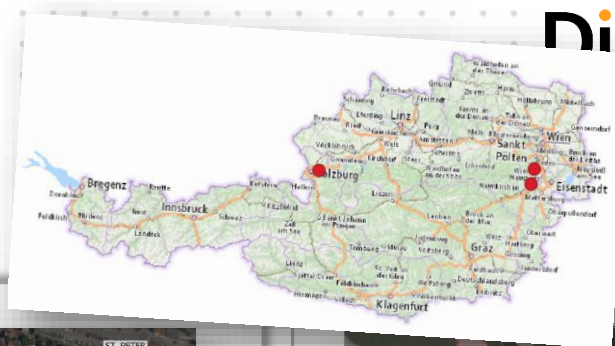


3 years runtime (2018-2021)

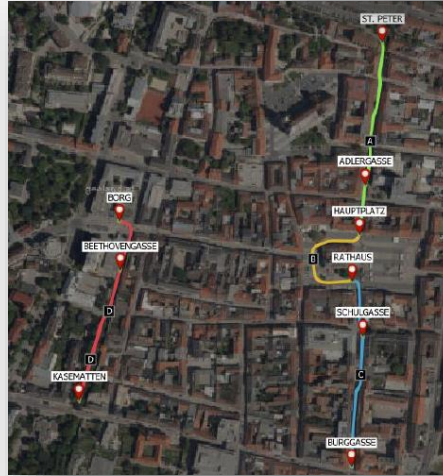
13 partners

4.2 million EUR budget

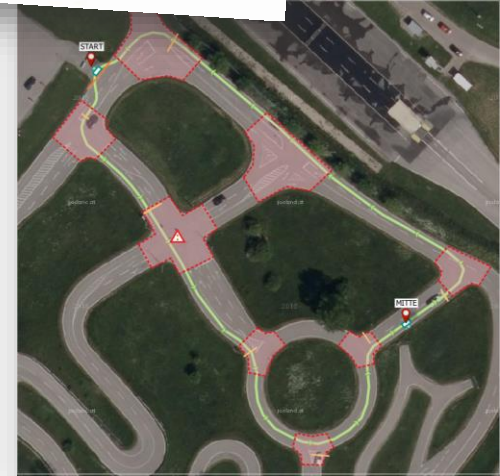
Sites for pilot tests



Koppl / Salzburg



Wiener Neustadt



Teesdorf

Impressions of the pilot tests



Koppl / Salzburg

Wiener Neustadt

Teesdorf

Video: <https://www.youtube.com/watch?v=wt4djna5Ans>

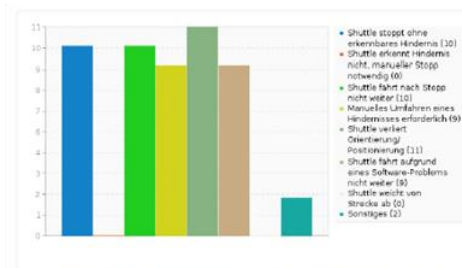
Systematic learning from pilot tests

Risk analysis / risk assessment



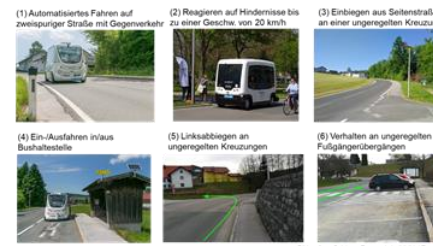
➔ Harmonization

Test protocols / test data



➔ Harmonization

Scientific experiments



➔ Publishing of results

Bericht zu den Testfahrten 2017 unter:
<https://www.digibus.at>

And the future? Vision of driverless operation

1

The shuttle is able to reliably manage all driving maneuvers automatically up to a speed of **20 km/h, without human intervention**, on all days and in all weather situations

2

The shuttle observe its automated driving capabilities, can be controlled remotely from a **control center** und can be anytime brought to a safe state

3

Shuttle is **fully integrated** into an automated **mobility system** including transfer management, ticketing, seat management, aso.

4

Passengers perceive a similar **level of trust** in a driverless vehicles compared to vehicles with drivers and are able to contact a control center person at any time

5

Shuttles communicates with passengers and other road users and informs effectively on driving state as well as driving maneuvers

6

For driverless operation the **regulatory frame is adapted**, at least as exceptional regulation for pilot testing

First driverless test on September, 18th 2019

- Shuttles was operated driverless on a pre-defined test track on a private site
 - First external test of a EasyMile EZ10 shuttle
- All drives were remotely monitored/controlled (vehicle control + voice communication)
- 18 test persons
- 4 experiments
 - Passenger rides alone
 - 2-persons-ride with annoyance
 - Capacity test
 - Disruption of the ride due to a technical problem
- Video: <https://www.youtube.com/watch?v=2quigToQhII>





auto.Bus Seestadt

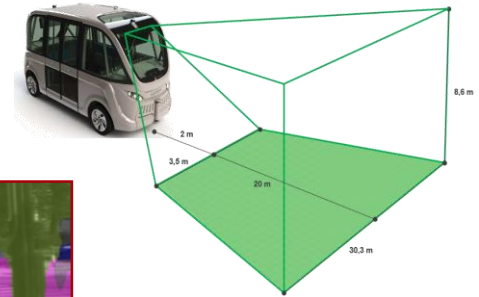


 Bundesministerium
Verkehr, Innovation
und Technologie



Advanced perception capabilities and system safety

- Semantic labeling - object classification
- Scene understanding through machine learning



	Road	Sidewalk	Building	Wall	Fence	Pole	Traffic Light	Traffic Sign	Vegetation
Terrain	Sky	Person	Rider	Car	Truck	Bus	Train	Motorcycle	Bicycle



Combination of vehicle and infrastructure information

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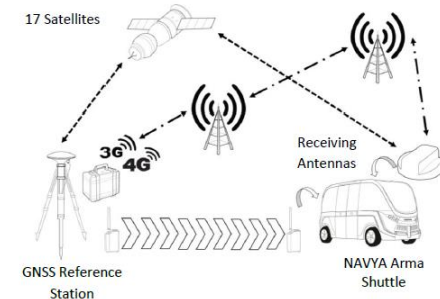
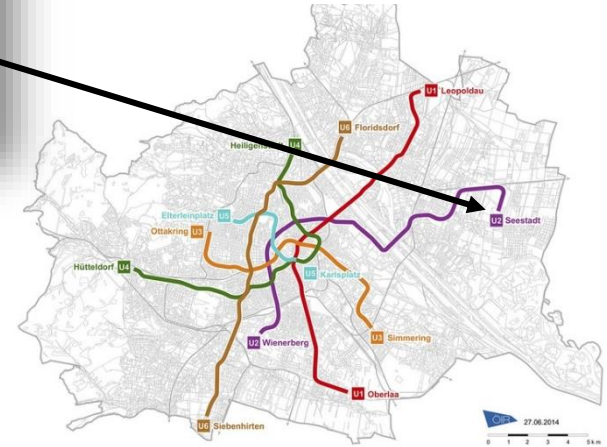
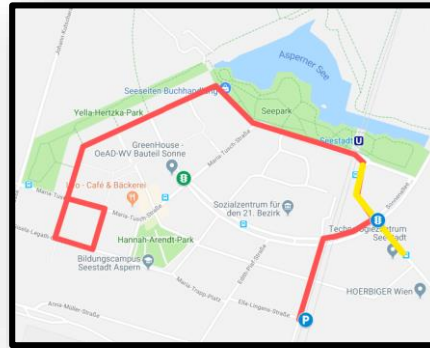


- The combination of vehicle and infrastructure information will lead to improved traffic safety and a better ease of traffic
- The sensors work reliably, even in the case of changing weather and light conditions, e.g. rain, snow, fog or glaring sunlight
- The sensor infrastructure helps to identify potential risks, even if they are not in the immediate surrounding of the vehicle
- WLAN-based radio module transmits real-time information to passing vehicles and receives data from cars, environmental detectors, traffic controllers and traffic control centers



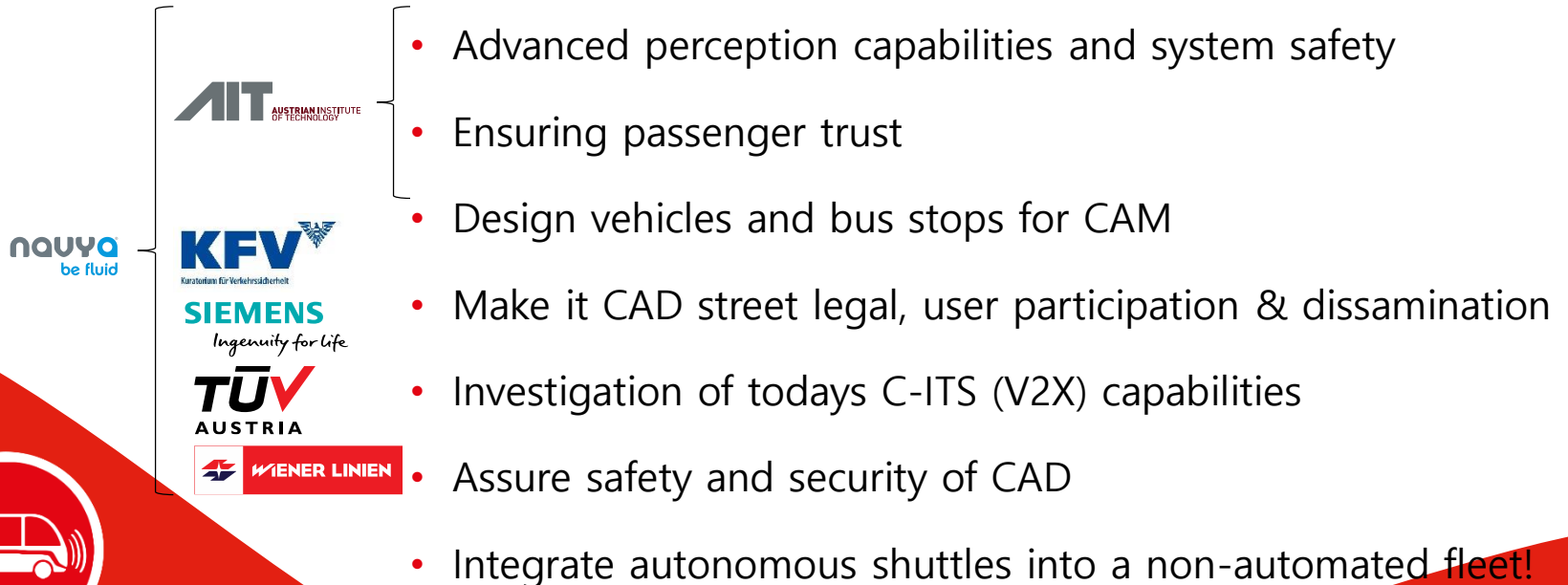
Test Track Vienna

- City of Vienna
 - 1.7 M inhabitants, ~40% PT
- Physical infrastructure of test track
 - 2,2 km (per direction)
 - Maximum allowed speed of 30 km/h
 - Adaptations: bus stop bays, GNSS reference station (via 3/4G and radio)
- Digital infrastructure
 - Digital map (pre-recorded and manually edited)
 - Mobile data connection (3/4G)



Take home messages

The project goals of auto.bus - Seestadt are:

- 
- Advanced perception capabilities and system safety
 - Ensuring passenger trust
 - Design vehicles and bus stops for CAM
 - Make it CAD street legal, user participation & dissemination
 - Investigation of today's C-ITS (V2X) capabilities
 - Assure safety and security of CAD
 - Integrate autonomous shuttles into a non-automated fleet!



Thank you for your attention!

