

Research of V2X communication for Cooperative Driving Automation

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1. Research status of V2X communication for cooperative driving automation

- TF on V2X communication for Cooperative Driving Automation (CDA)
 has been established in 2019
- Started research for communication methods for CDA

[Purpose]

Draw the ideal form of cooperative driving automation and the roadmap to realization, while considering international standards, establish the optimal communication method policy by ALL JAPAN

[goal]

- Propose the optimal communication method for CDA
- Draw the roadmap for communication method (requirement)



1. Research status of V2X communication for cooperative driving automation

- Activities of TF on V2X Communication for CDA
- Define CDA
- Develop CDA use cases based on the definition

Phase1

Done

Define communication requirements based on use cases

Phase2

Done

- Examination of applicability of existing ITS communication
- Technology verification for Communication methods (frequency / bandwidth) for CDA
- Proposal of communication method and the roadmap

Phase3

On going

1. Research status of V2X communication for cooperative driving automation

Phase1

♦ SIP Cooperative Autonomous Driving Use Case 1st Edition released

Contents

- CDA system definition
- Scope of study
- Use case review process
- SIP CDA use cases

SIP Use Cases for Cooperative Driving Automation

— Activity Report of Task Force on V2X Communication for
Cooperative Driving Automation in FY2019 —

First edition issued on September 3, 2020

Task Force on V2X Communication for Cooperative Driving Automation.

System Implementation For Cooperative Univing Automation

System Implementation Working Group,

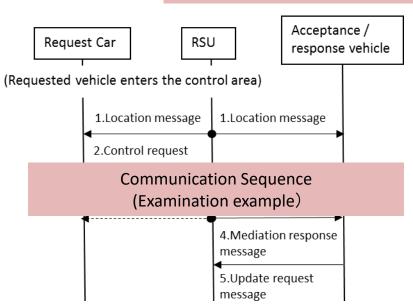
Cross-Ministerial Strategic Innovation Promotion Program (SIP)



2. Communication requirements

- Examined with reference to similar cases implemented in the past or currently under consideration
- Experimental guidelines for communication systems for CDA (ITS FORUM RC-015 1.0 version)
- ✓ Demonstration experiments by ITS-related organizations, etc.

Functional classification	a. Merging / lane change support
Use case	Main line gap aiming merge support
No.	a-1-2
Message name	Location information provided
Communication form	V2I $(I \rightarrow V)$
(exa	nication requirements mination example)
per area	1 Torrido
Required communication distance	66.7~116.7m
Maximum relative speed	Connection route : 20~70km/h
Maximum data size	1942 byte (1692+250) Estimated number : 62 vehicles



Phase 2

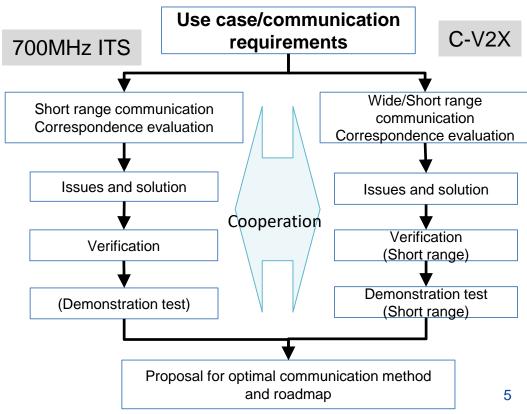
Use case (image)



3. Examination of application to communication technologies

 Consider issues and solutions when applying use cases and communication requirements to ITS radio communication

- Applicability of existing ITS radio communication (700MHz band)
- Application study and experiments of cellular V2X
- Proposal for optimal radio communication method and roadmap



Phase3



